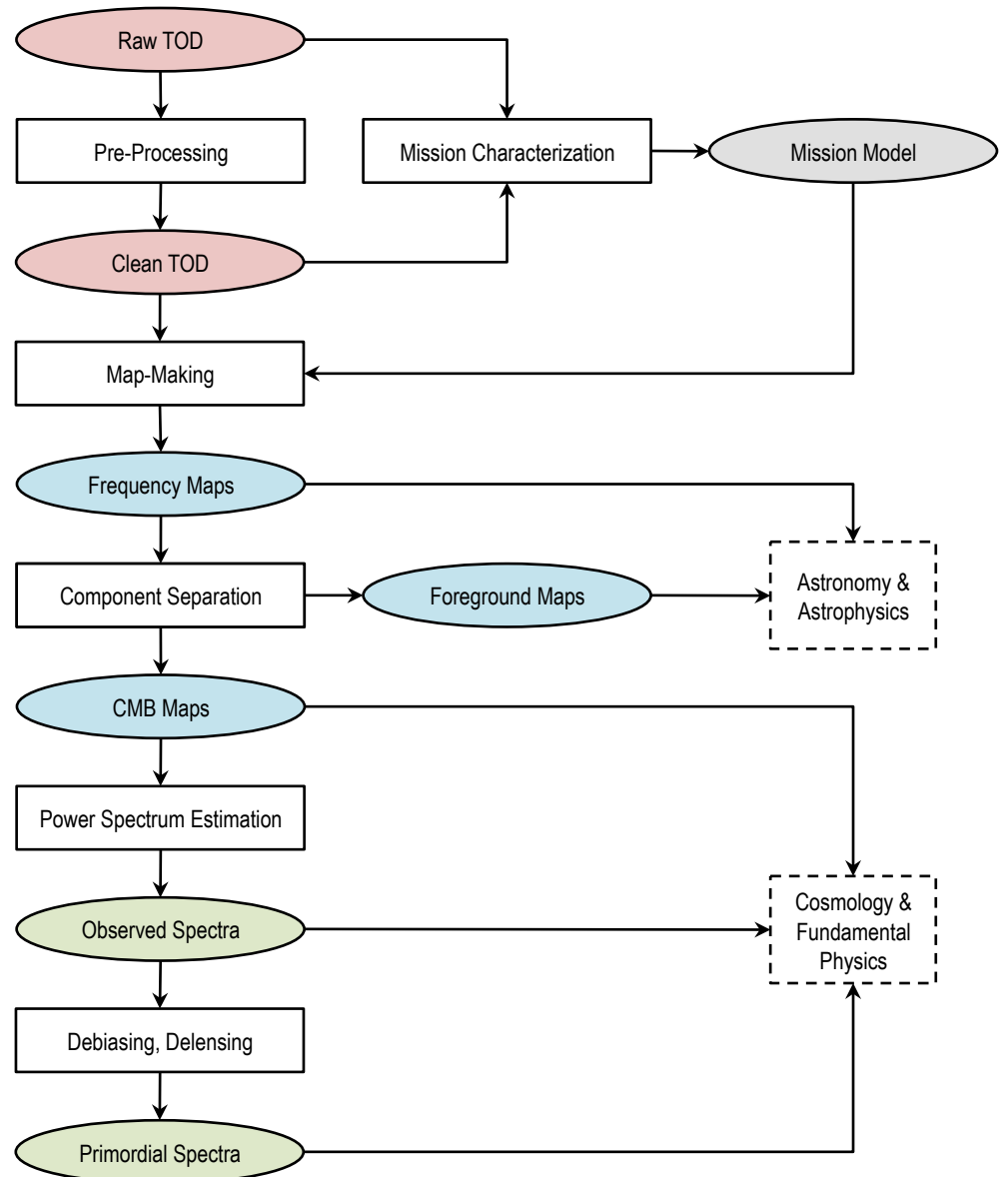


Simulations, Data Analysis & High Performance Computing After Planck

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Data Analysis

- DA challenge comes from both systematic and statistical uncertainties.
- DA pipeline is an alternating sequence of
 - a) domain-specific systematic mitigation
 - b) S/N-increasing data compression
- Must propagate both data *and their covariance* for a sufficient statistic.



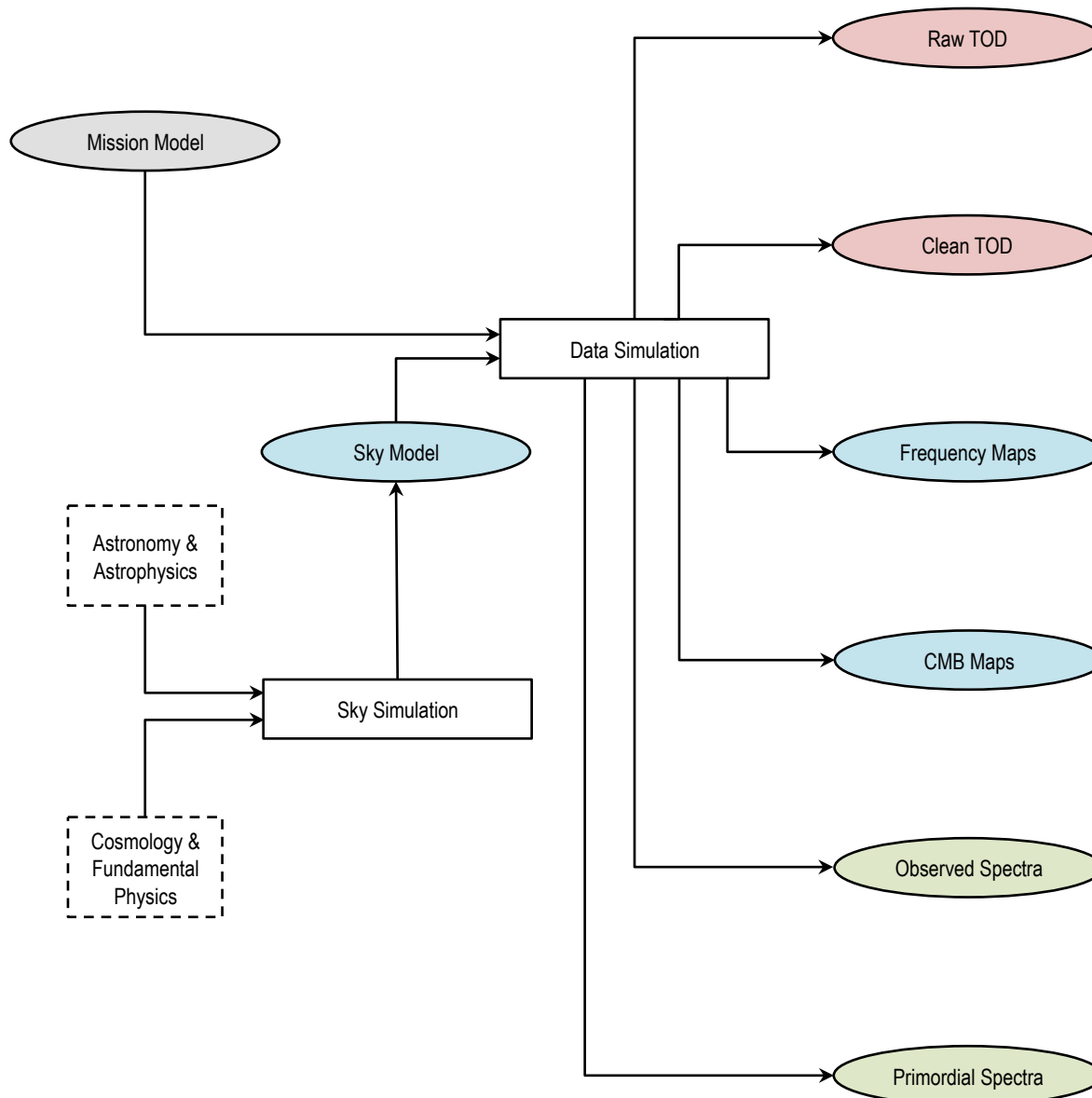
Analysis Methods

- CMB data volumes:
 - Time domain: $\mathcal{N}_t \sim \sum_{\text{det}} \text{Sampling Rate (Hz)} \times \text{Observation Time (s)}$
 - Pixel domain: $\mathcal{N}_p \sim \sum_{\text{freq, pol}} 10^9 \times \text{Sky Fraction} / [\text{Beam (arcmin)}]^2$
- CMB data analysis scaling dominated by:
 - \mathcal{N}_p^3 for exact methods with explicit covariance matrices.
 - $\mathcal{N}_{\text{mc}} \mathcal{N}_t$ for approximate methods with MC uncertainty quantification.
- Computational constraints (1% cycles/year on Top 10 system):
 - 2000 : $\mathcal{N}_p < 10^6$ & $\mathcal{N}_t < 10^{12}$
 - 2015 : $\mathcal{N}_p < 10^7$ & $\mathcal{N}_t < 10^{15}$
 - 2030 : $\mathcal{N}_p < 10^8$ & $\mathcal{N}_t < 10^{18}$
- Except in special cases, exact methods now computationally intractable.

Assumes:

- Moore's Law
- 100% & 1% efficiency

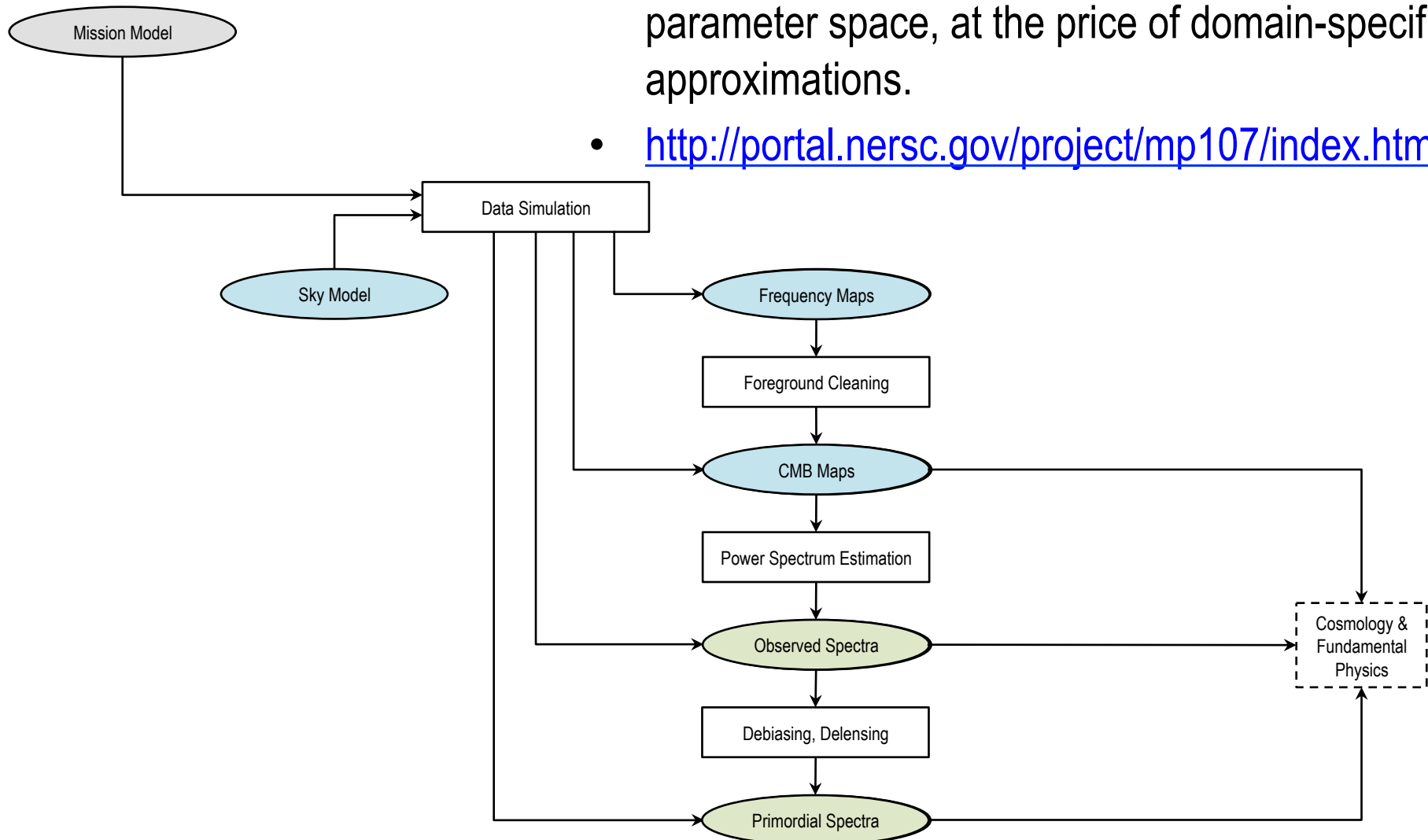
Simulations



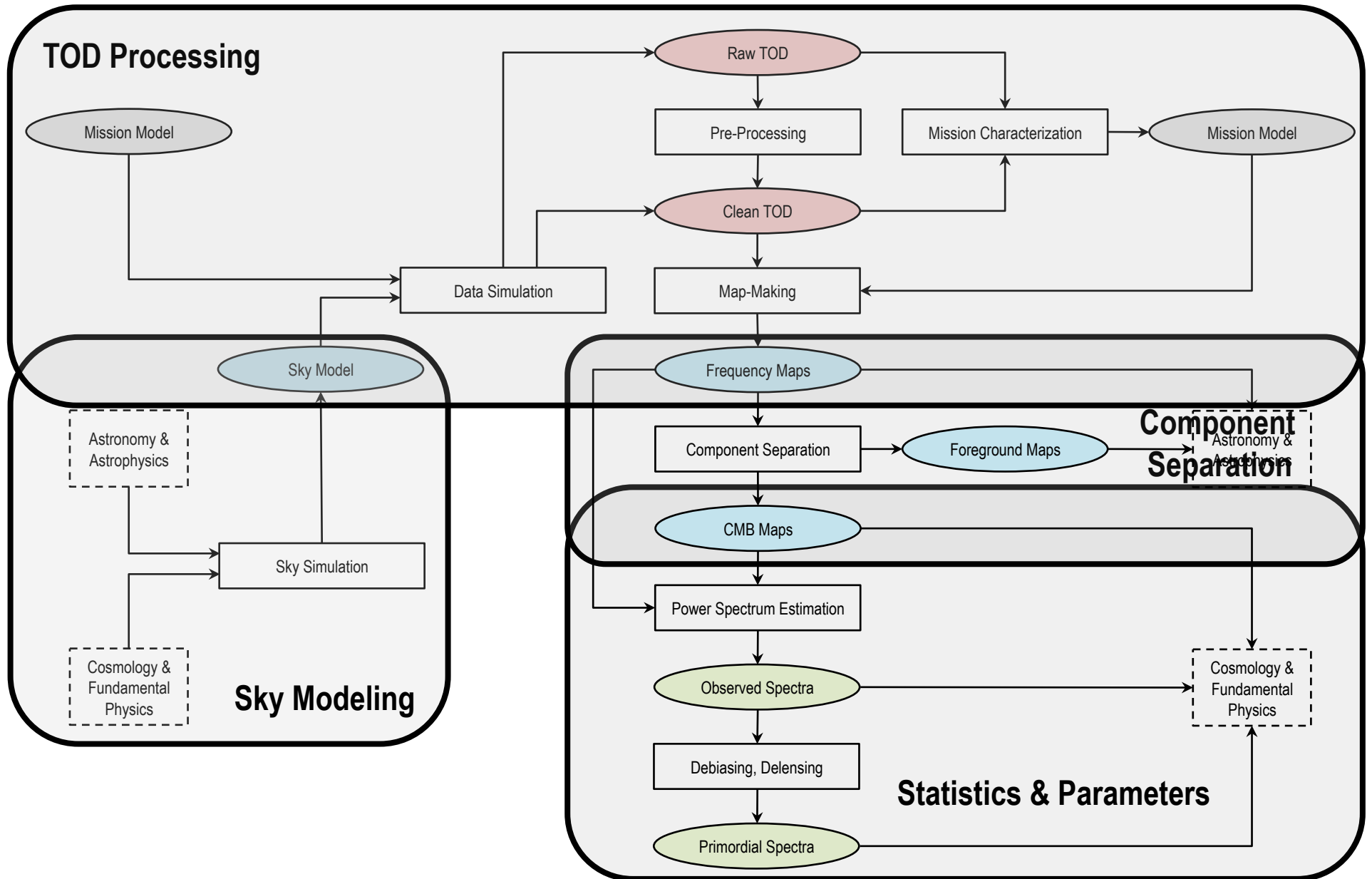
- Needed for:
 - Forecasting
 - Mission design & development
 - DA validation & verification
 - Data uncertainty quantification & debiasing (MC)
- From top to bottom, trade-off between:
 - computational cost
 - realism/reliability

Forecasting SimDA

- Speed allows for exploration of full mission parameter space, at the price of domain-specific approximations.
- <http://portal.nersc.gov/project/mp107/index.html>

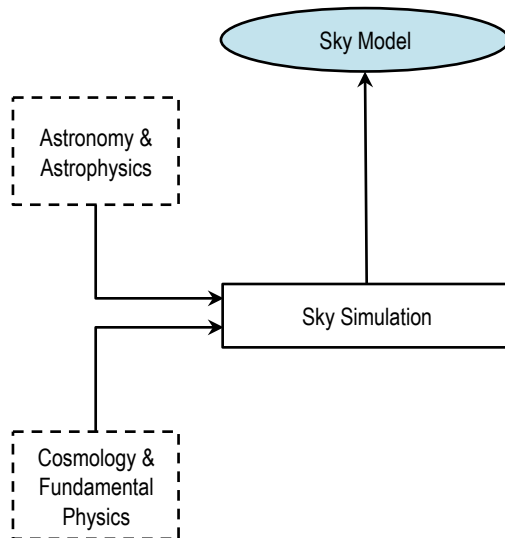


SimDA: Sub-Domains



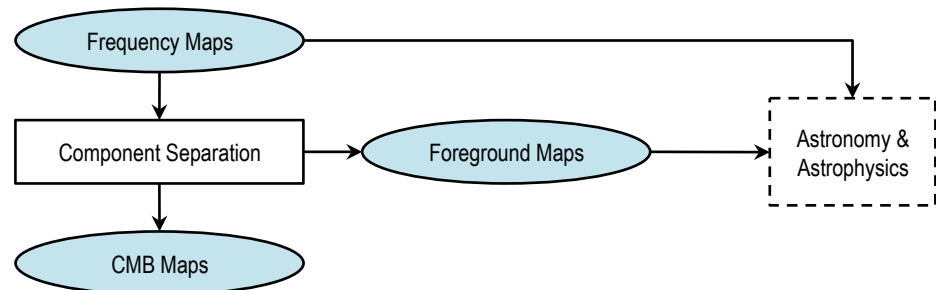
Sky Modeling

- Key Challenges:
 - Reliability: noisy, confused, band-passed, beam-convolved templates (inc. Planck) and/or speculative modeling.
 - Self-consistency: eg. CMB secondaries & extra-Galactic foregrounds
 - Usability: software engineering



Component Separation

- Key Challenges:
 - Validation: are these the right algorithms for the (as yet unknown) real foregrounds?
 - Verification: are these algorithms right given (as yet flawed) simulated foregrounds?
 - Polarization!

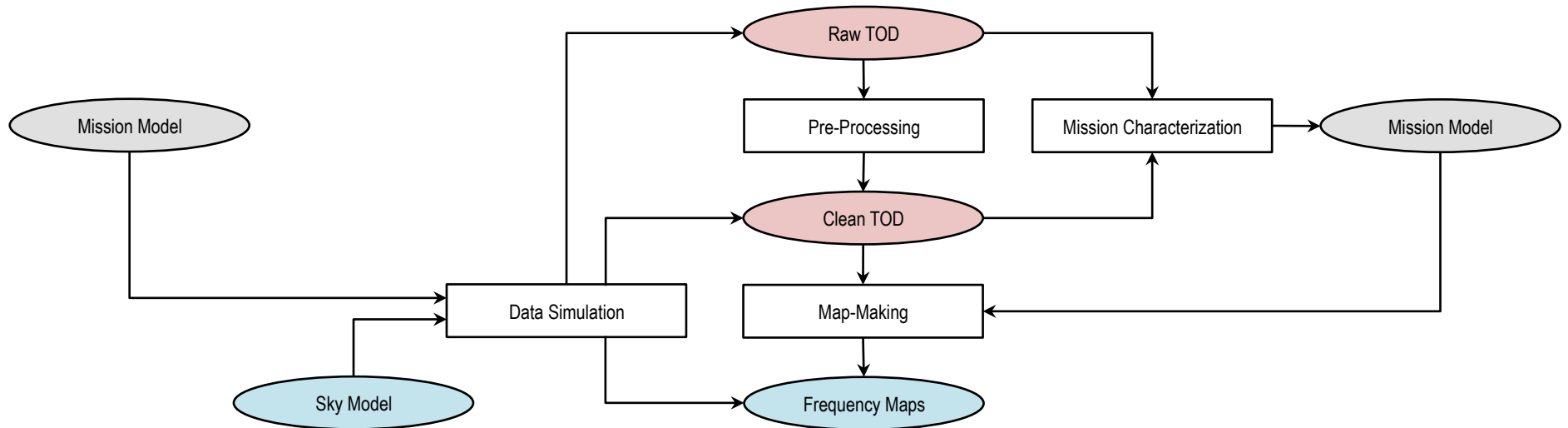


Statistics & Parameters

- Key Challenges:
 - Reliability: sufficiency of data covariance approximations.
 - Tractability: disk space for many millions of MC maps.

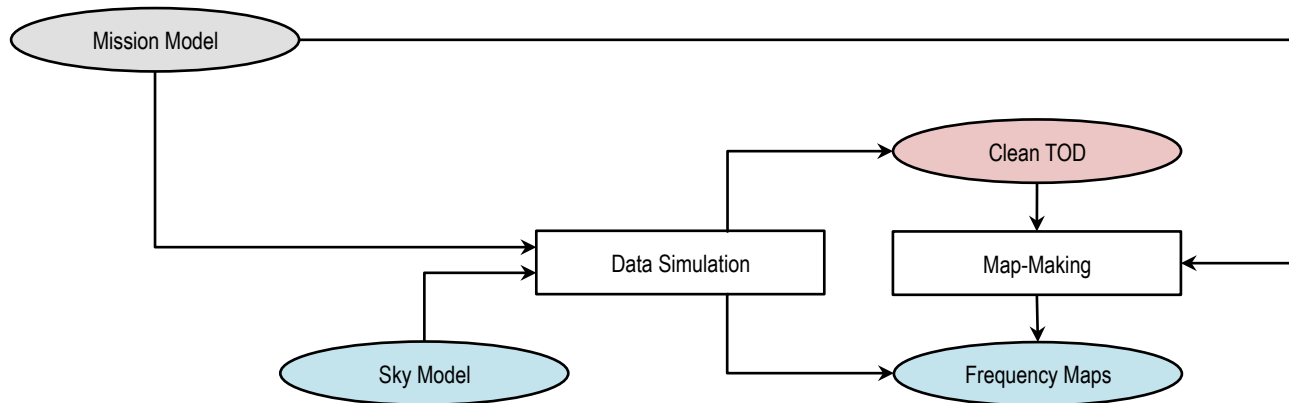


TOD Challenges



- Two bounding challenges:
 - *Tractability* for massive Monte Carlo sets.
 - *Usability* for exploratory pre-processing & mission characterization.

Massive Monte Carlos

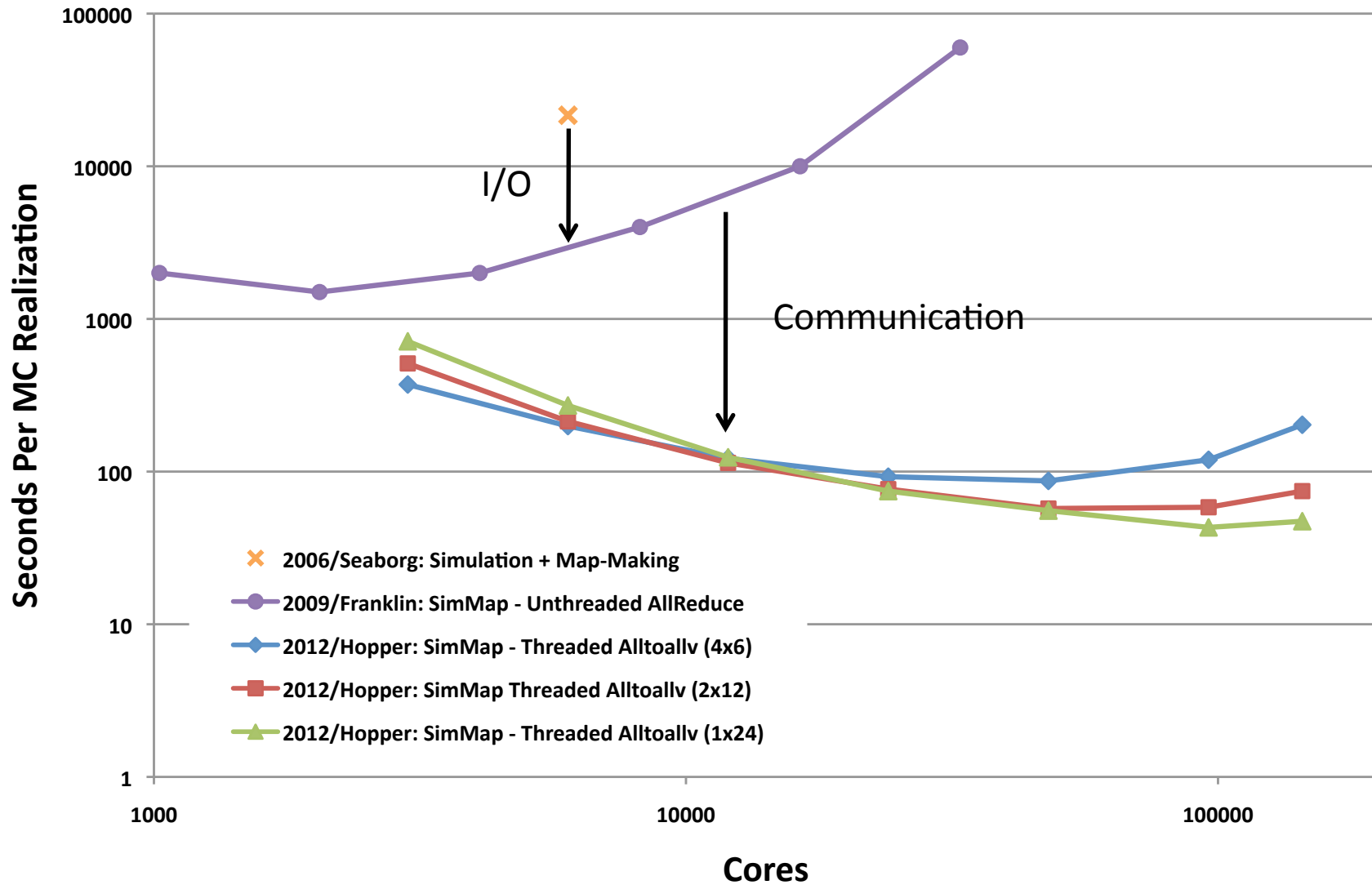


- Operation count scales with
 - Number of MC realizations: $\mathcal{N}_{mc} \sim 10^4$
 - Number of map-makings per realization: $\mathcal{N}_{mm} \sim 10$
 - Number of PCG iterations per map-making: $\mathcal{N}_{it} \sim 10$
 - Number of operations per PCG iteration: $\mathcal{N}_{ops} \sim 10 \times \mathcal{N}_t$
- Required FLOP $\sim 10^7 \mathcal{N}_t \sim 10^{19}$ for Planck

High Performance Computing

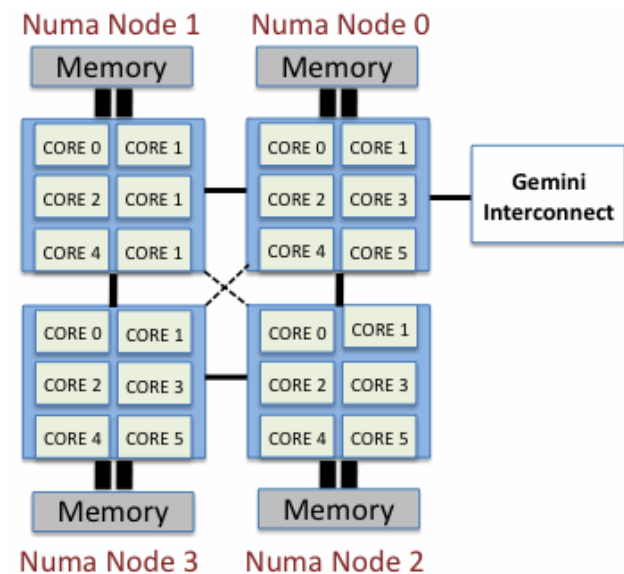
- 10^{19} FLOP $\sim 10^5$ CPU-years at 1% efficiency on 1GHz CPU
⇒ Massive parallelism + Moore's Law growth
- Whole-data reduction
⇒ Tightly-coupled cores (not grid/cloud/at-home/etc)
- Planck solution:
 - NERSC: Open-access HPC facility with long-term system upgrade plan.
 - New Top 10 system every 2-3 years
 - 6,000 users from 50 countries
 - NASA/DOE MOU guaranteed minimum annual NERSC allocation for mission lifetime:
 - In practice 1% NERSC cycles/year $\sim 10^5$ x Peak FLOP/s

Implementation/Architecture Evolution

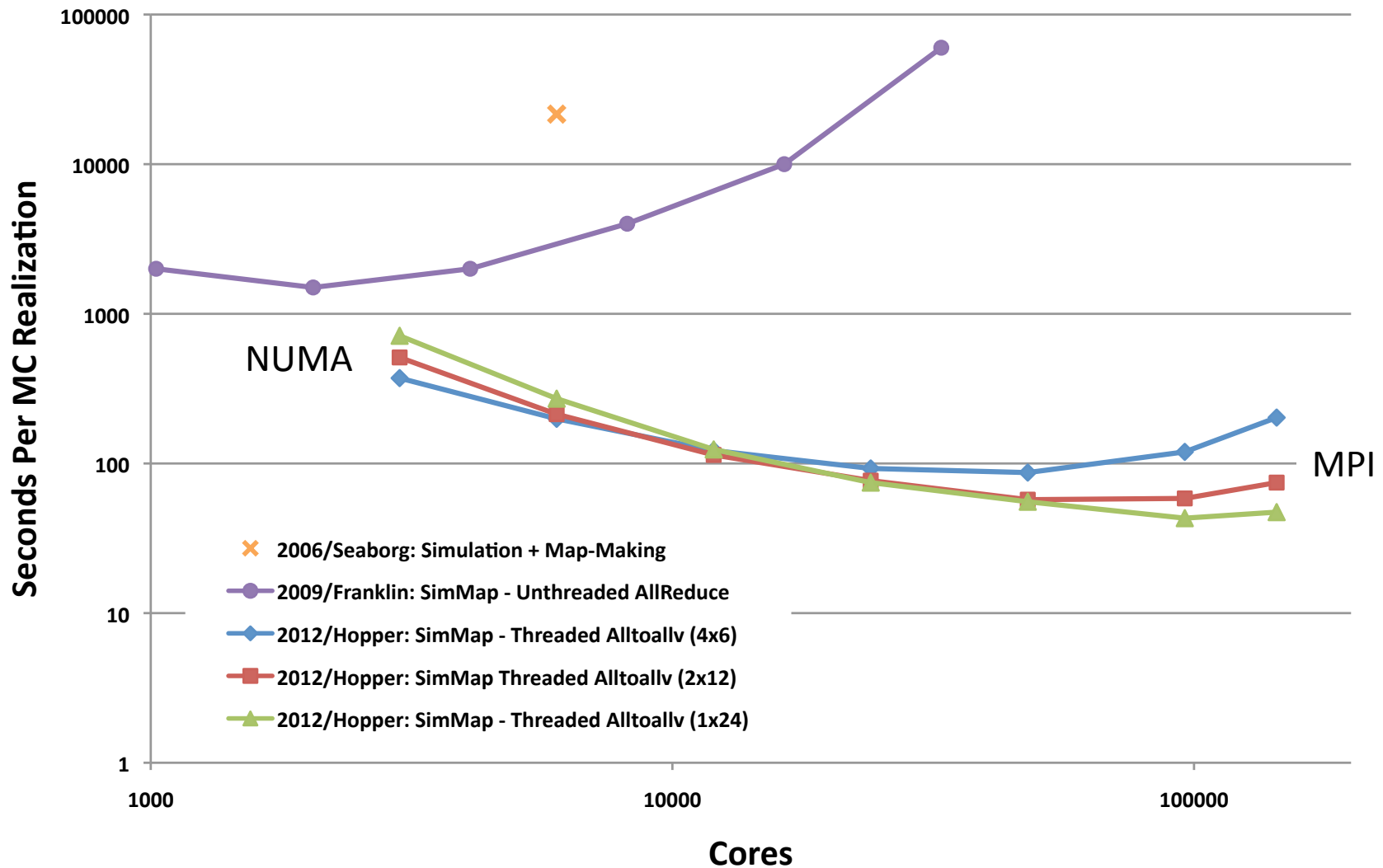


Architecture Evolution

- Clock speed is no longer able to maintain Moore's Law.
- Many-core and GPU are two major approaches.
- Both of these will require
 - significant code development
 - performance experiments & auto-tuning
- Eg. NERSC's Cray XE6 system *Hopper*
 - 6384 nodes
 - 2 sockets per node
 - 2 NUMA nodes per socket
 - 6 cores per NUMA node
- What is the best way to run hybrid code on such a system?



Configuration With Concurrency

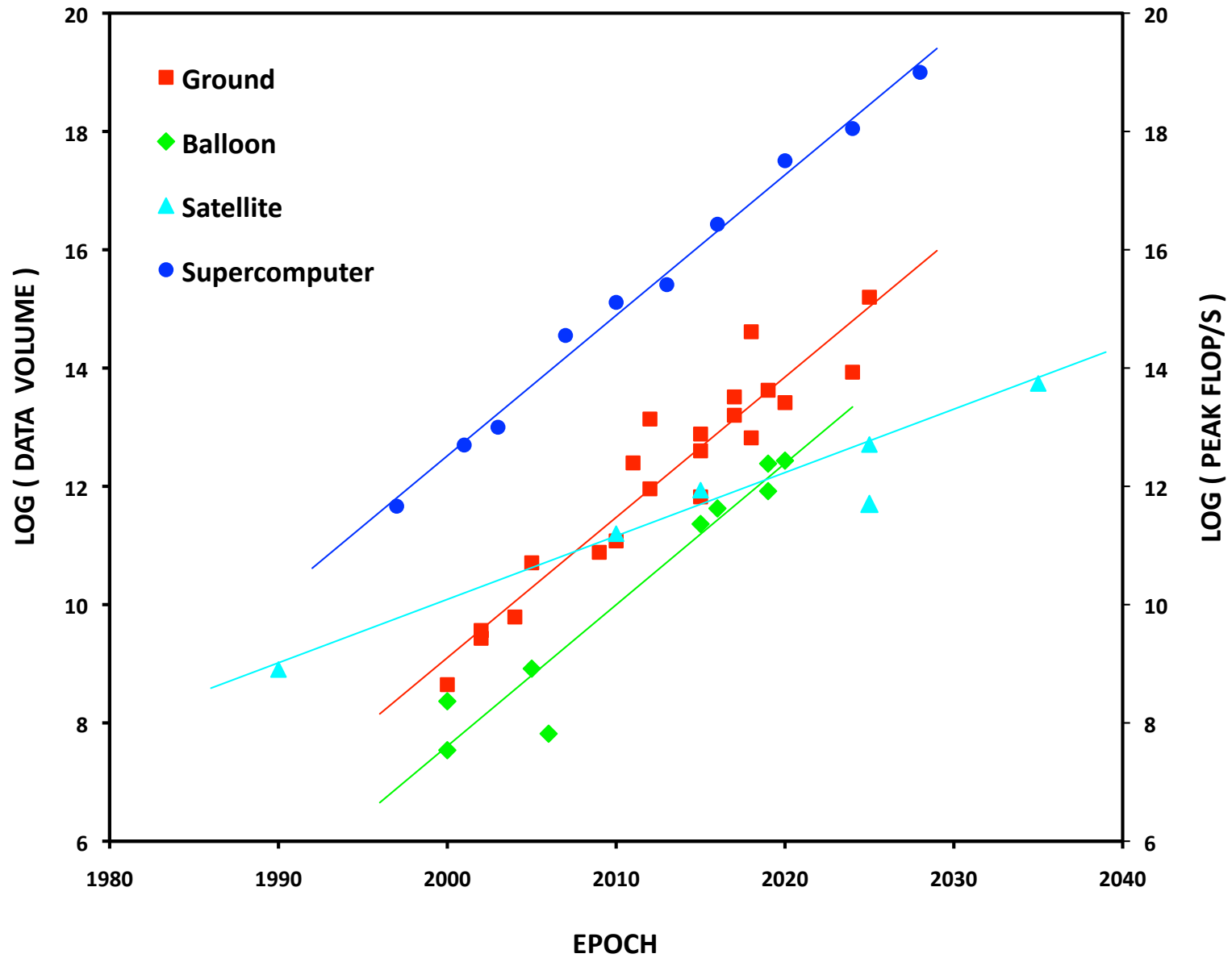


Results: Planck Full Focal Plane 8

- 10^4 Monte Carlo realizations reduced to 10^6 maps
 - multiple maps made per simulation

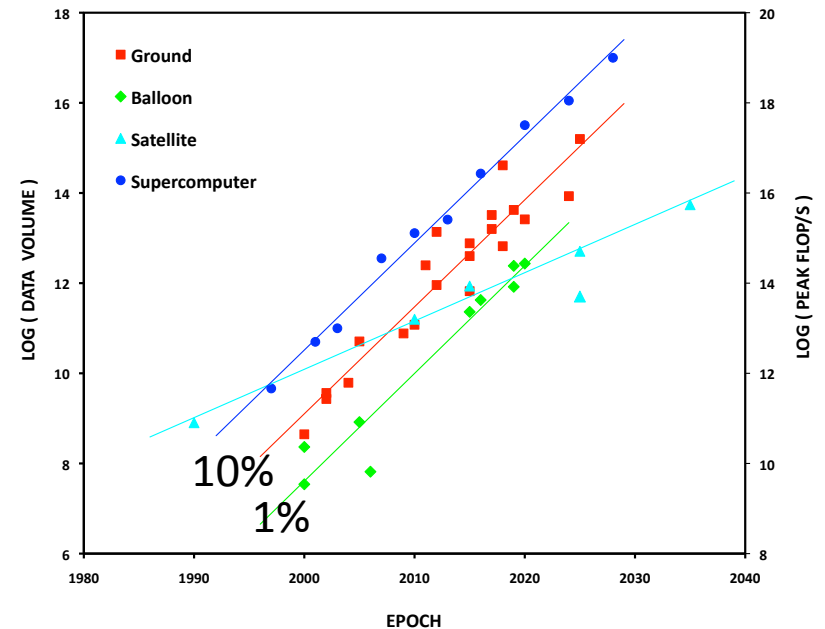


Data & HPC Growth



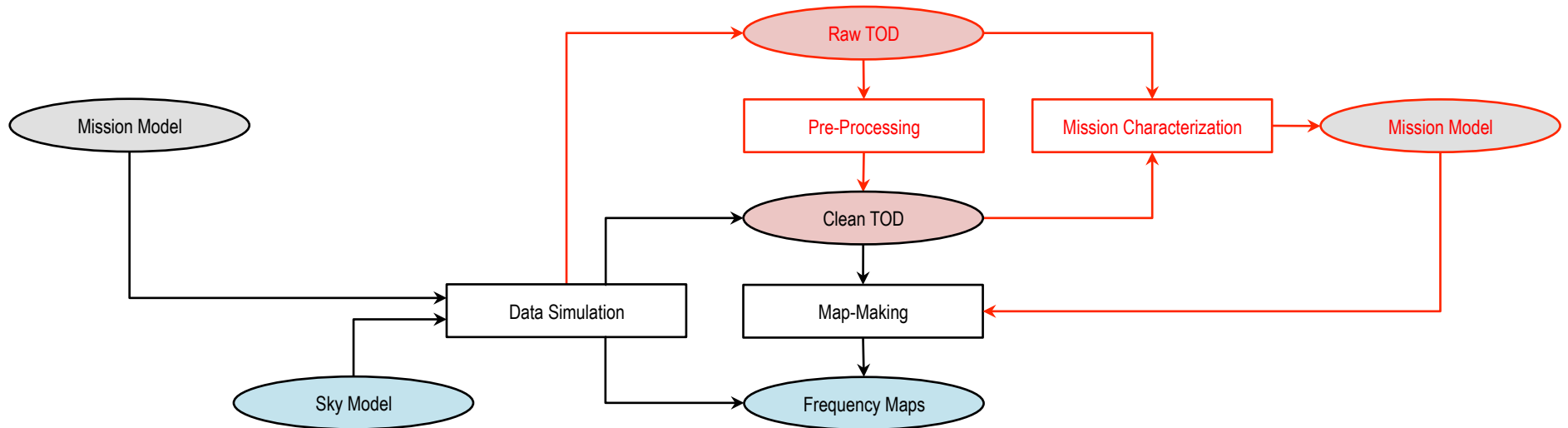
Next Generation Challenges

- Computational Efficiency
 - Required FLOP $\sim 10^7 \mathcal{N}_t$
 - Available FLOP $\sim 10^5 \times \text{Peak}$
 - Efficiency: $\varepsilon > 10^2 \mathcal{N}_t / \text{Peak}$
 - compare suborbital & space!



- Next-generation HPC challenges
 - Energy constraints limiting Watt/FLOP (Tianhe-2 ~ Belize!)
 - More complex architectures will be harder to program efficiently
 - system heterogeneity, deep memory hierarchies, dark silicon, etc
 - End of Moore's Law

Pre-Processing & Mission Characterization



- A limiting factor for Planck has been our ability to easily and quickly
 - simulate detector-level data in full detail
 - prototype pre-processing/mission characterization algorithms.
- As sensitivity increases, mitigating systematics and characterizing their residuals becomes ever more important.

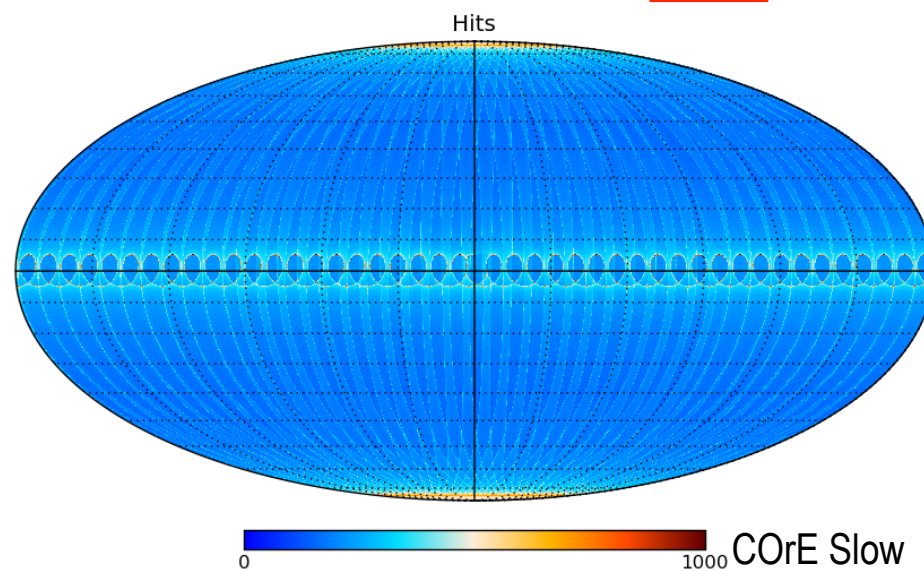
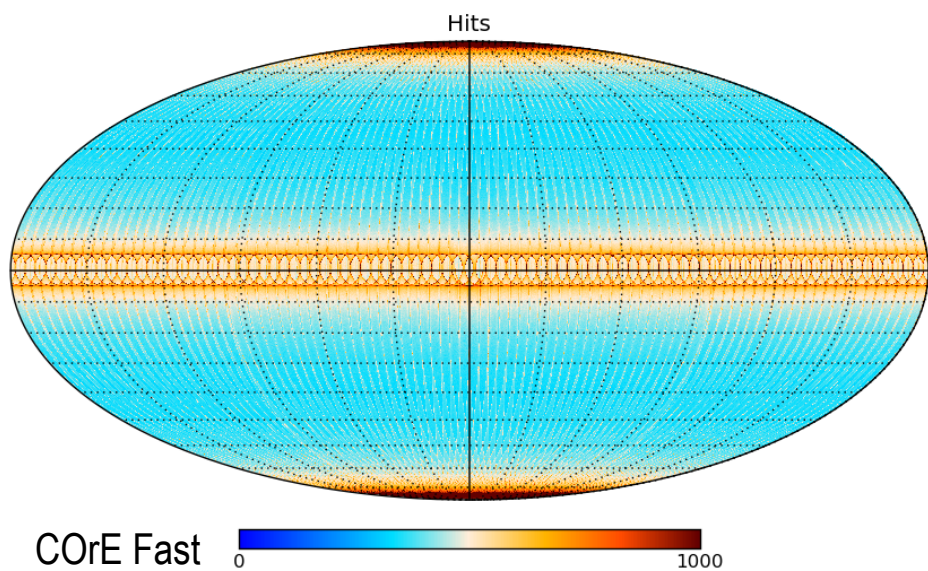
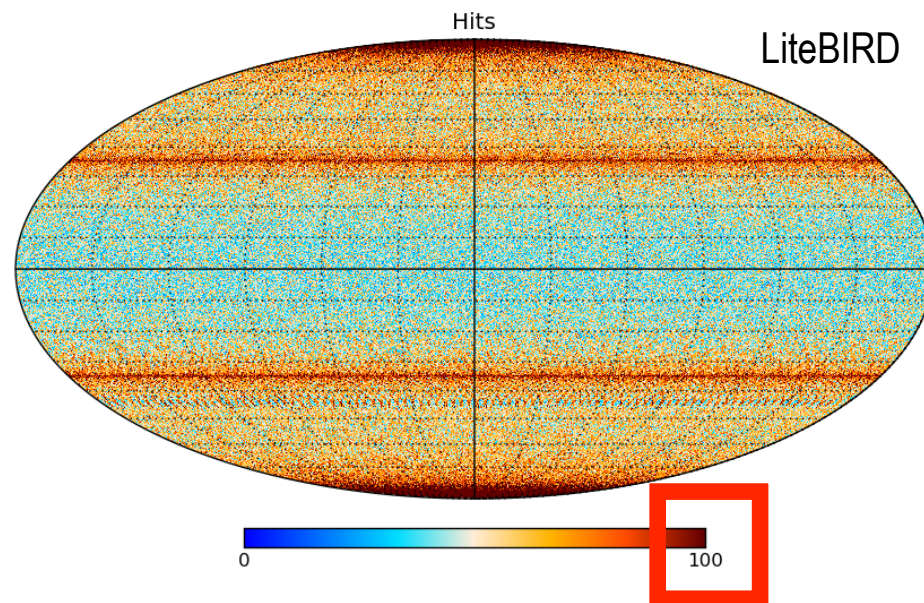
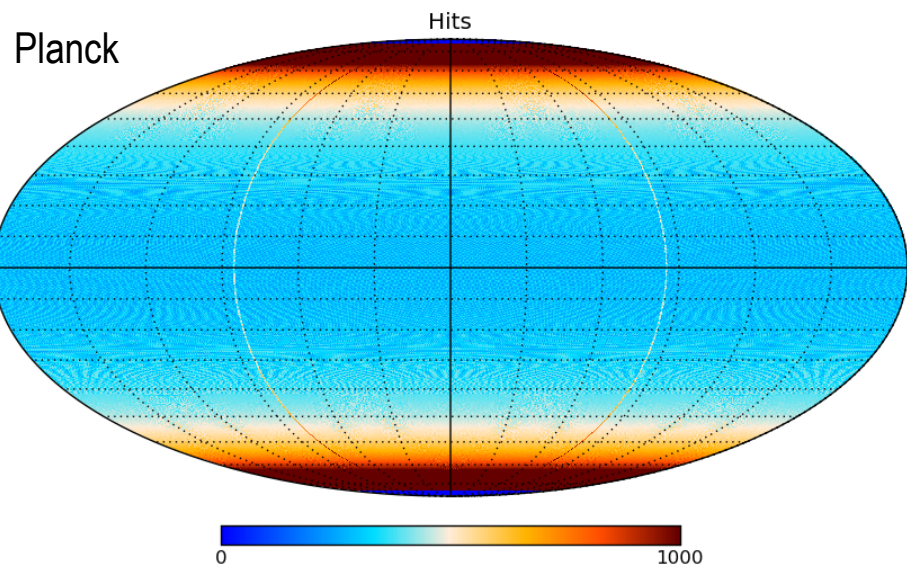
TOAST Overview

- Competing requirements:
 - Massively parallel & very efficient even on coming HPC architectures
 - Easy for non-HPC experts to adapt, extend & run
- Re-implement entire TOAST framework as open source python modules
 - Expanded developer base
 - Rapid prototyping
 - Split generic and experiment-specific elements
- Efficiency issues:
 - Start-up cost: pre-bundle libraries (eg. pyinstaller)
 - I/O avoidance: pass data between modules in memory
 - Compute efficiency: link to compiled C(++) code at key points

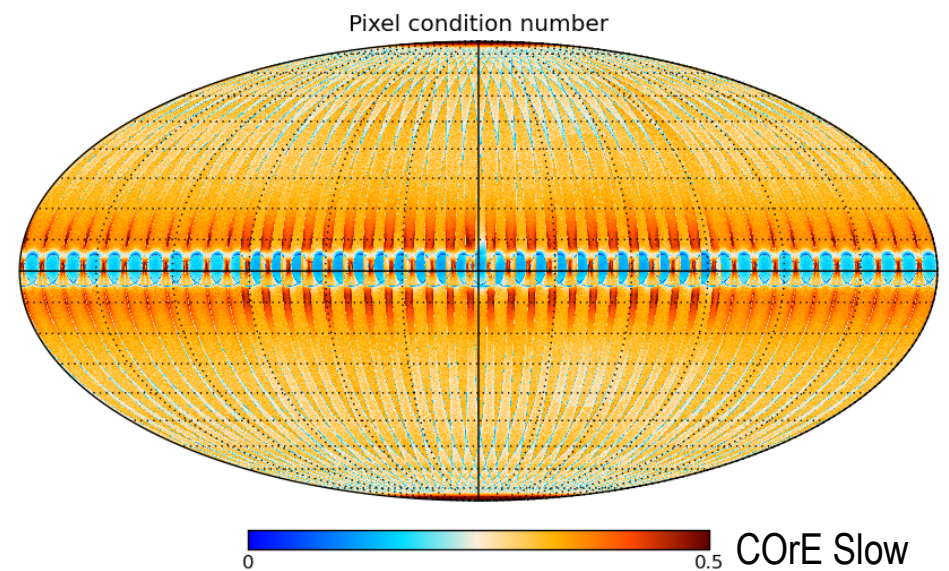
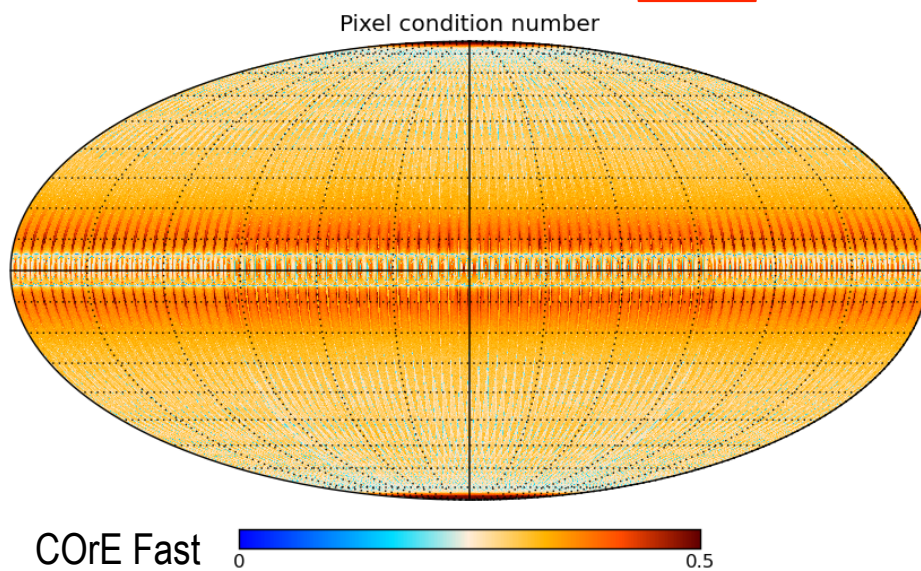
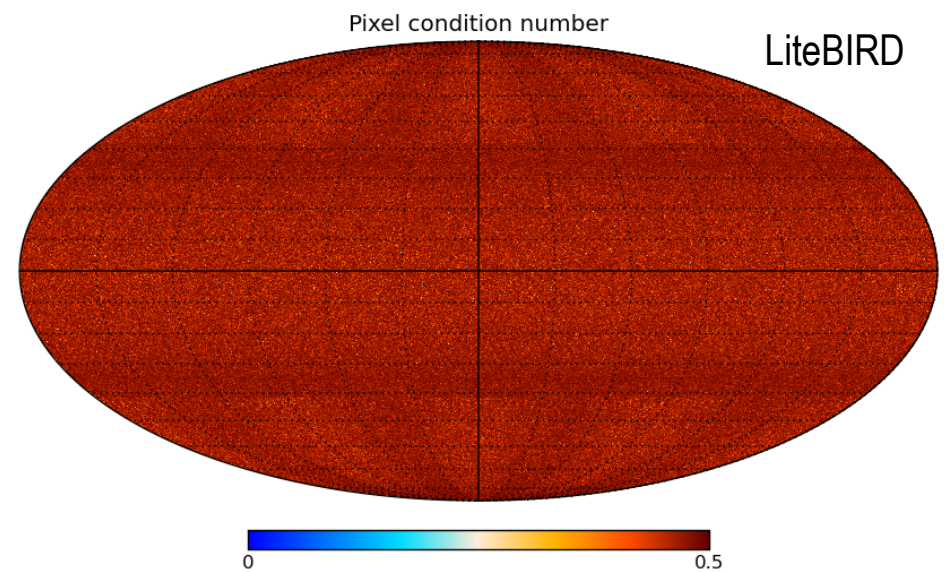
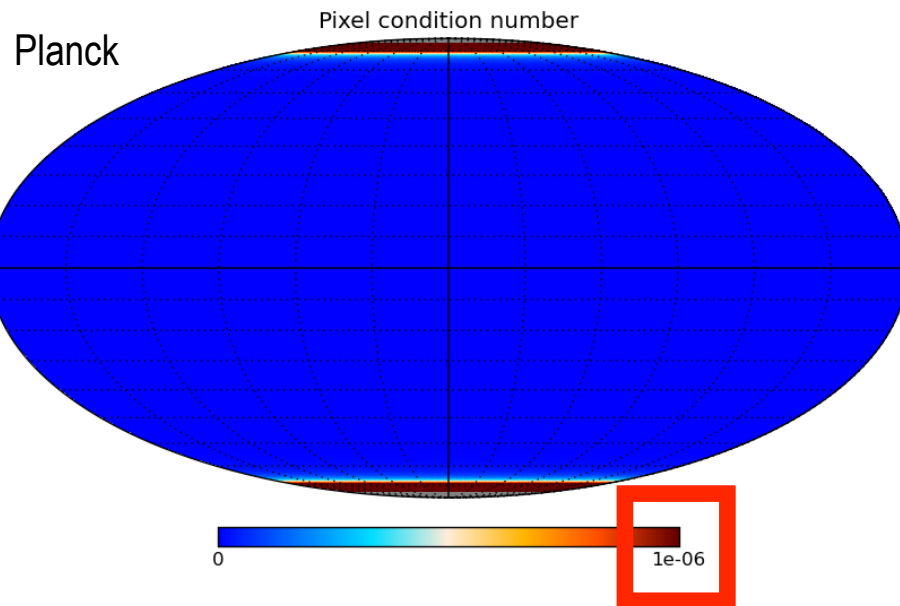
Example: Single-Detector Maps

- Single-detector maps provide powerful systematics tests since they avoid beam, bandpass mismatch issues.
 - Also provide checks on single-detector systematics (side-lobes etc)
- Polarized single-detector maps require observations of each pixel with many attack angles.
- Comparing scanning strategies is an inherently time-domain activity.
- Satellite scans parameterized by precession & spin angles & rates.
- Compare 4 cases:
 - Planck
 - LiteBIRD (with HWP)
 - COrE fast spin
 - COrE slow spin

Example: Single-Detector Hit Maps

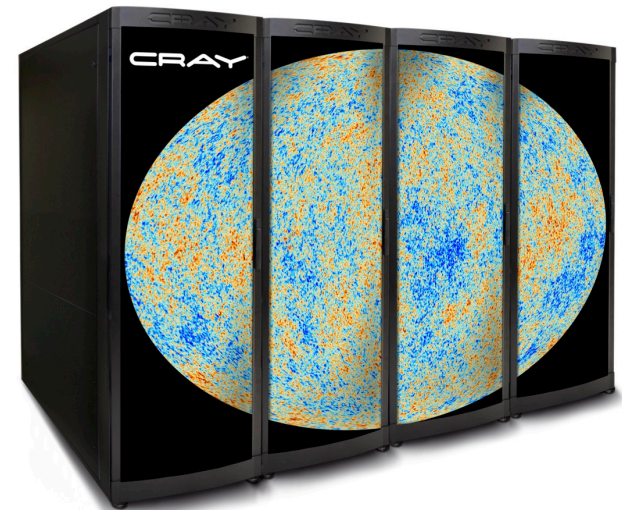


Example: Single-Detector Condition Maps

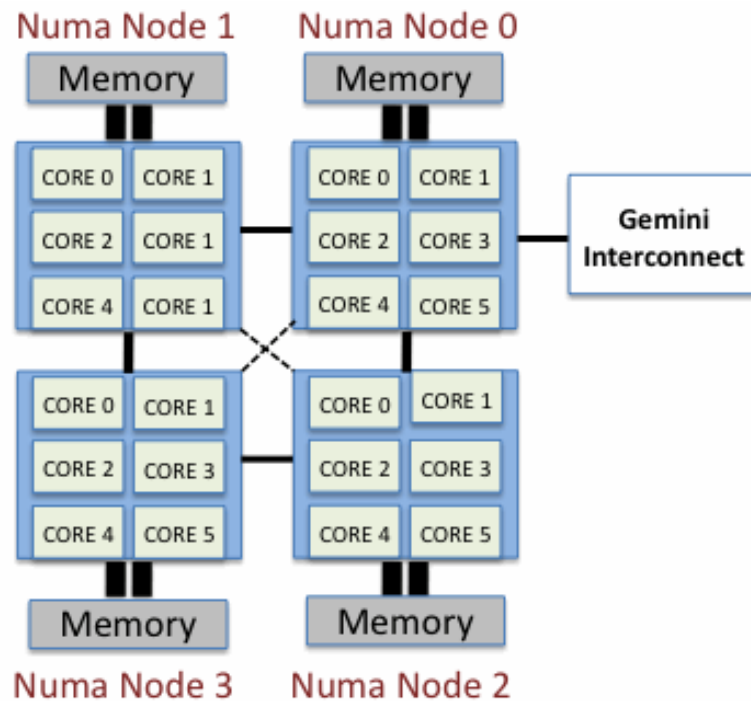


TOAST Status

- Base framework & generic tools/scripts
 - Public git repo <https://github.com/hpc4cmb/toast>
- Experiment-specific extensions & scripts:
 - Private git repos <https://github.com/hpc4cmb/toast-X>
 - X: toast-planck, toast-litebird, toast-core, toast-cmb4, etc
- Planned additions/extensions:
 - **Xeon Phi KNL port/optimization**
 - On-the-fly band-pass integration
 - HWP-varying beam, bandpass
 - Multichroic/multiplexed cross-talk
 - Planet/variable source observations
 - Atmosphere & ground-pickup

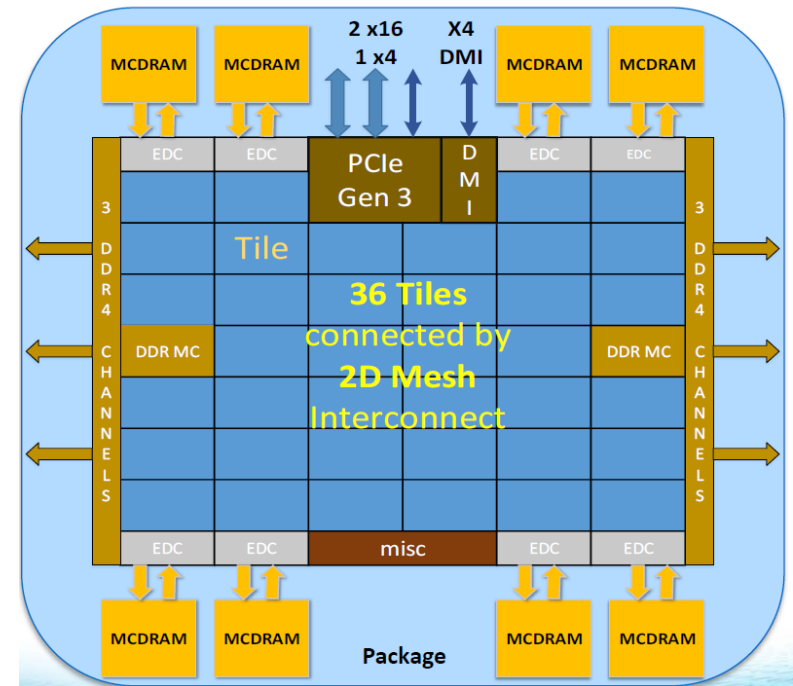


Energy-Constrained Node Evolution



Magny-Cours
(24 threads)

=>



Knights Landing
(~160 threads)

A Modest Proposal

- A two-tier community-wide program:
 - developing common, generic capabilities in the public domain
 - deploying them for specific analyses within our various collaborations

