

Probing Dark Energy with the
Canadian Hydrogen Intensity
Mapping Experiment

Richard Shaw



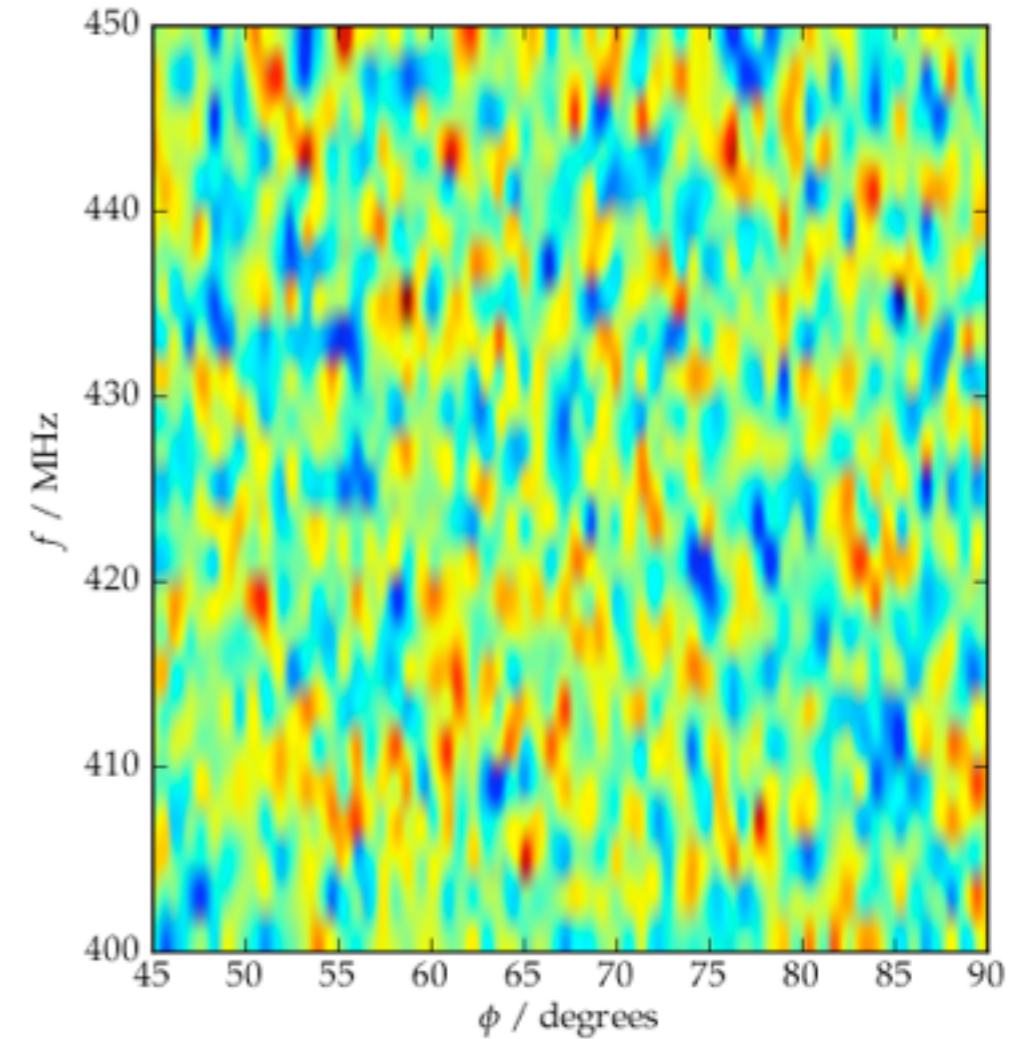
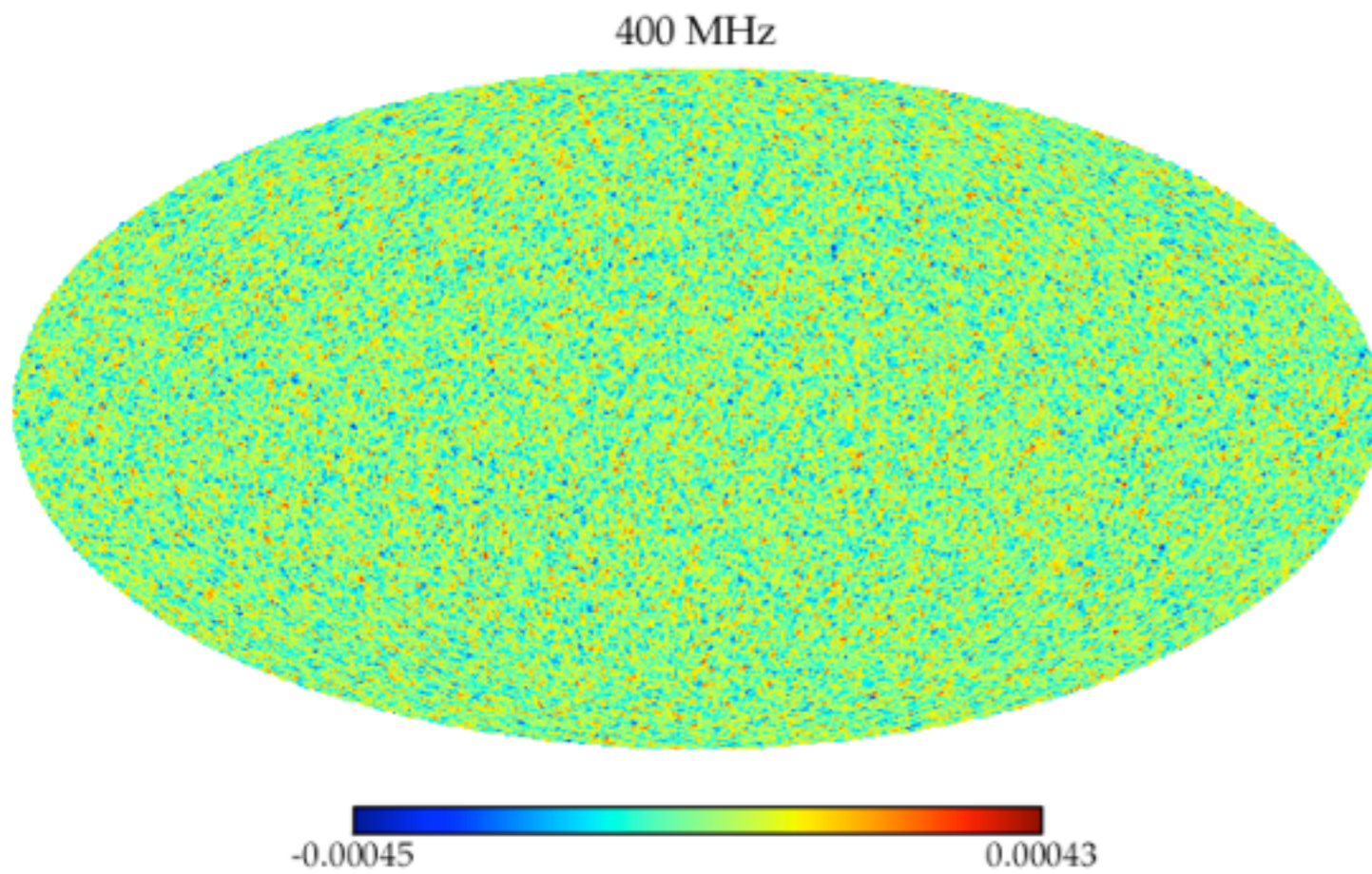
a place of mind

THE UNIVERSITY OF BRITISH COLUMBIA

Outline

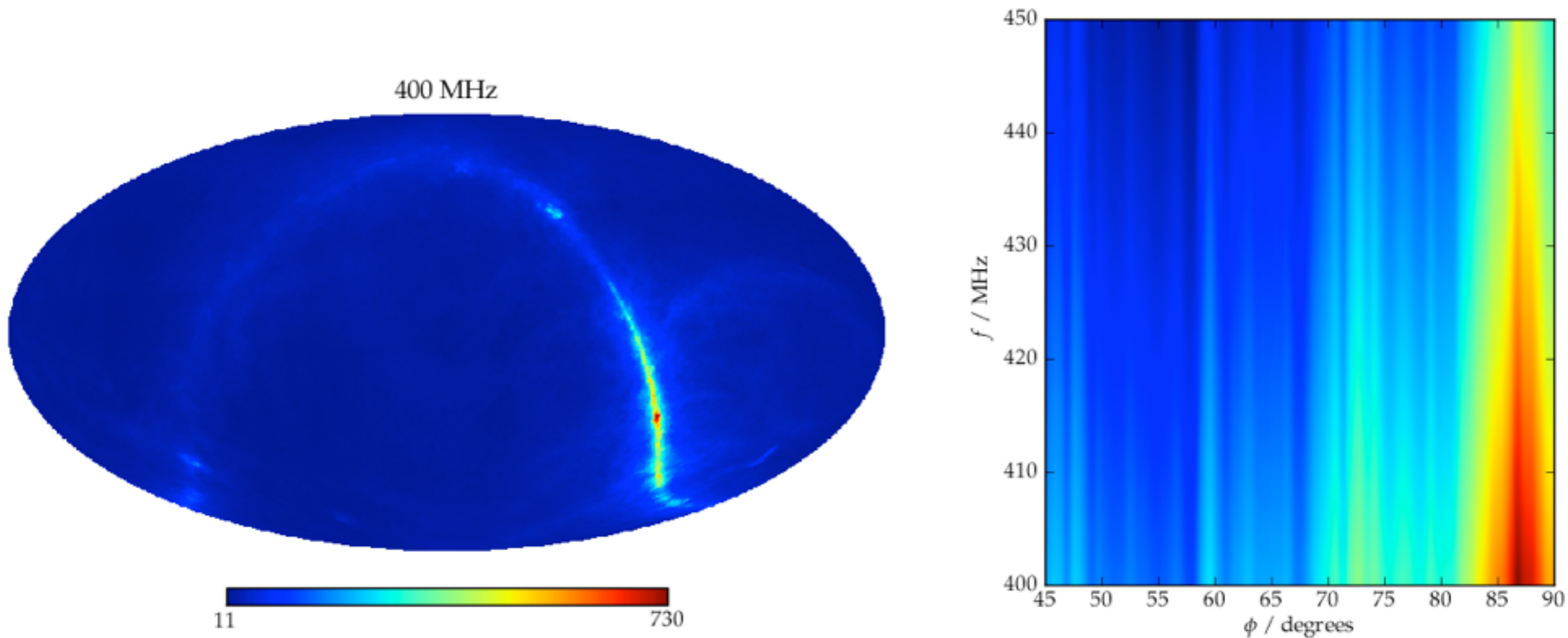
- Brief intro
- CHIME
- Data analysis
 - ▶ M-mode transform
 - ▶ Map making
 - ▶ Foreground removal

Foreground Challenges



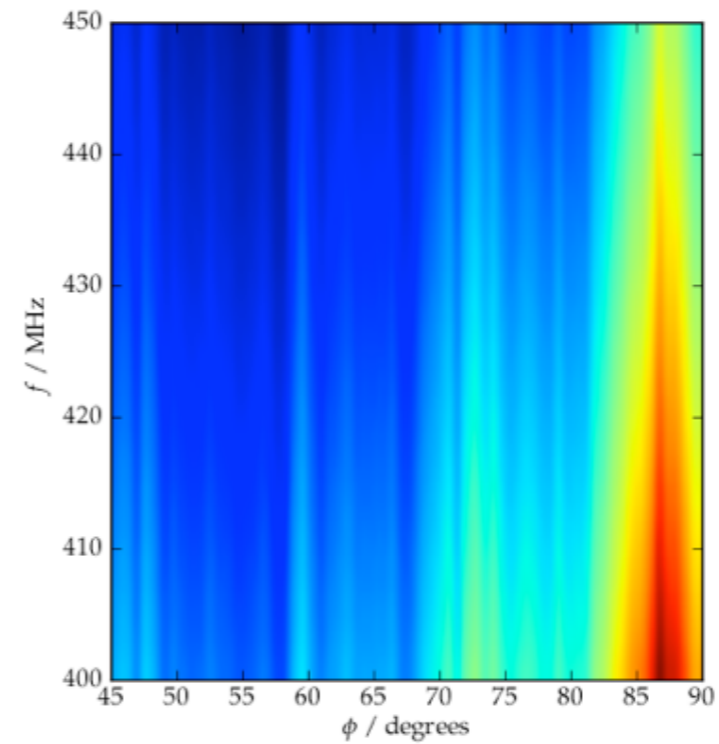
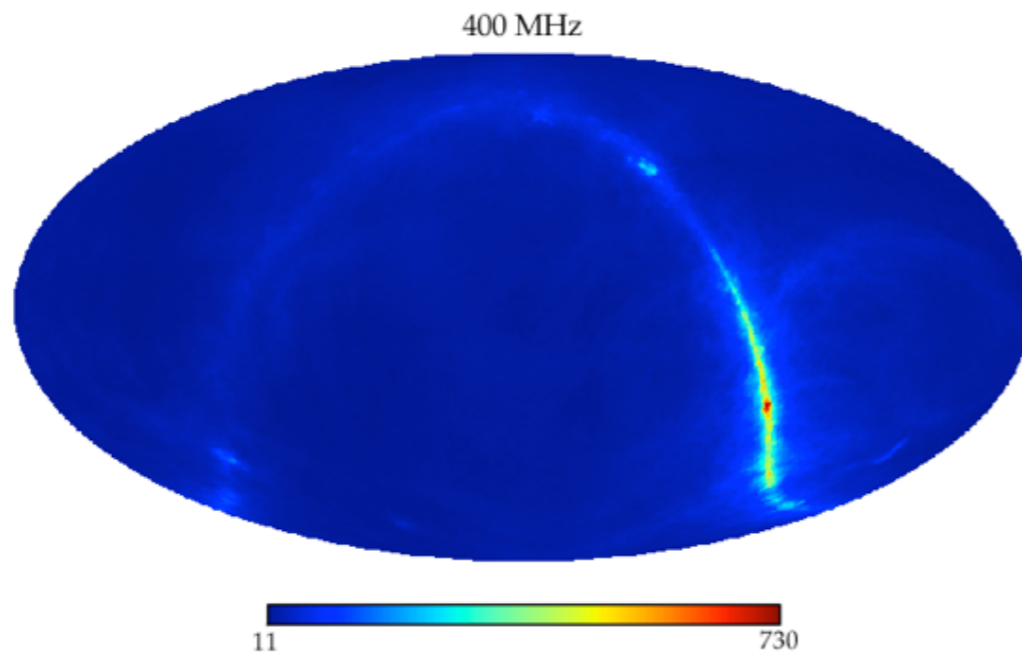
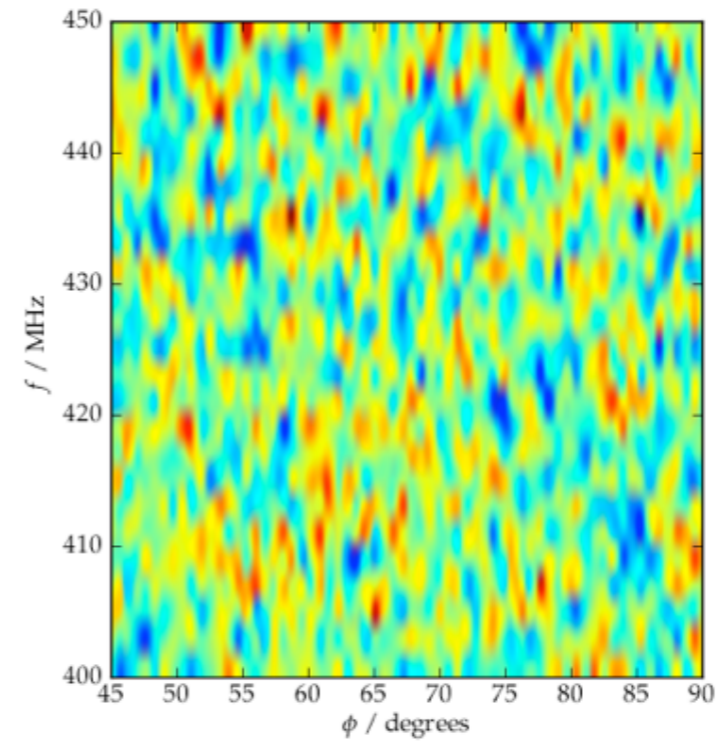
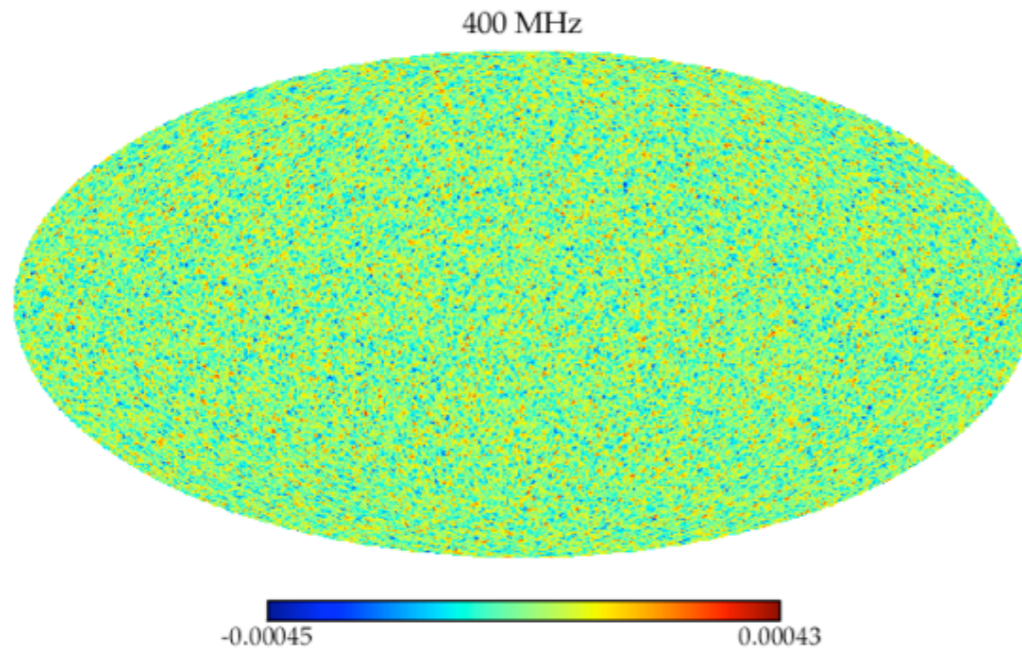
Cosmological 21cm Signal $\sim 1\text{mK}$

Foreground Challenges

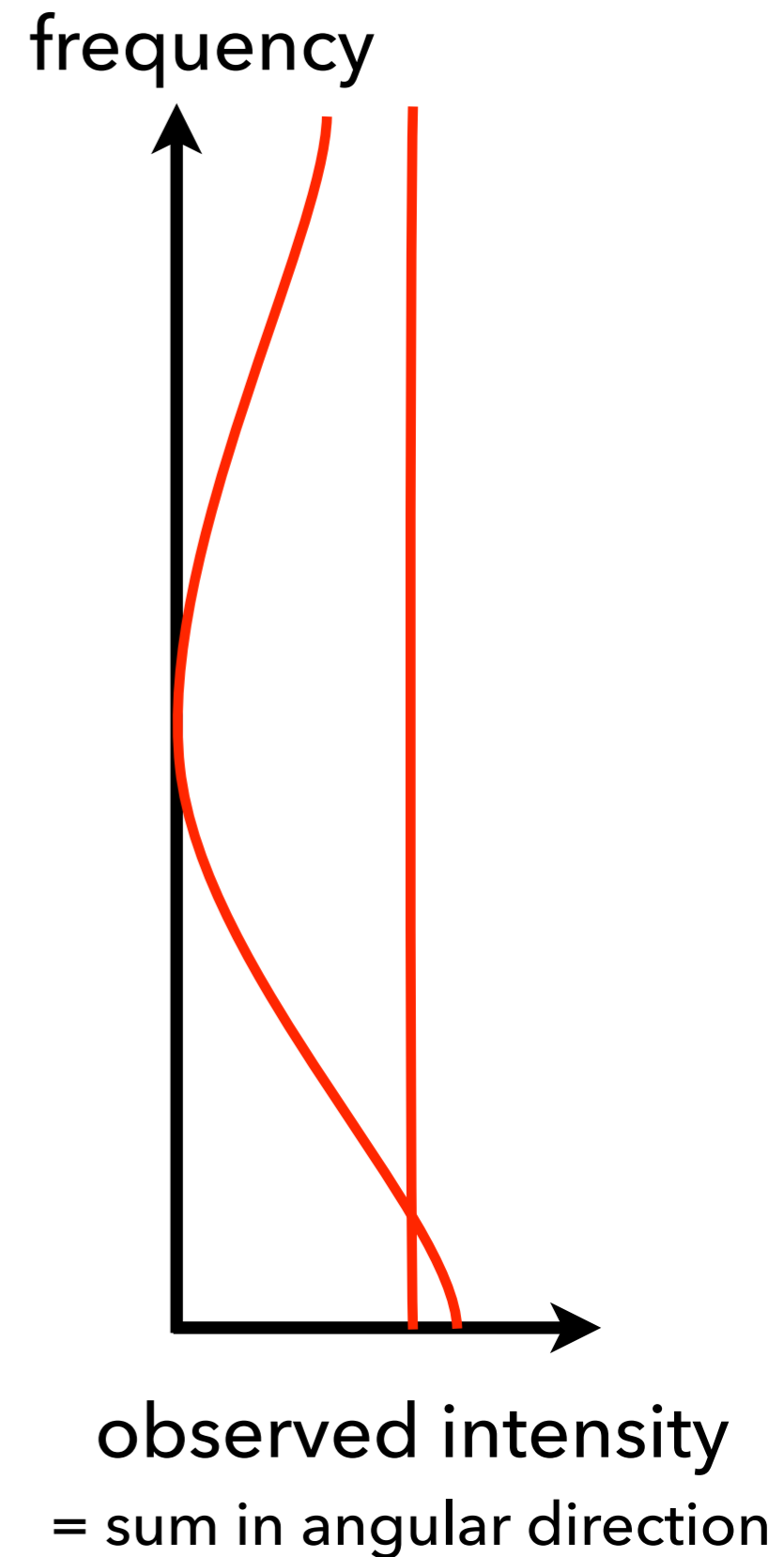
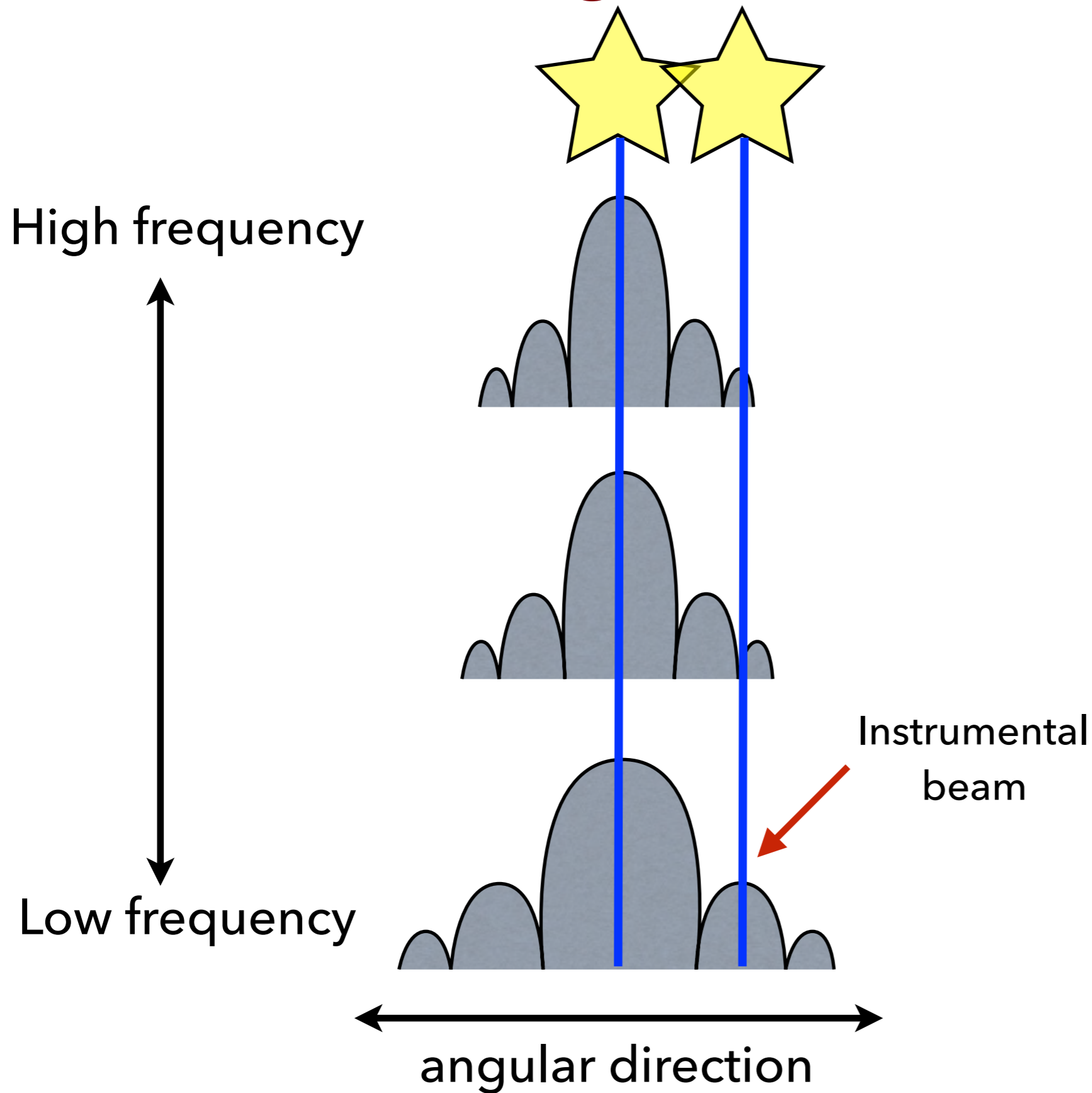


Galaxy: up to 700K

A way out?



Mode mixing

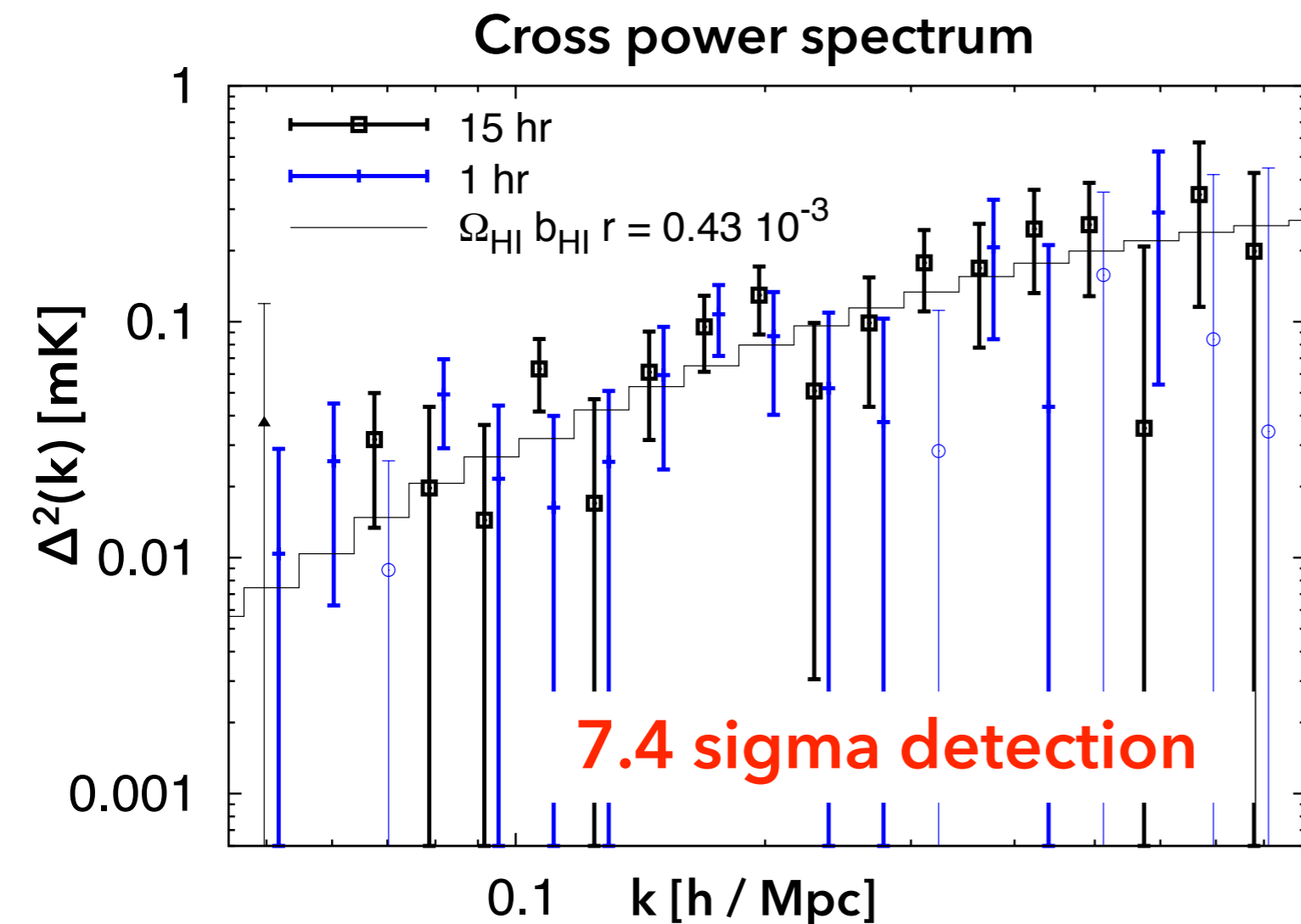


Intensity Mapping at Green Bank

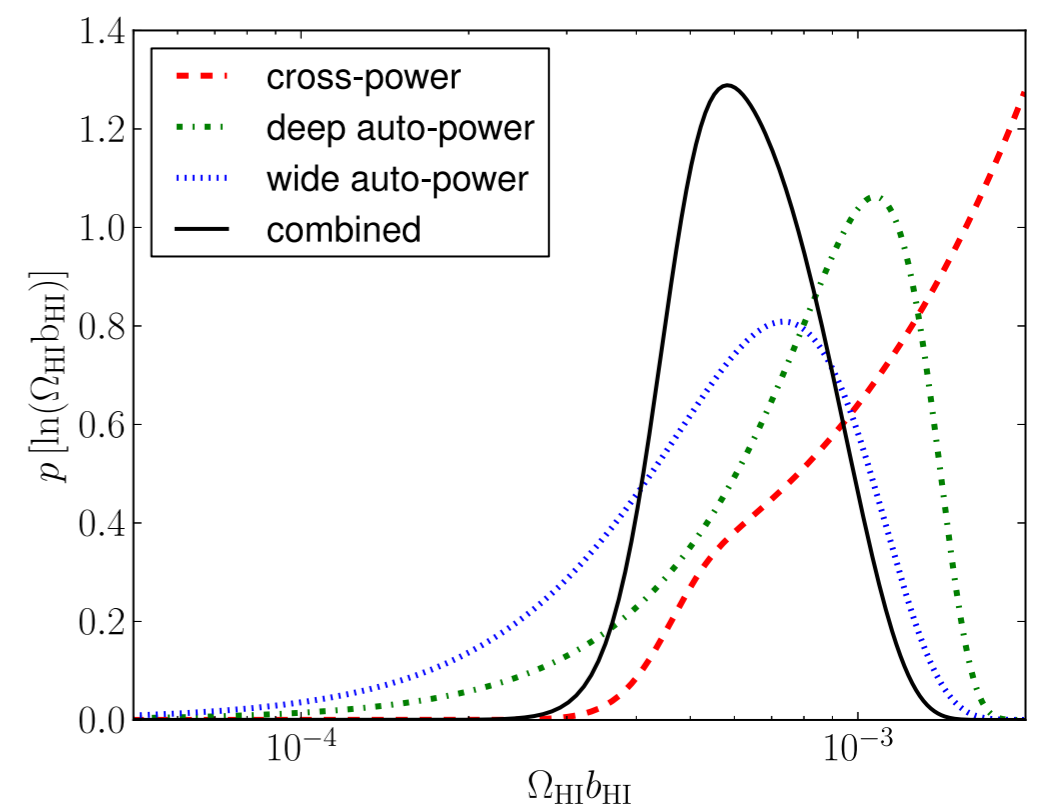


Cross correlation detection

- Correlation with DEEP2 Galaxy survey by Chang et al. (2010) - *avoids foreground problem!*
- Updated using WiggleZ survey (Masui et al. 2012)



$$\Omega_{\text{HI}} = [0.62^{+0.25}_{-0.15}] \times 10^{-3}$$

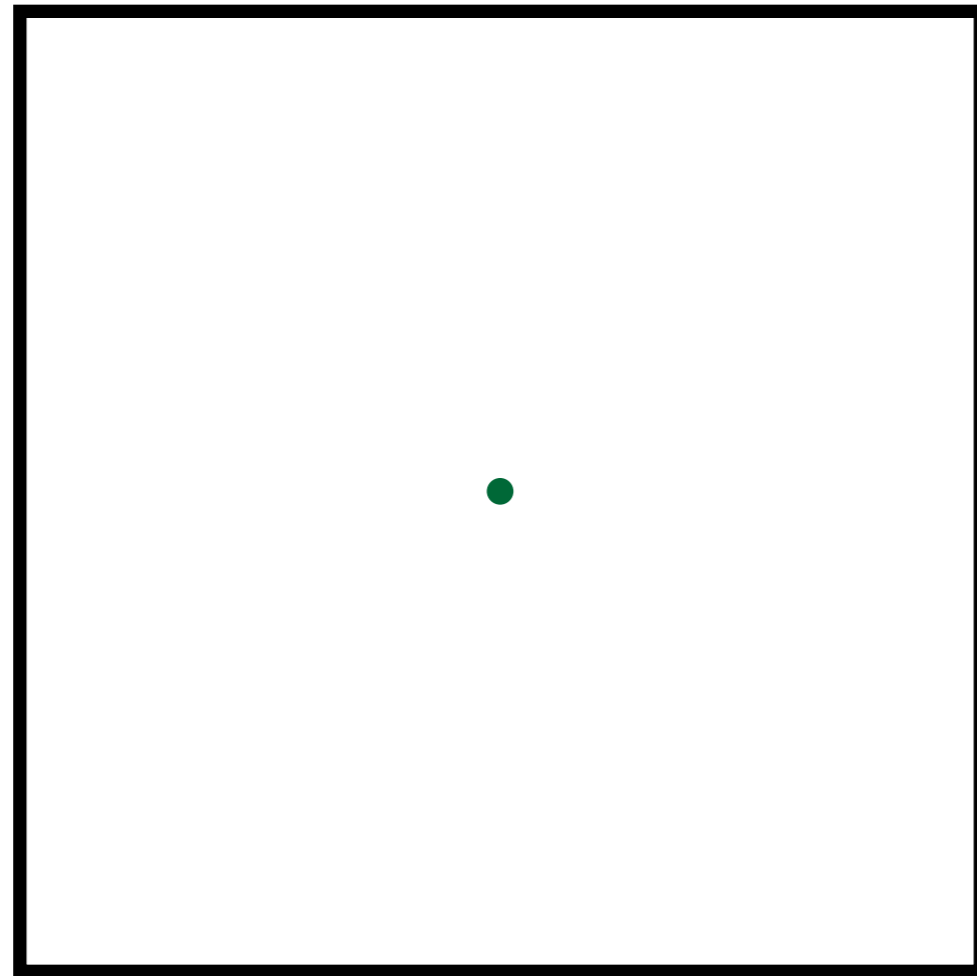


Next Generation Experiments

The Future?

- Observations like this are slow. To survey the whole sky to this depth ~ 20 years
 - ▶ Is there a better way to do this?

Single Dish

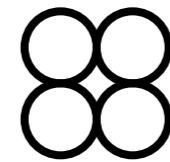
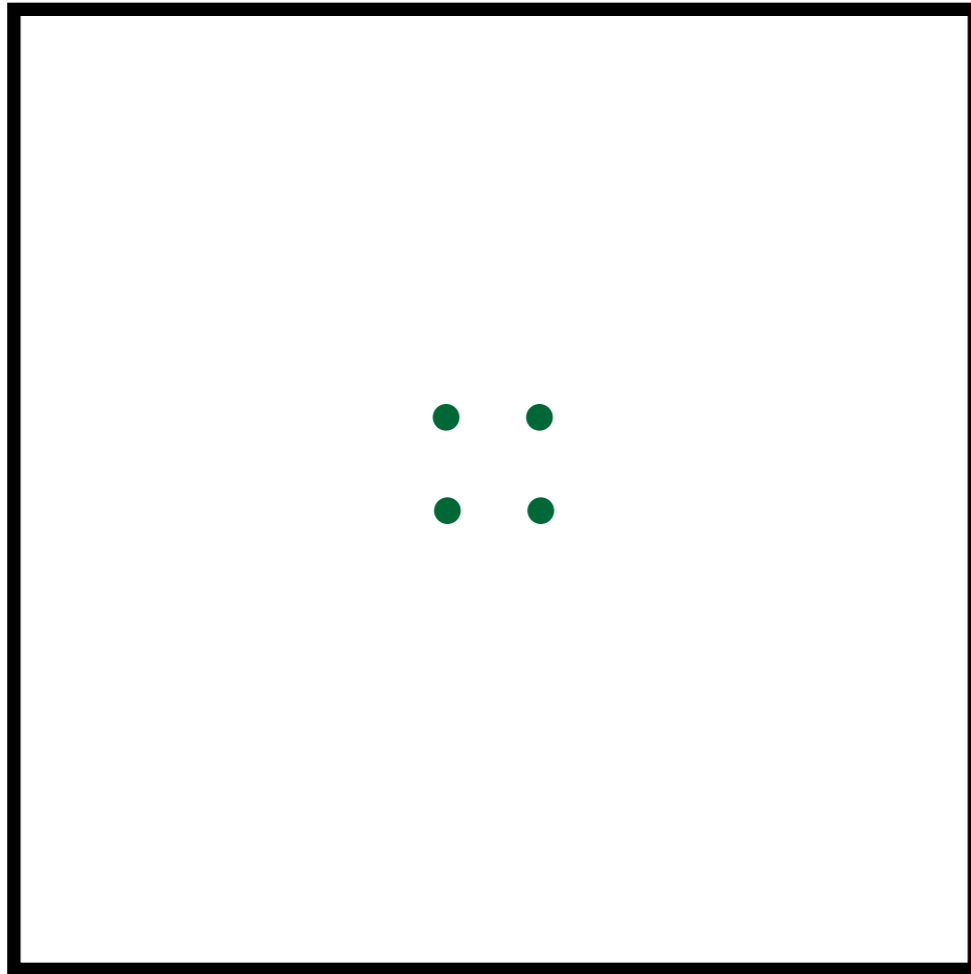


100m

O  15'

- Slow survey
- Noise: σ_T

Focal Plane Array

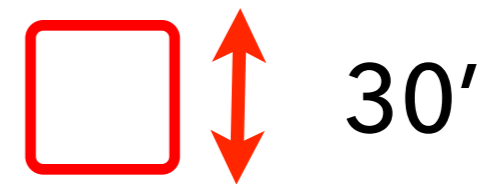
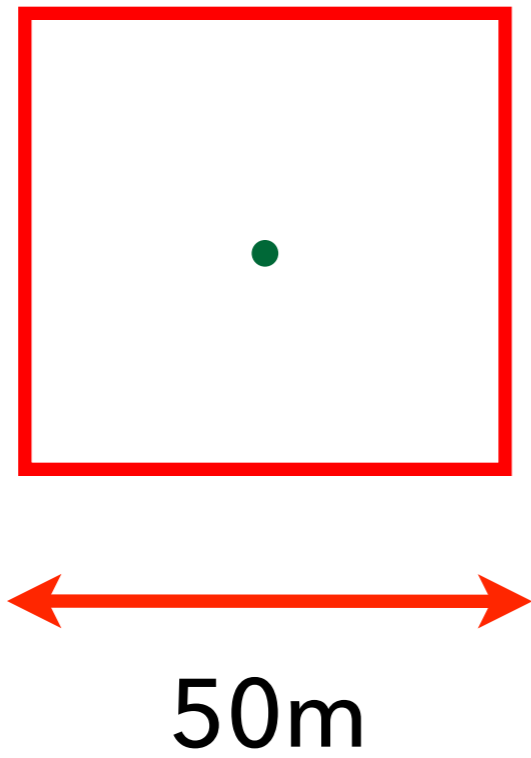


- Slightly offset feeds
- Each beam noise: σ_T
- 4x faster survey

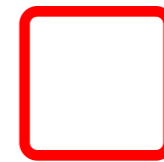
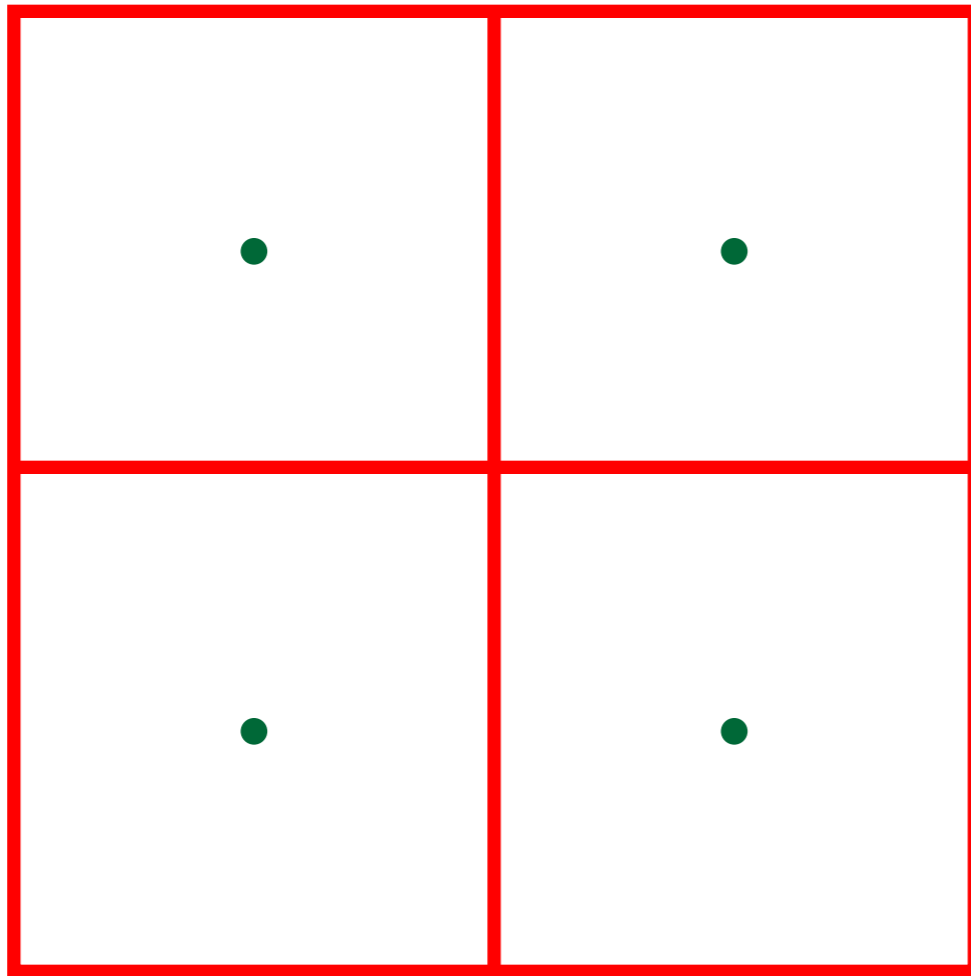
Interferometers



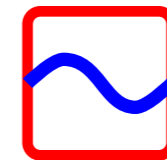
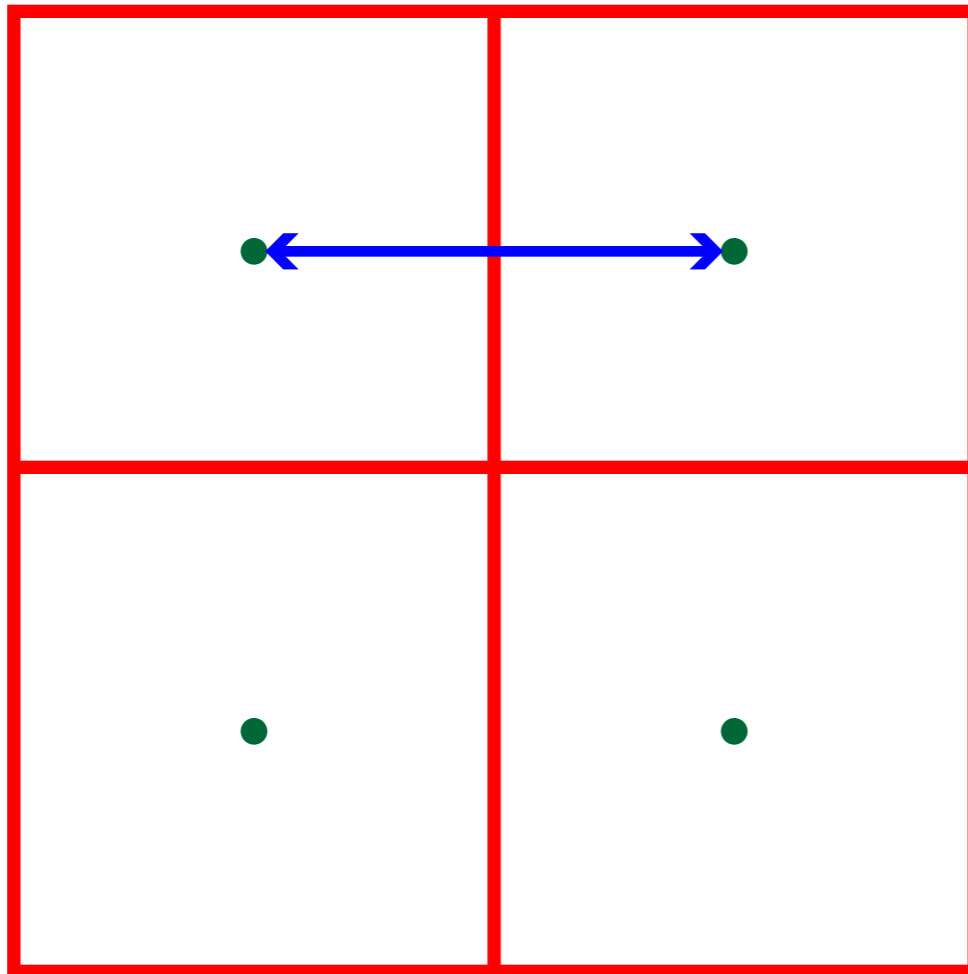
2x2 Interferometer



2x2 Interferometer

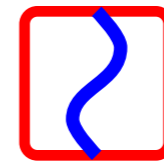
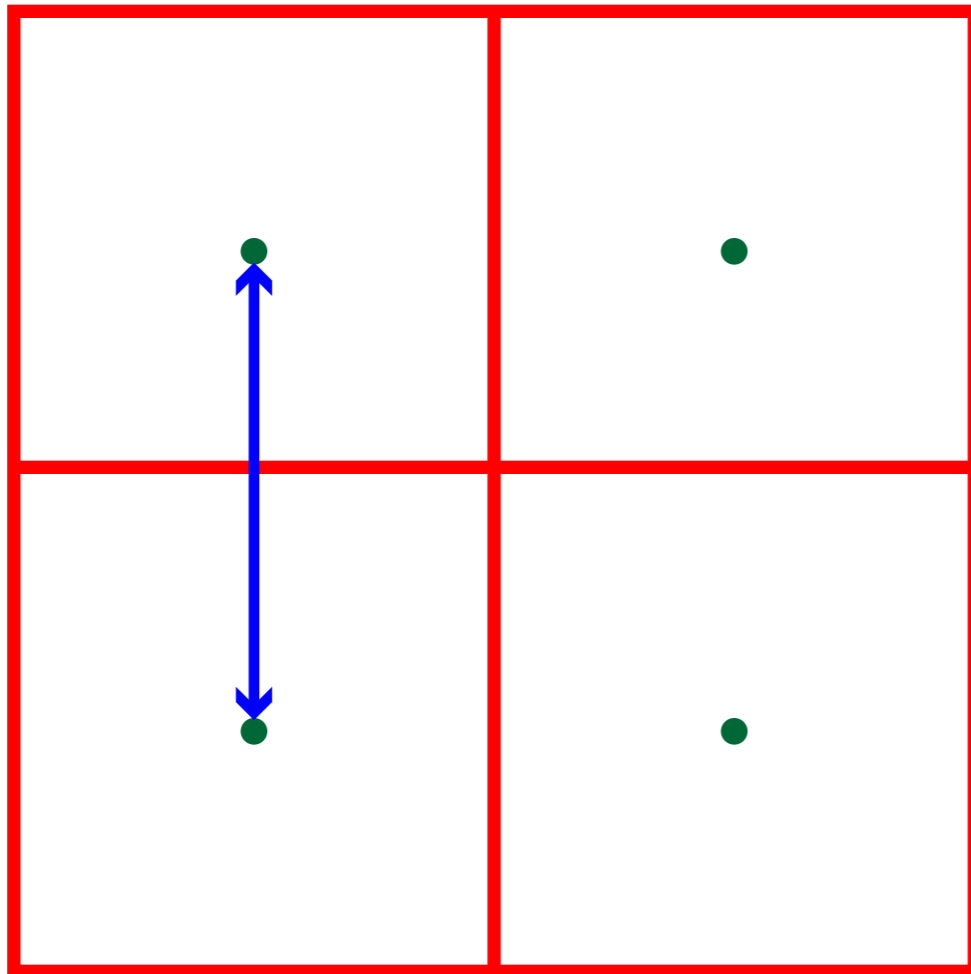


2x2 Interferometer



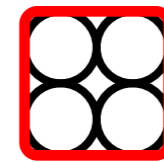
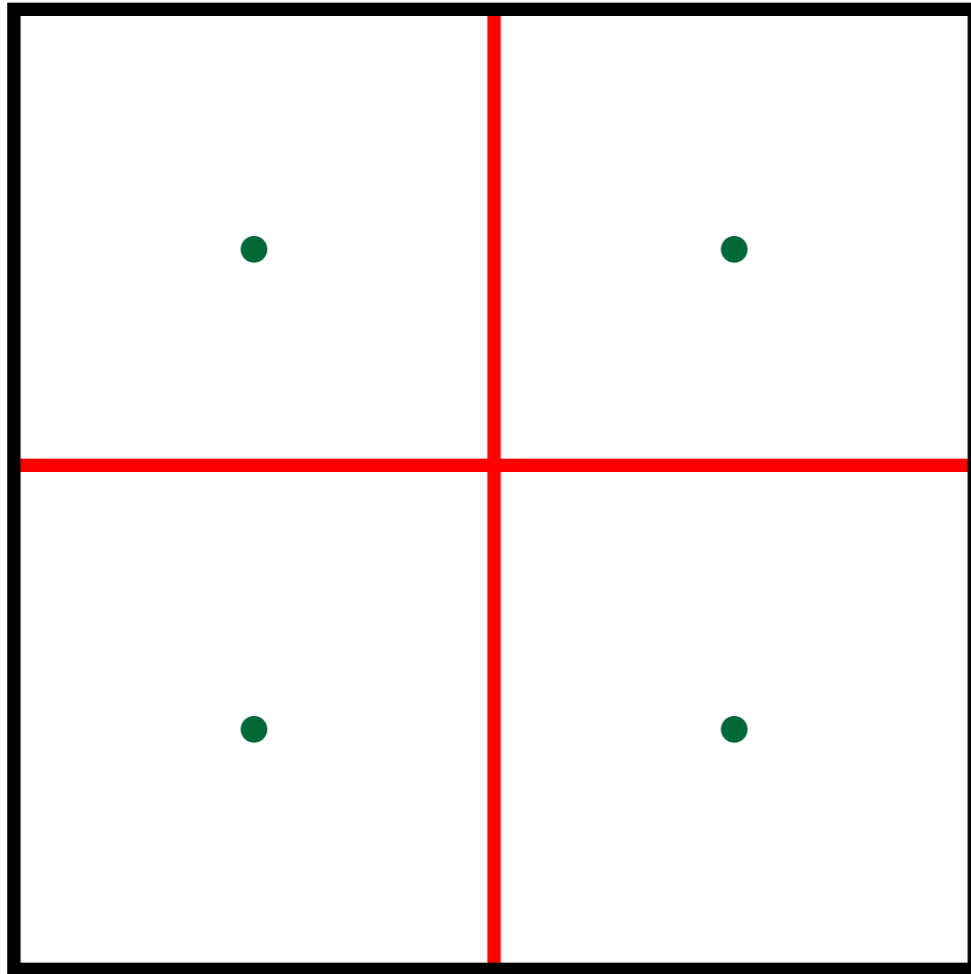
- Measure fourier modes in redbox (primary beam)

2x2 Interferometer



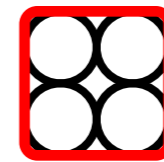
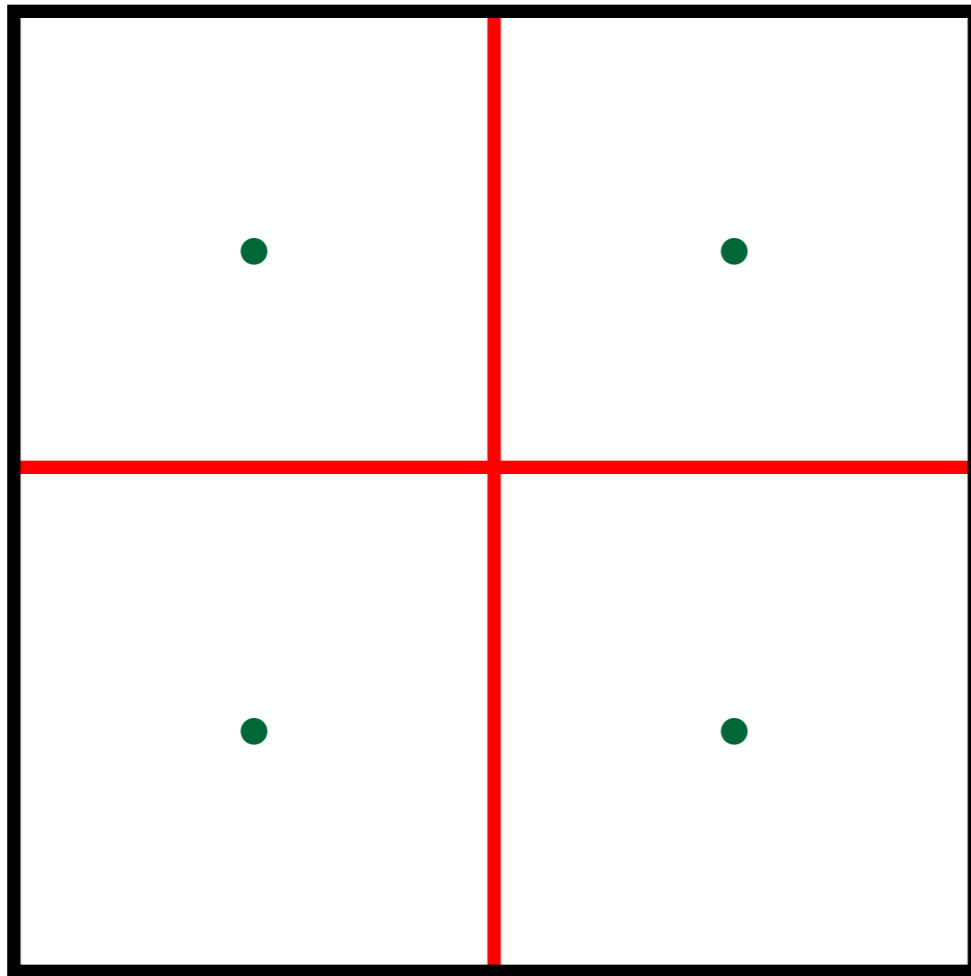
- Measure fourier modes in redbox (primary beam)

2x2 Interferometer



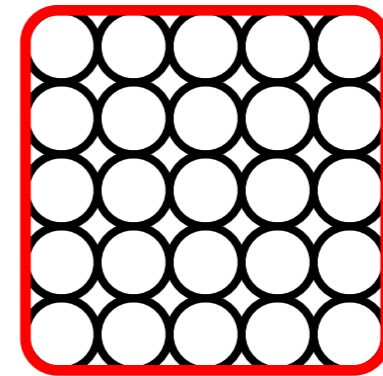
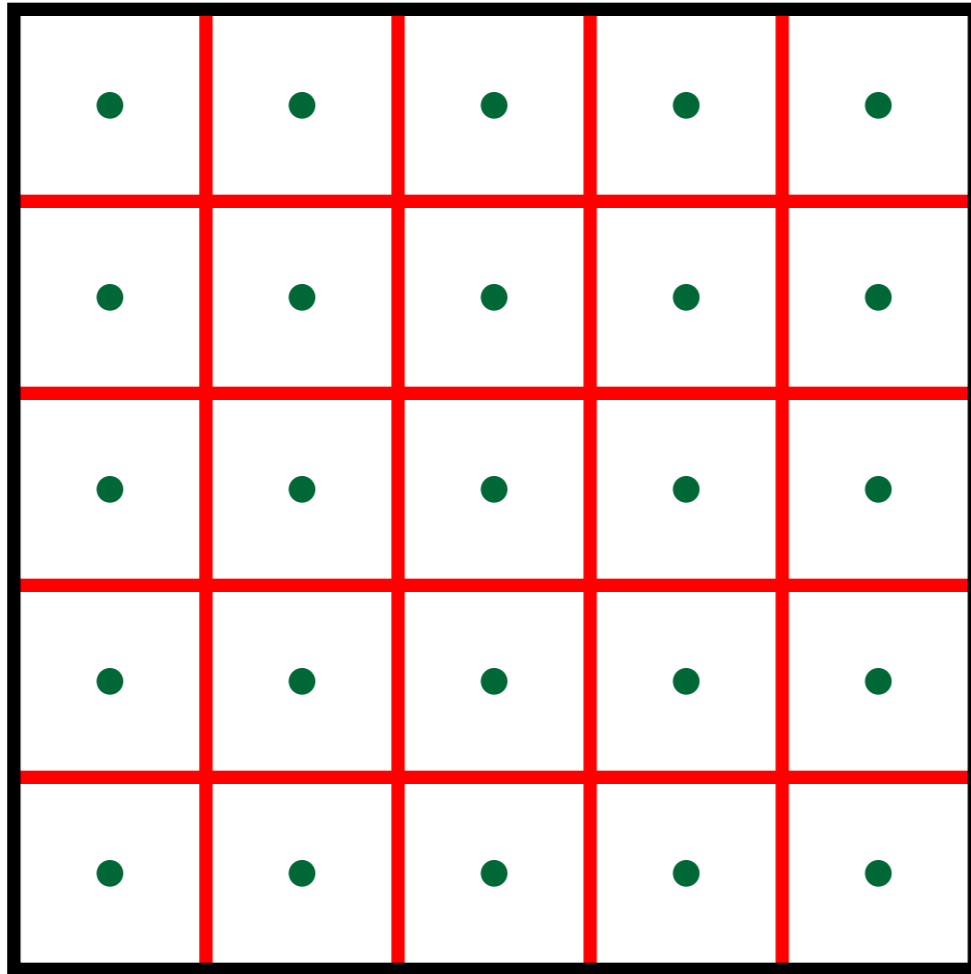
- Linear combinations give independent beams

2x2 Interferometer



- Each beam has noise σ_T
- 4x faster, with same noise and resolution

5x5 Interferometer



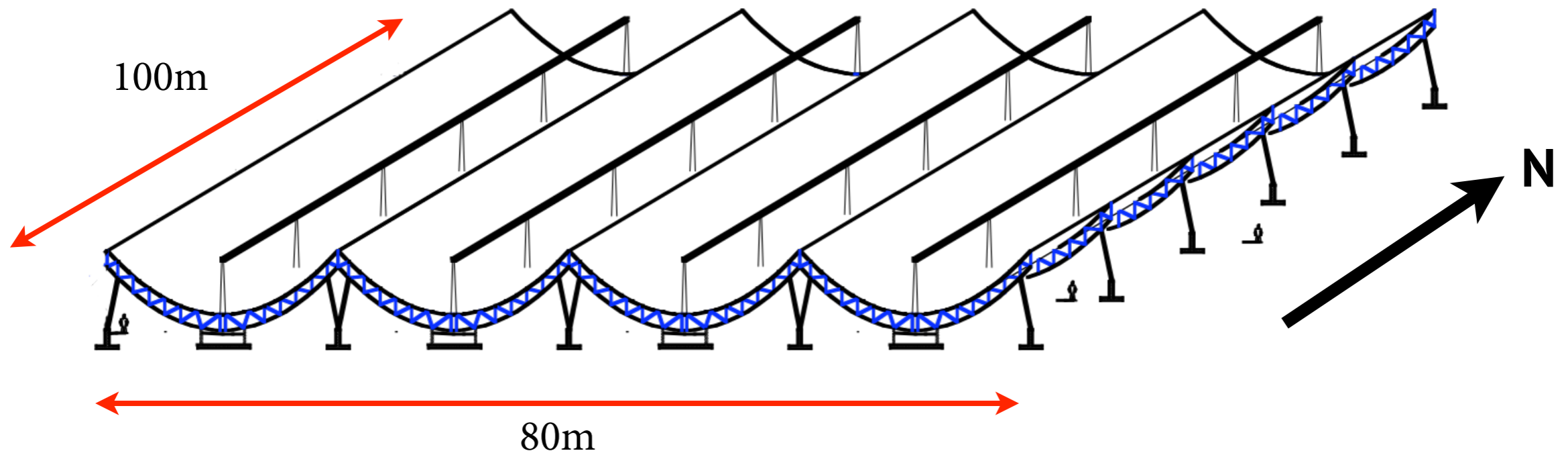
25x faster



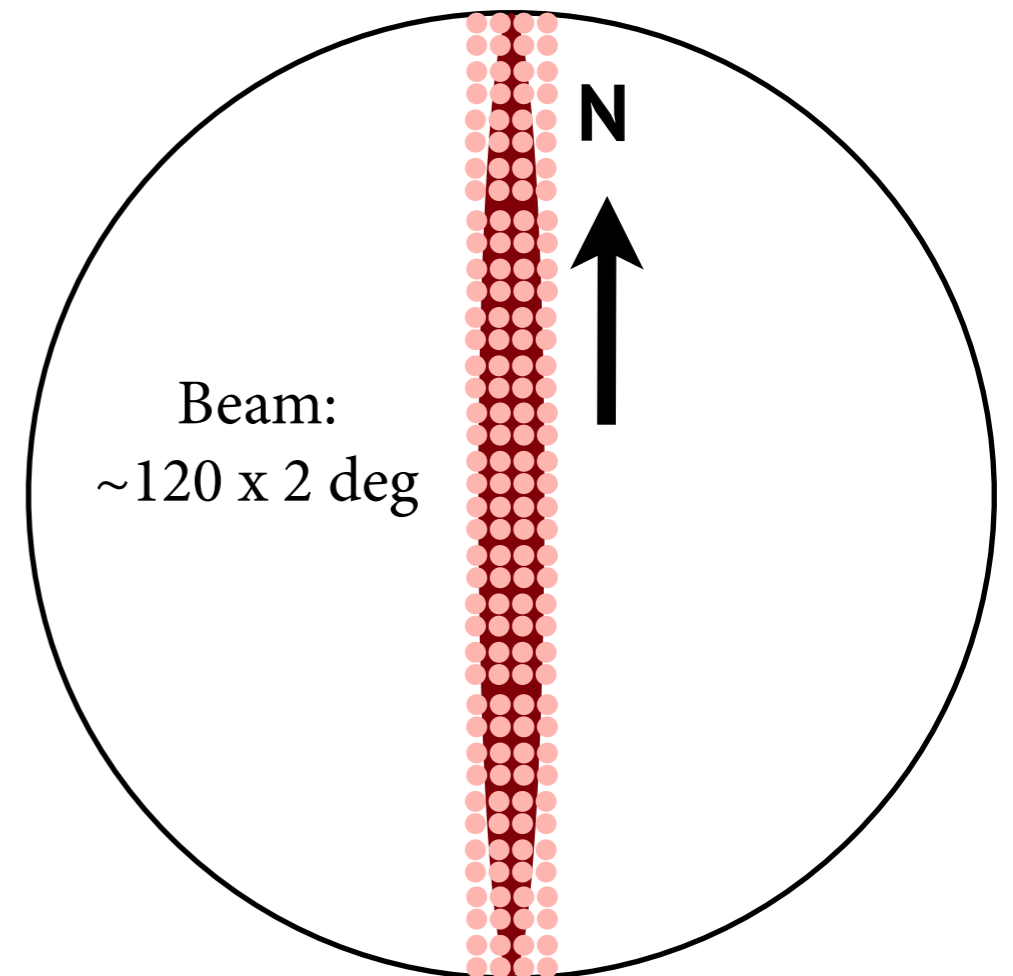
chime



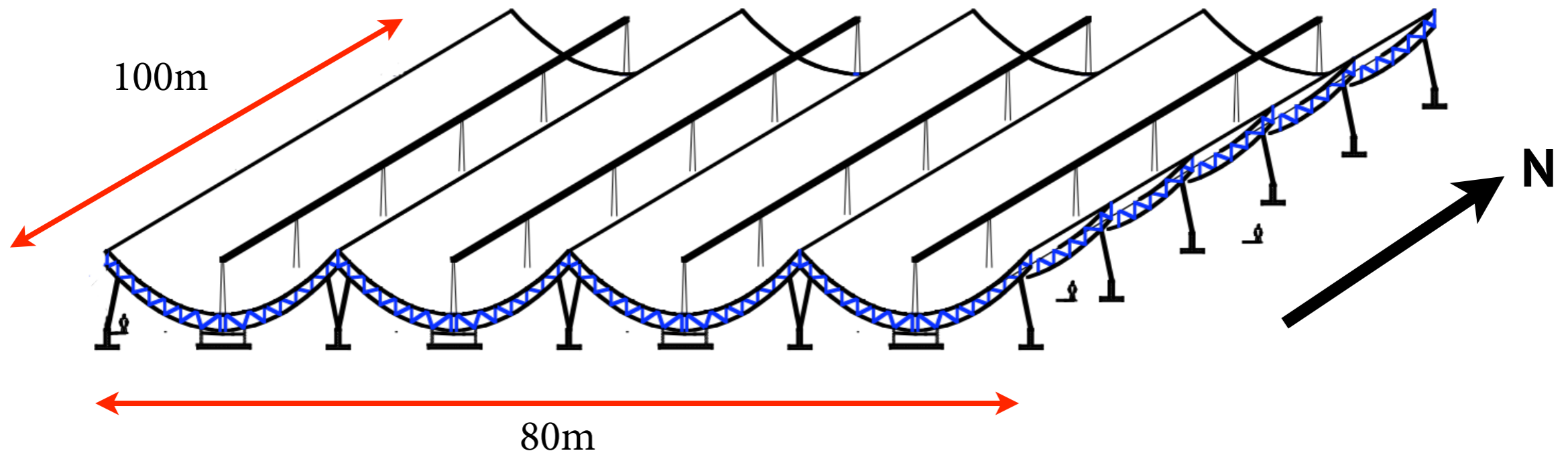
CHIME Overview



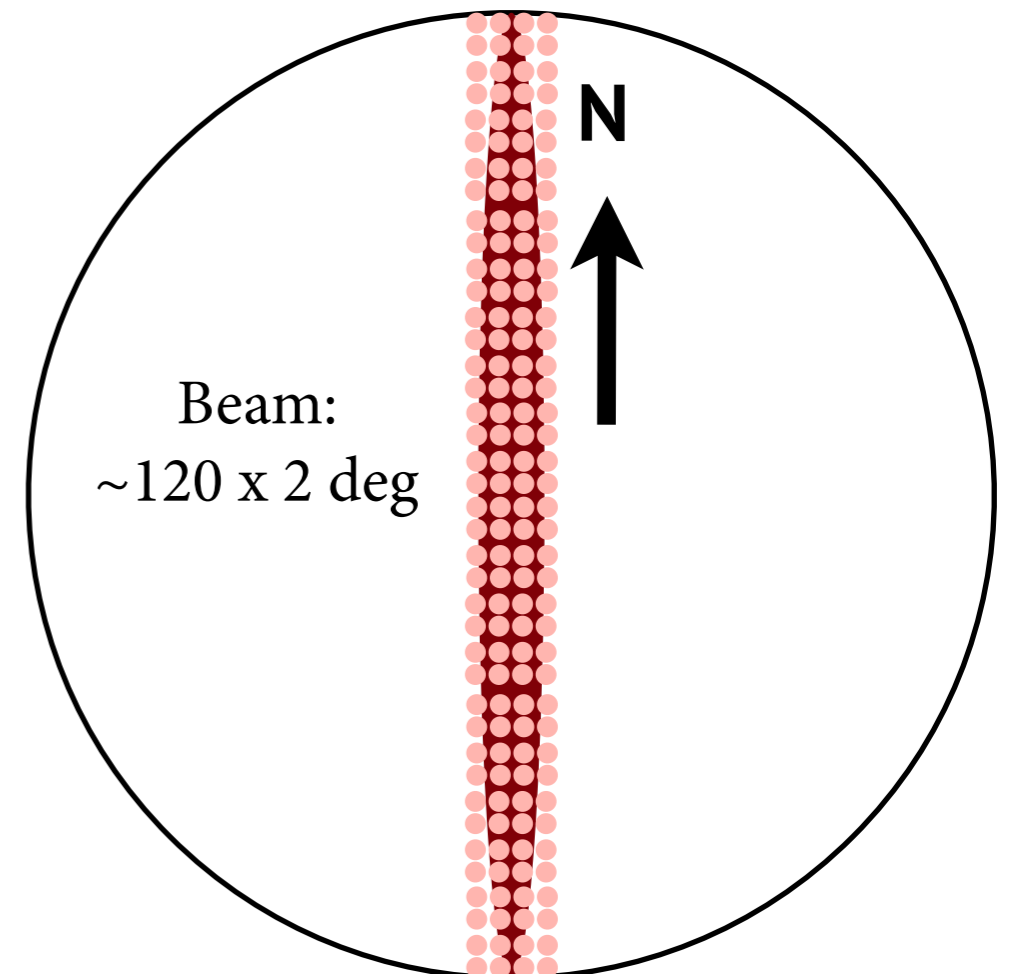
- Located at DRAO in BC
- Transit radio interferometer
 - ▶ Observe between 400-800 MHz
 - ▶ 0.4 MHz spectral resolution
 - ▶ 1024 dual pol antennas ($T_{\text{recv}} = 50\text{K}$)
- 120 x 2 degree FoV
- 4x256 beams = 15 arcmin resolution



CHIME Overview



- Science Goals
 - ▶ Intensity mapping for BAOs
 - ▶ Pulsar observations
 - ▶ Radio transients
 - ▶ Fully funded!



CANADA



CHIME

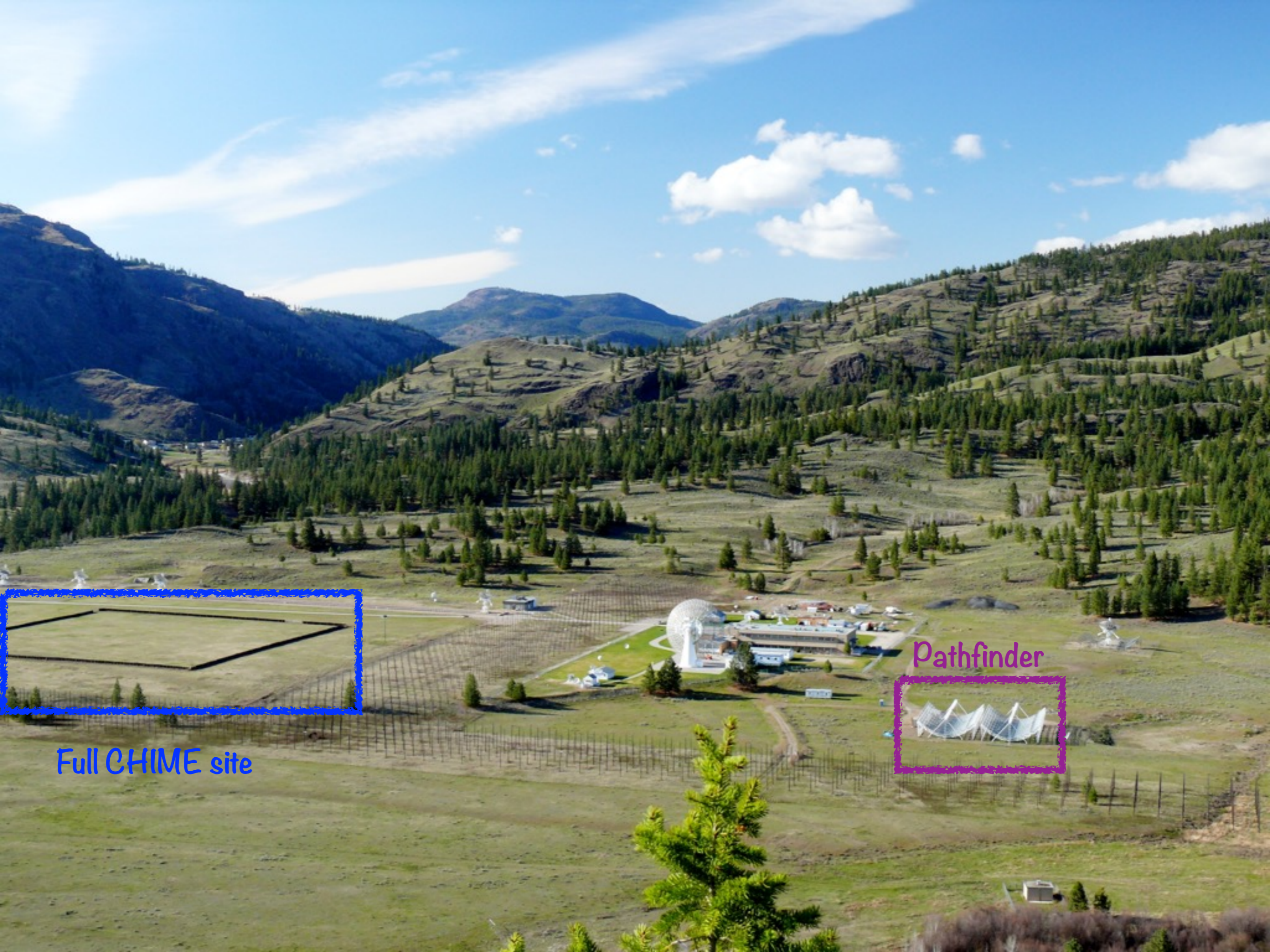




CHIME



CANADA
0 km 300 600 900 km
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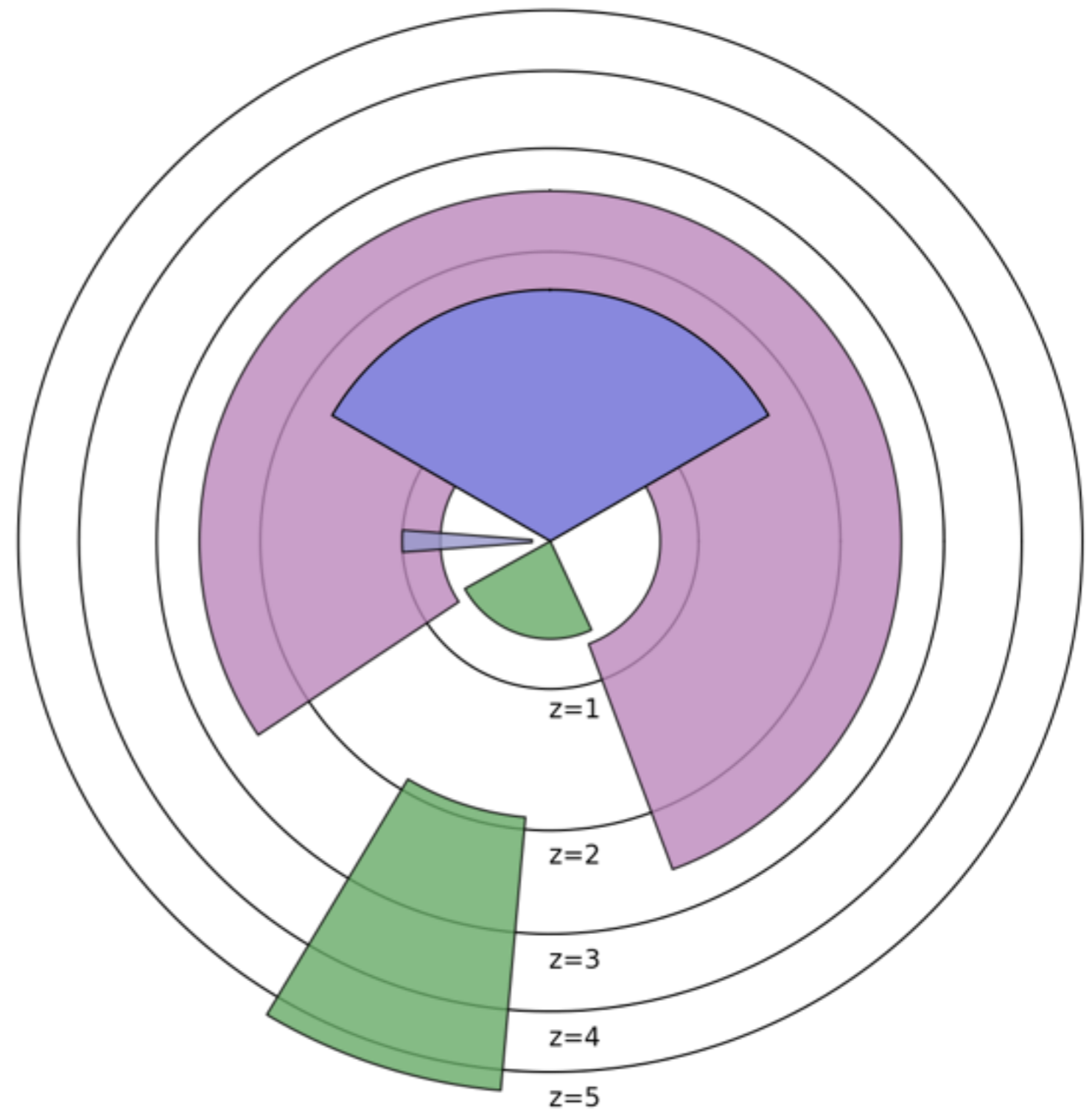
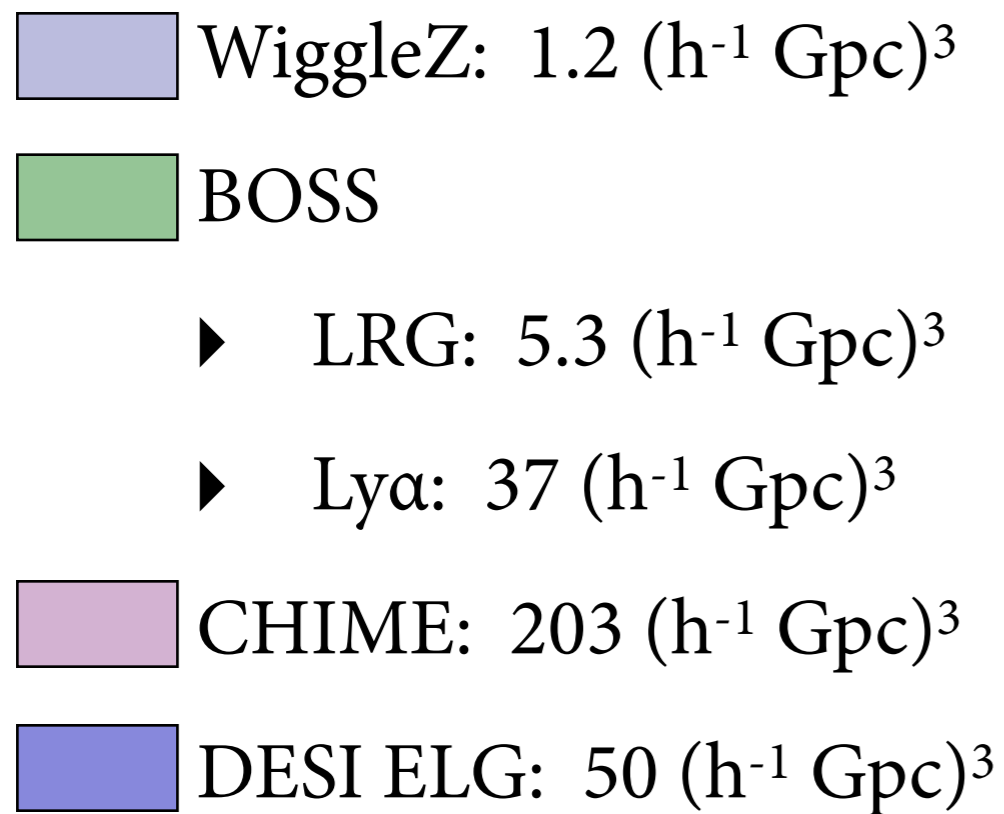


Full CHIME site



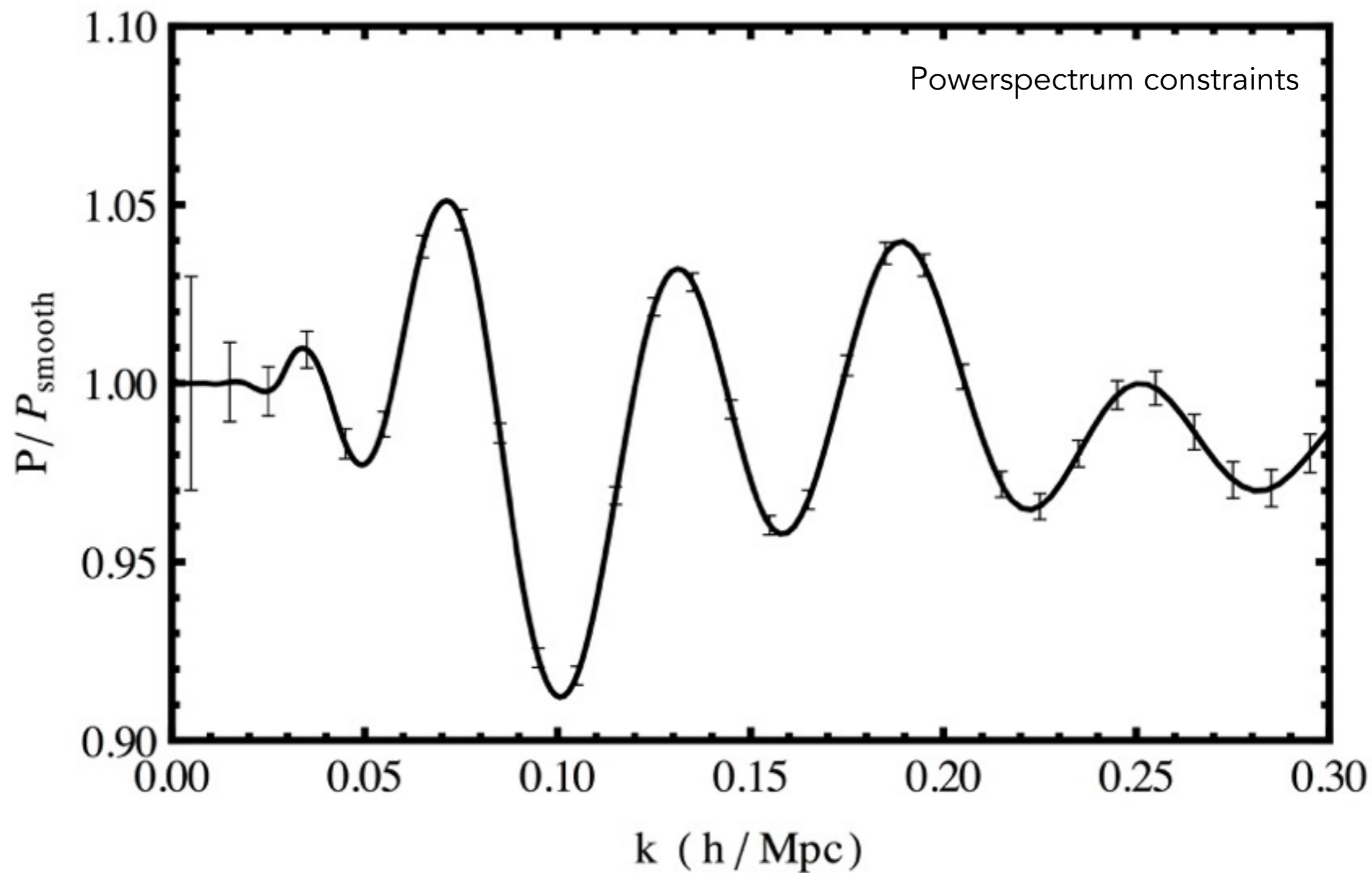
Pathfinder

Survey Volume

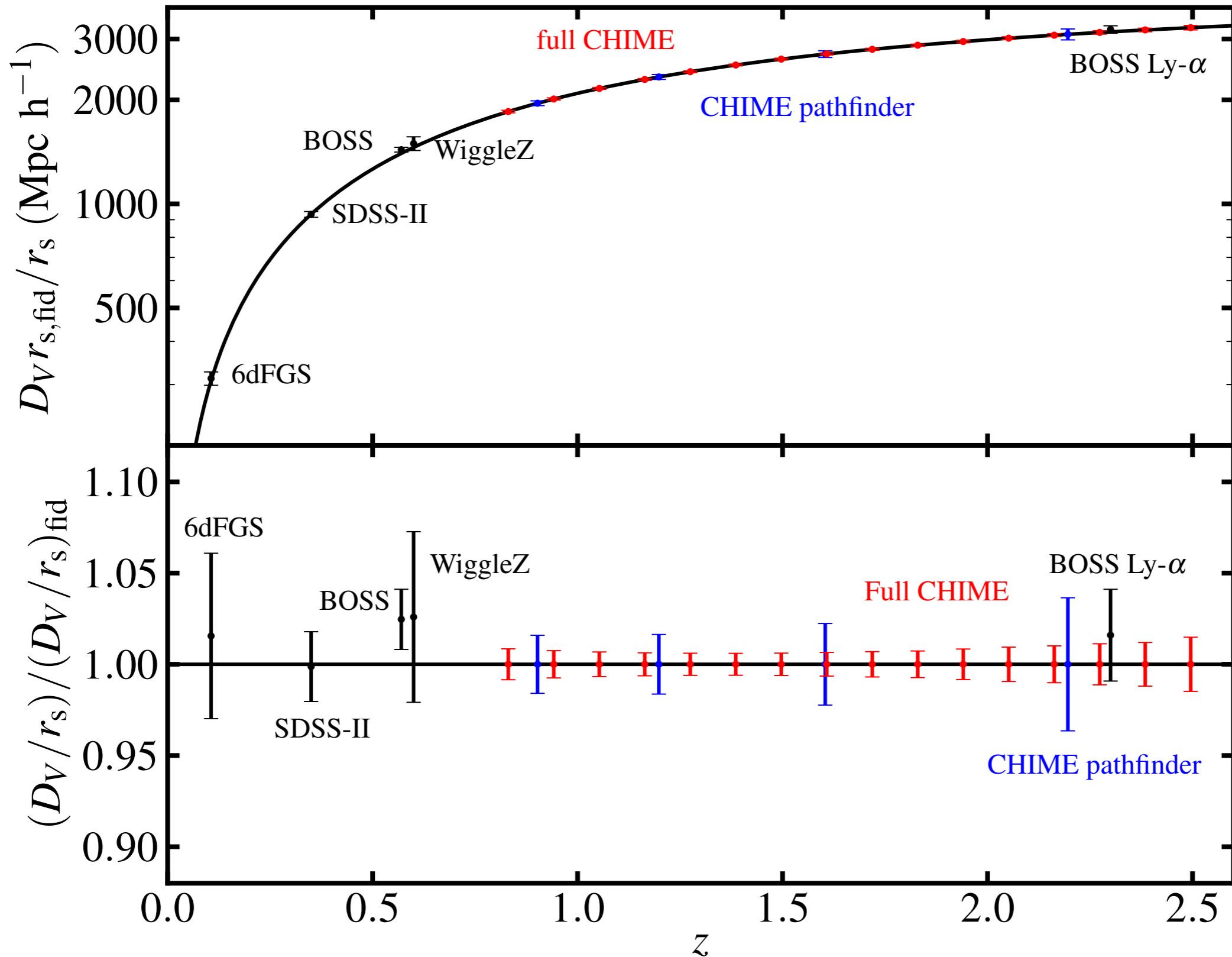


Scaled such that:
area of patch=volume of survey

BAO Forecasts



BAO Forecasts

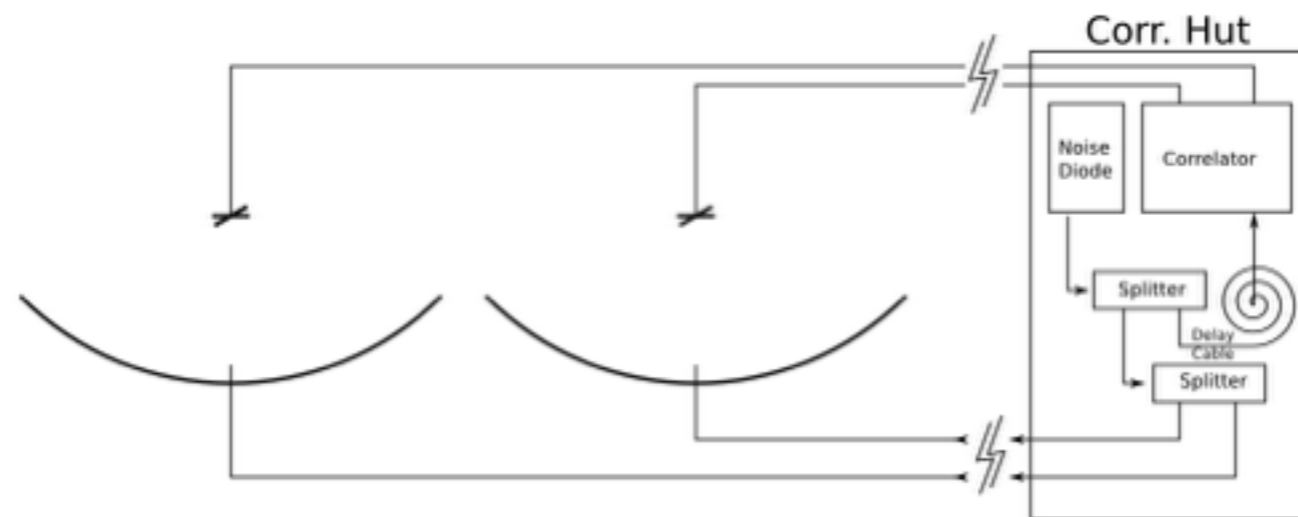


Status: Construction completed!

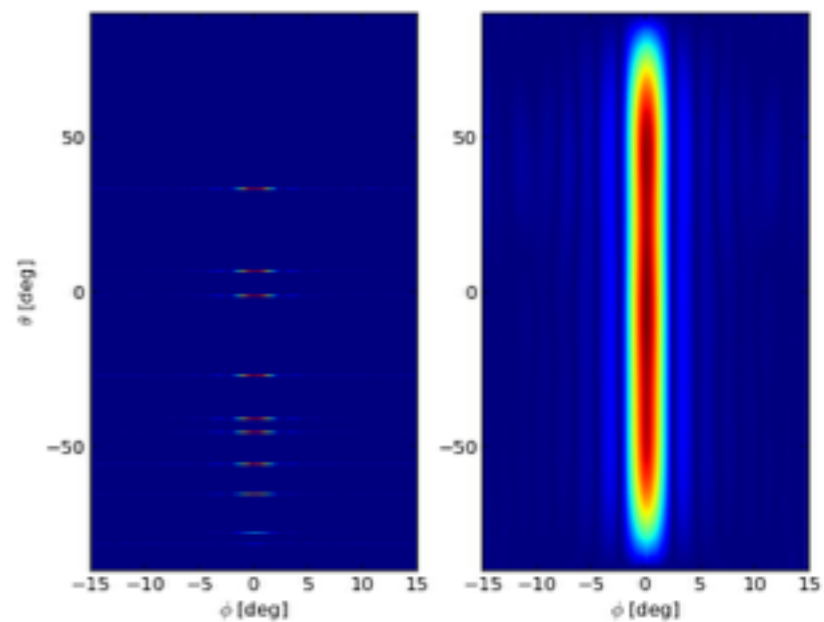
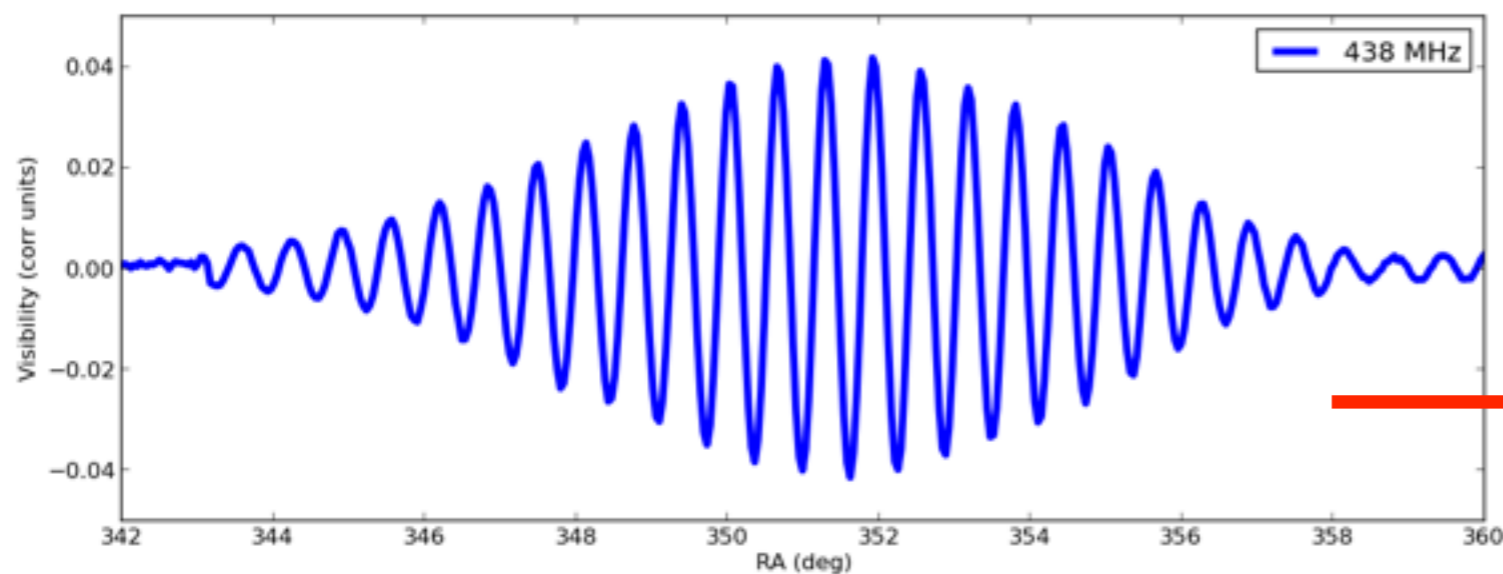


Calibration

- See more in Jon's talk tomorrow....
- Requirements set by ratio of signal to foregrounds $\sim 10^{-5}$
- Calibration of electric gains (broadband noise injection)



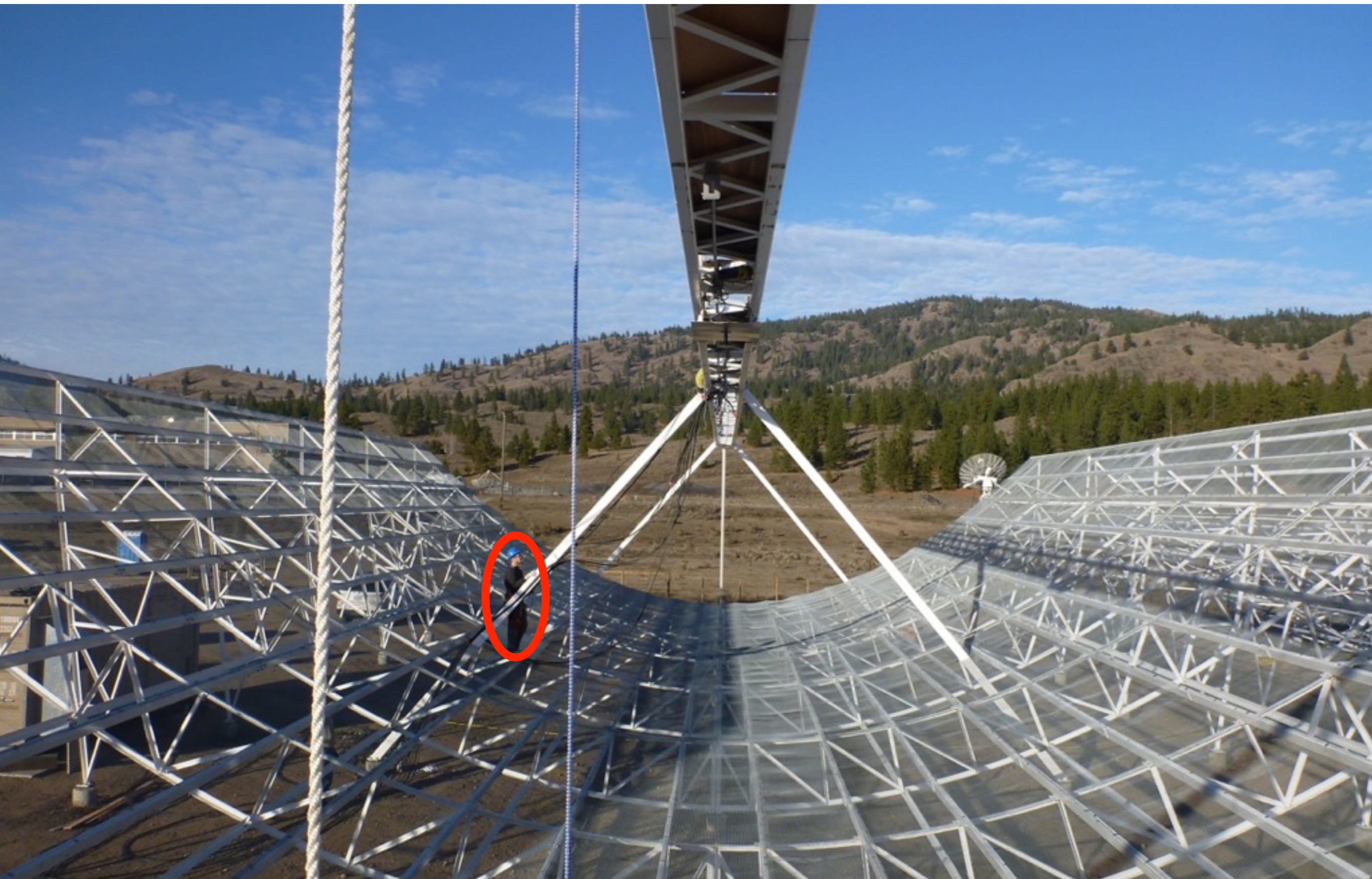
- Calibration of primary beams (pulsar holography...)



CHIME Pathfinder

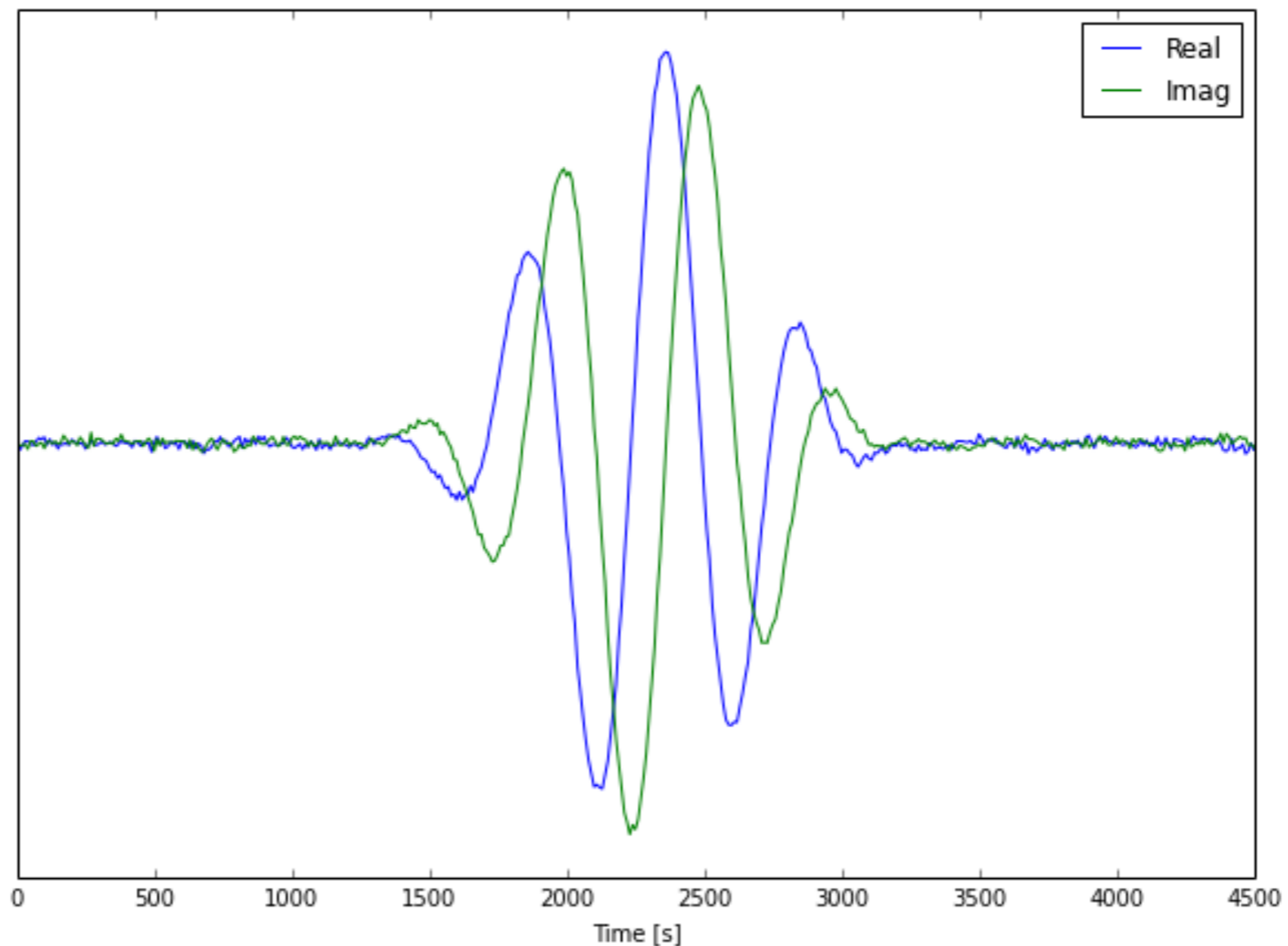
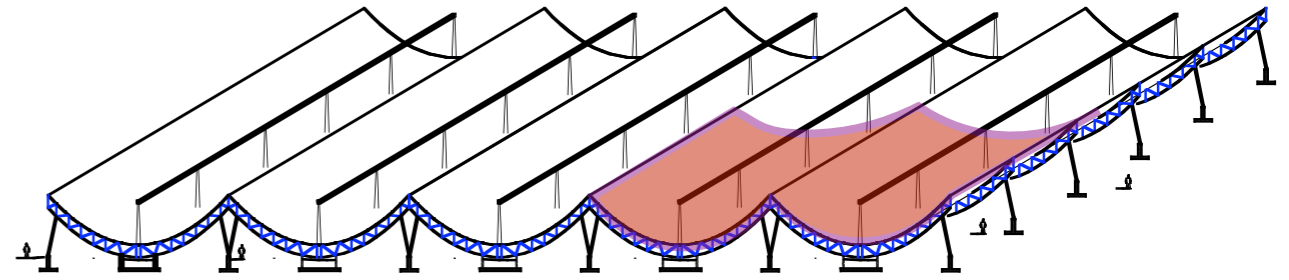


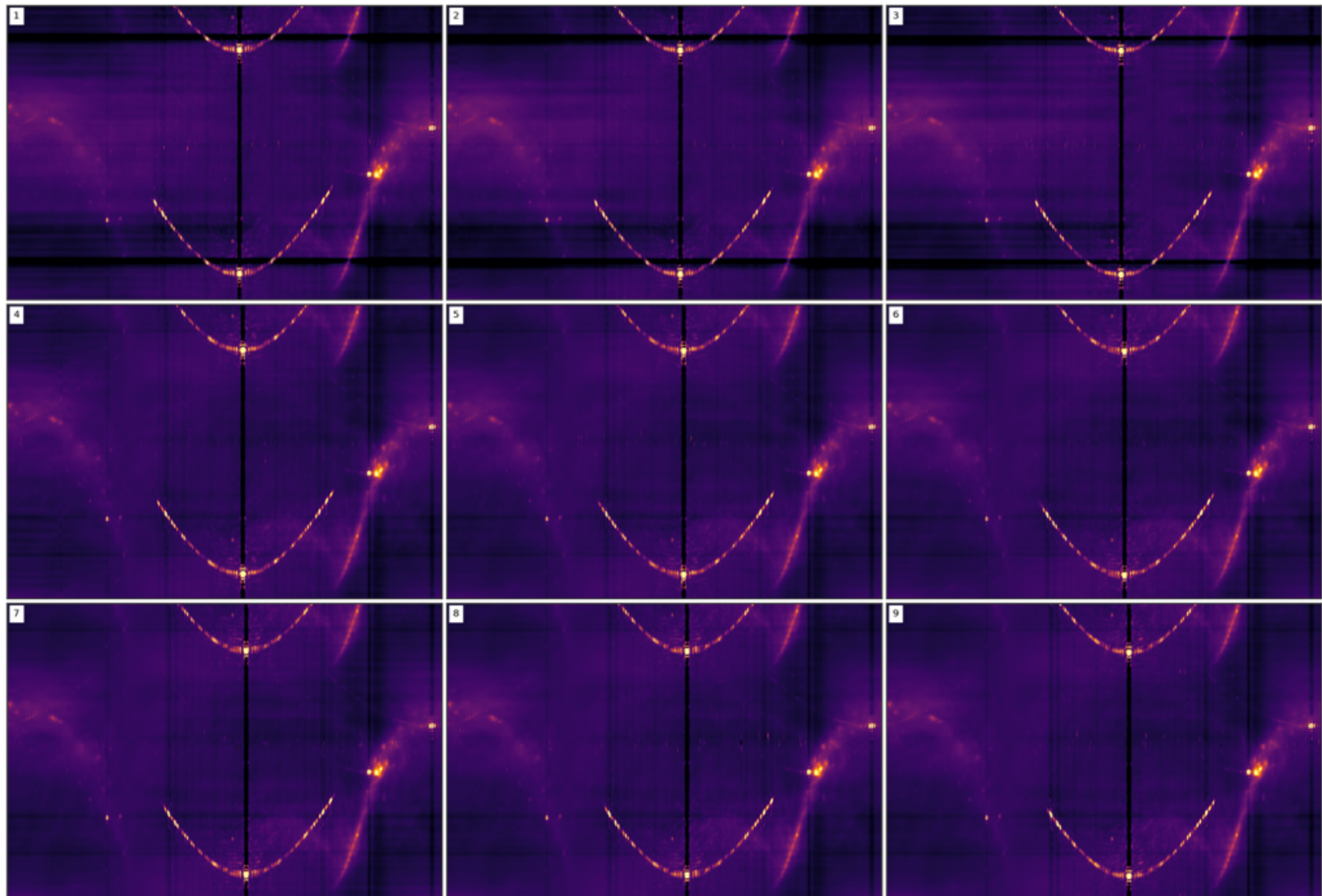
CHIME Pathfinder



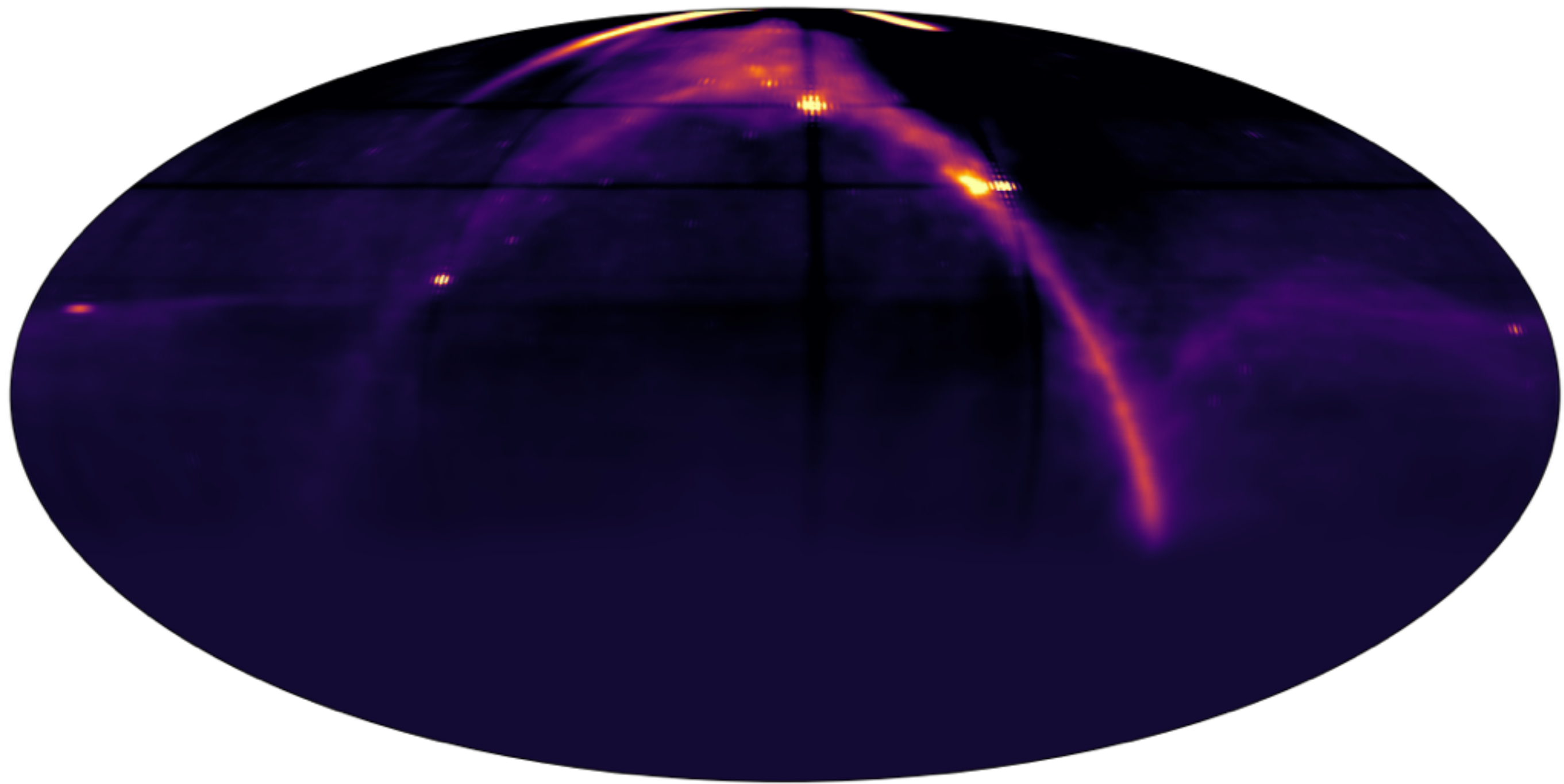
CHIME Pathfinder

- 2x20m cylinder, 40m long
- First light was late 2013
- Commissioning finished early 2015



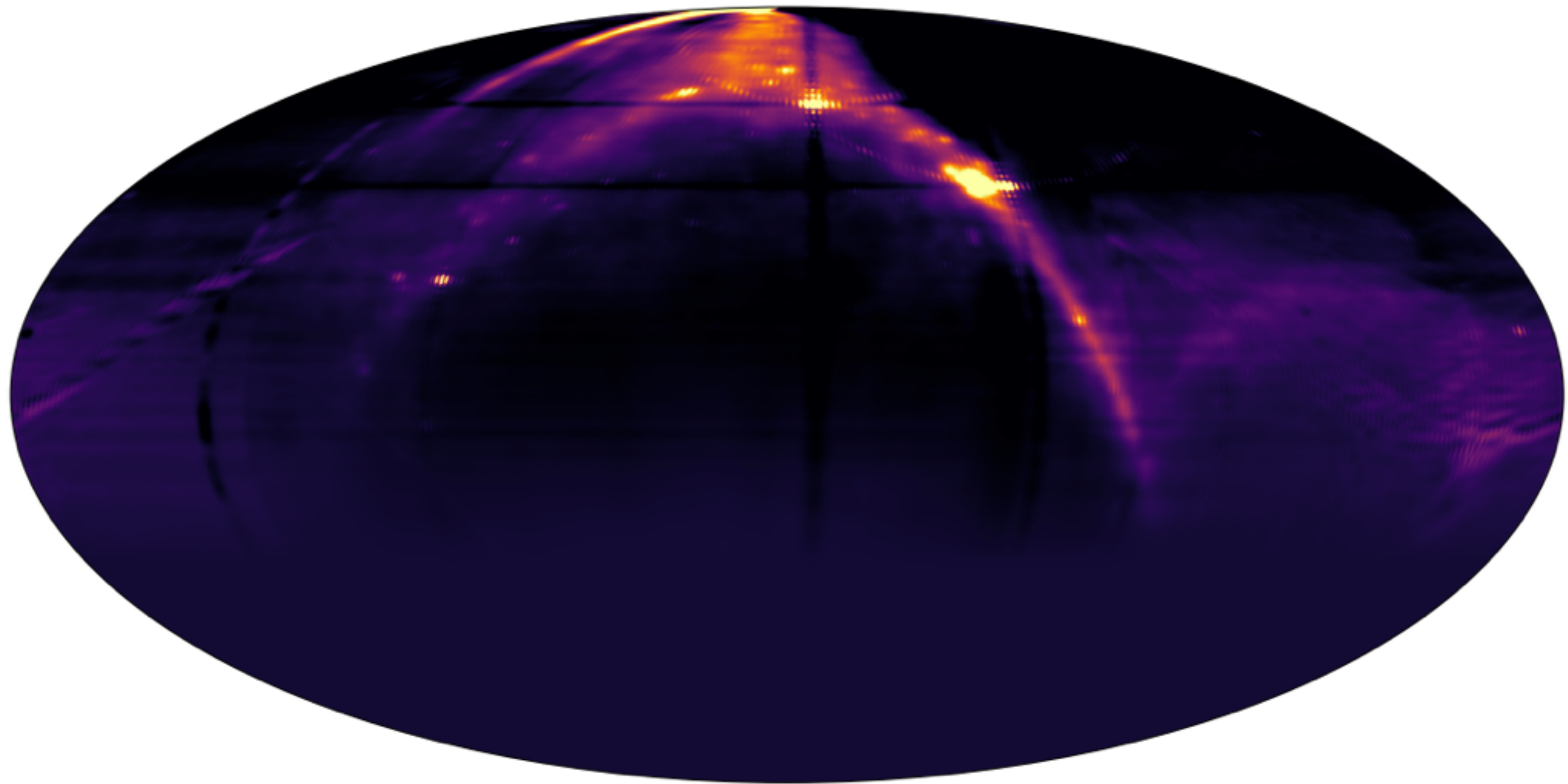


Dirty map



Simulated

Dirty map



Real

Stack of 10 days data

Data Analysis with the m-mode formalism

Interferometers

$$V_{ij}(t) = \frac{1}{\Omega_{ij}} \int d^2 \hat{\mathbf{n}} A_i(\hat{\mathbf{n}}; t) A_j^*(\hat{\mathbf{n}}; t) e^{2\pi i \hat{\mathbf{n}} \cdot \mathbf{u}_{ij}(t)} T(\hat{\mathbf{n}})$$

Write in terms of a transfer function

$$V_{ij}(t) = \int d^2 \hat{\mathbf{n}} B_{ij}(\hat{\mathbf{n}}; t) T(\hat{\mathbf{n}}) + n_{ij}(t)$$

Analysis challenges

- Data size (~ for CHIME):
 - ▶ Time samples: ~8000 / day
 - ▶ Baselines: ~3000 unique
 - ▶ Pixels: ~ 12×10^6
 - ▶ Frequencies: ~1000
- As a matrix in pixel space $\mathbf{B} \sim 10\text{M} \times 30\text{M}$ (per frequency)
- Operations (e.g. direct map making are hugely costly)
- Consider other options....

Transit Interferometers

- Timeseries is periodic on the sidereal day $t \rightarrow \phi$
 - ▶ Apply this restriction and see how the analysis goes.

$$V_{ij}(\phi) = \int d^2 \hat{\mathbf{n}} B_{ij}(\hat{\mathbf{n}}; \phi) T(\hat{\mathbf{n}}) + n_{ij}(\phi)$$

Spherical Harmonic Transform

$$V^{ij}(\phi) = \sum_{lm} B_{lm}^{ij}(\phi) a_{lm}^T + n^{ij}(\phi)$$

Fourier Transform

$$V_m^{ij} = \sum_l B_{lm}^{ij} a_{lm}^T + n_m^{ij}$$

m-mode transform

- Mapping does not mix m's (each is independent)

$$V_m^\alpha = \sum_l B_{lm}^\alpha a_{lm}^T + n_m^\alpha$$

- Write in vector form

$$\mathbf{v} = \mathbf{B} \mathbf{a} + \mathbf{n} .$$

- Simple, linear mapping from the information on the sky, to the measured degrees of freedom
- Discrete relation, with finite number of degrees, can apply all the standard statistical, signal processing techniques.
- Computationally efficient: For 1000 m's an $O(N^3)$ matrix operation becomes 10^6 times faster

Interferometric Imaging

- Traditional imaging is based around the 2D Fourier Transform approximation to the interferometry equation (only valid on small patches instantaneously)
- Use a series of steps to relax this approximation and increase field of view (w-projection, mosaicking, A-projection)
 - ▶ eg. w-term. From non coplanarity of array and sky. Solve by iteratively deconvolving the effects

$$V = \int dx dy A^2(x, y) e^{2\pi i (ux + vy + w \sqrt{1-x^2-y^2})} I(x, y)$$

m-mode Imaging

- For our restricted domain (transit telescopes), we can solve the problem exactly.

- Measurement is linear mapping:

$$\mathbf{v} = \mathbf{B} \mathbf{a} + \mathbf{n} .$$

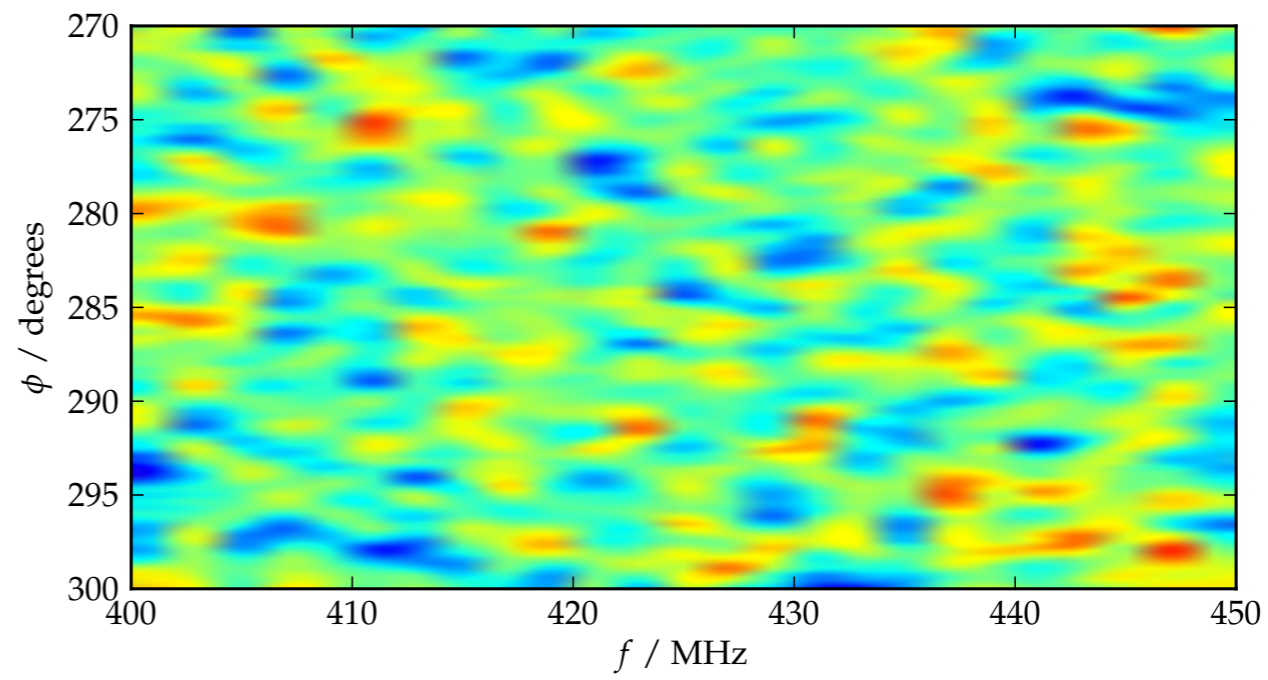
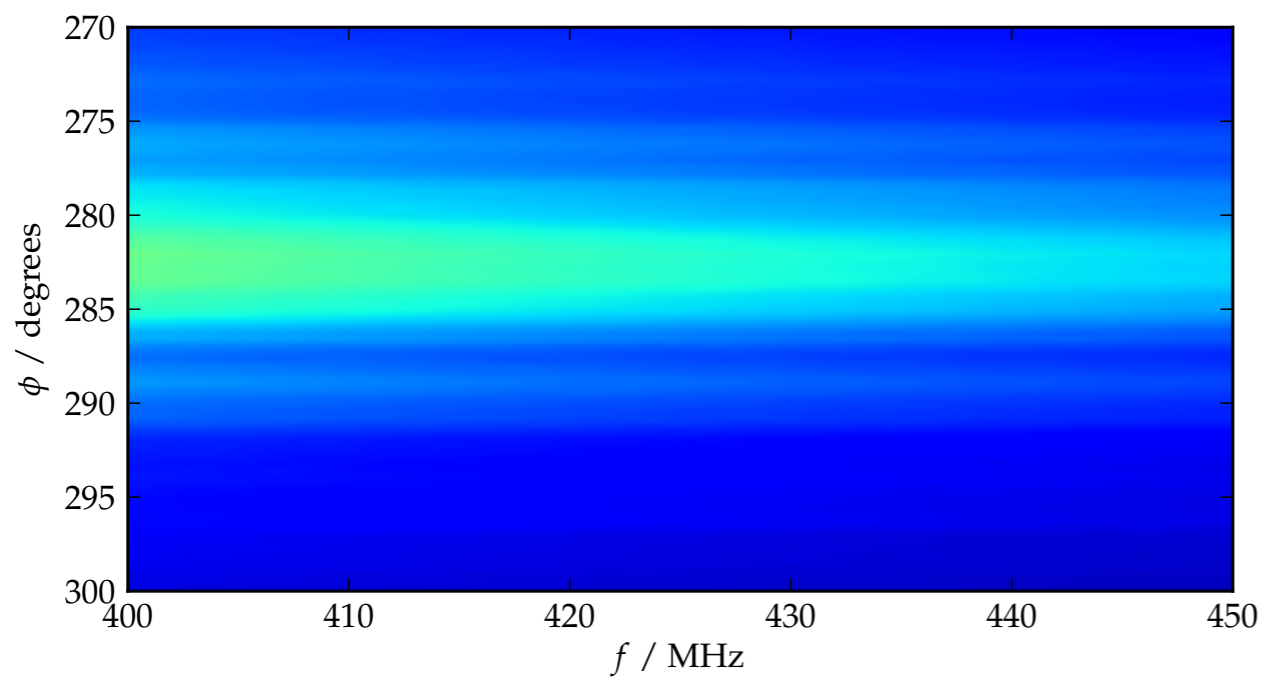
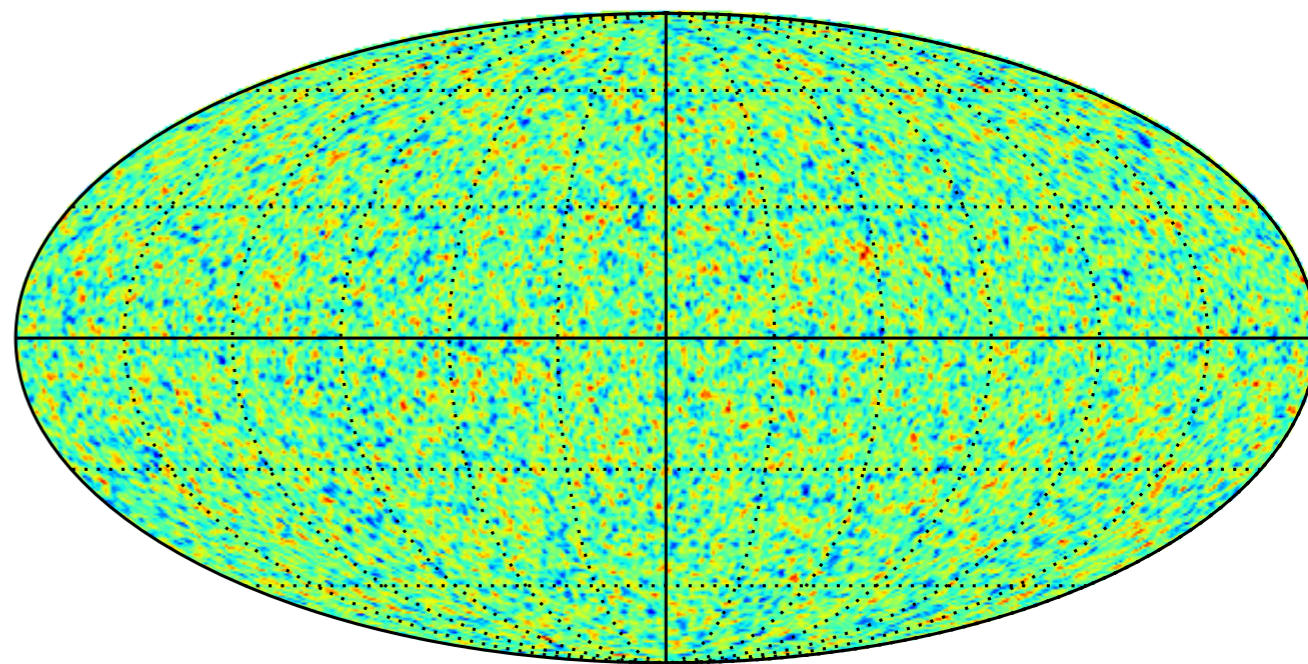
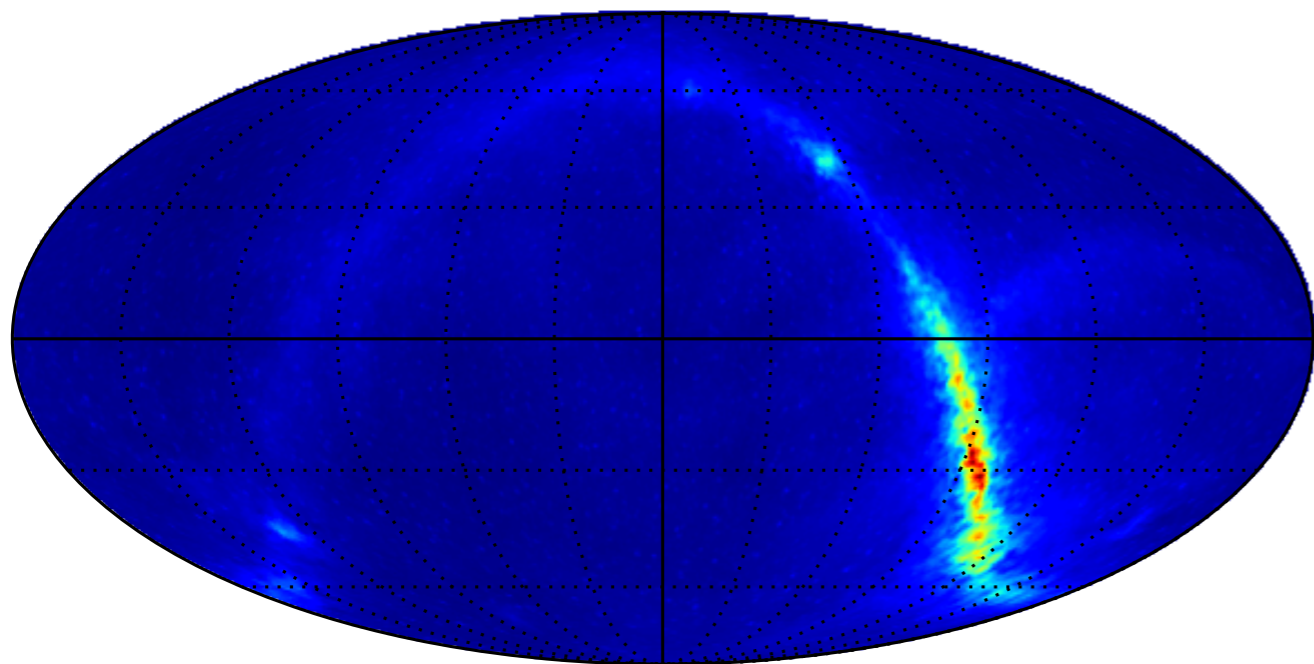
- How do we make an image of the sky? Use standard tools of signal processing:

- ▶ Pseudo-inverse to solve and regularize (*Maximum likelihood*)

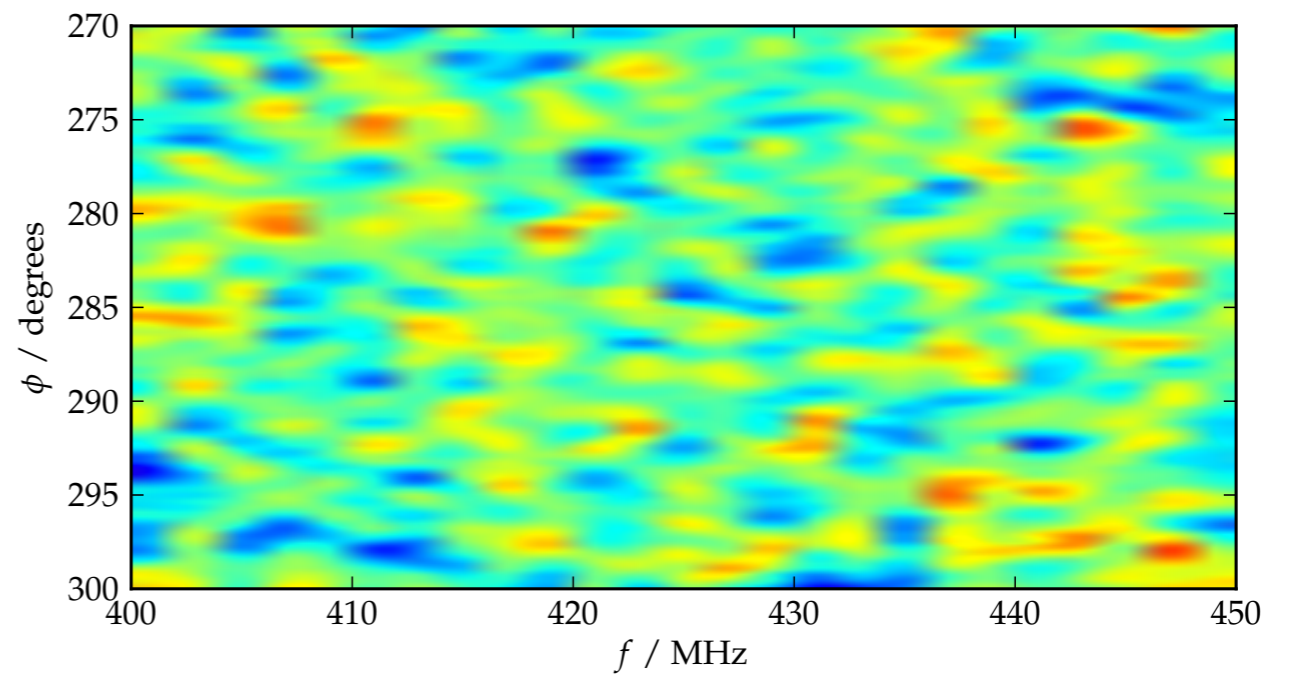
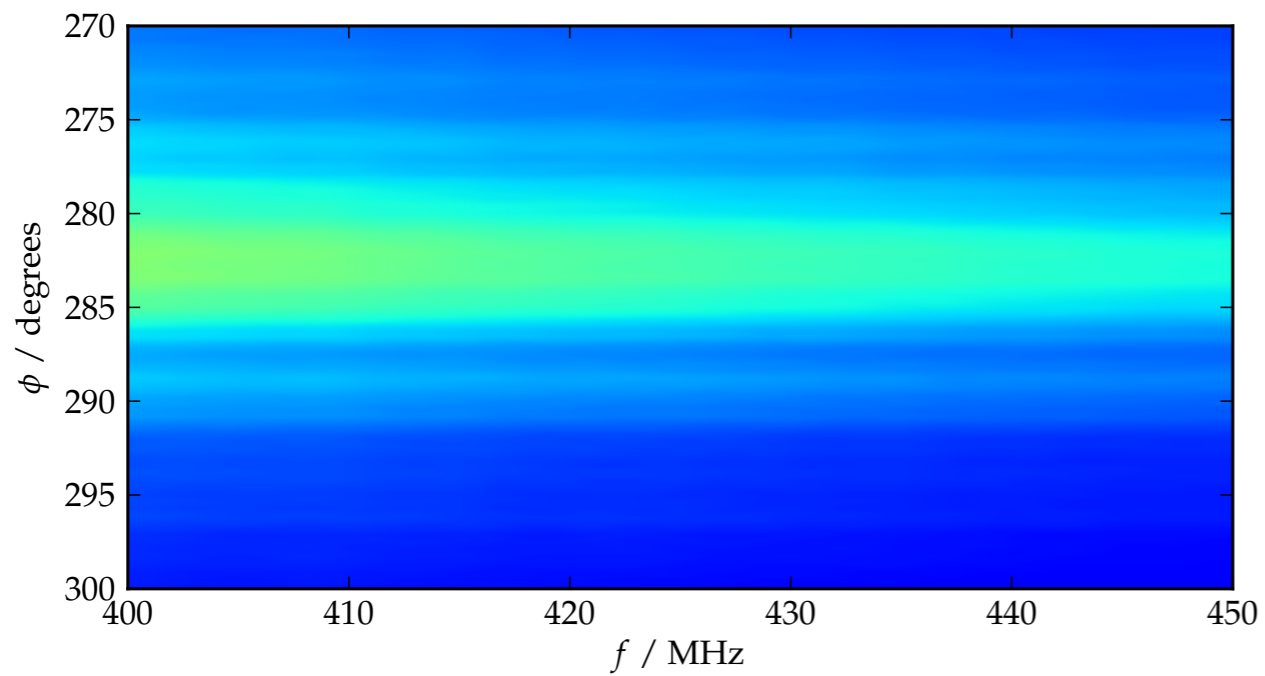
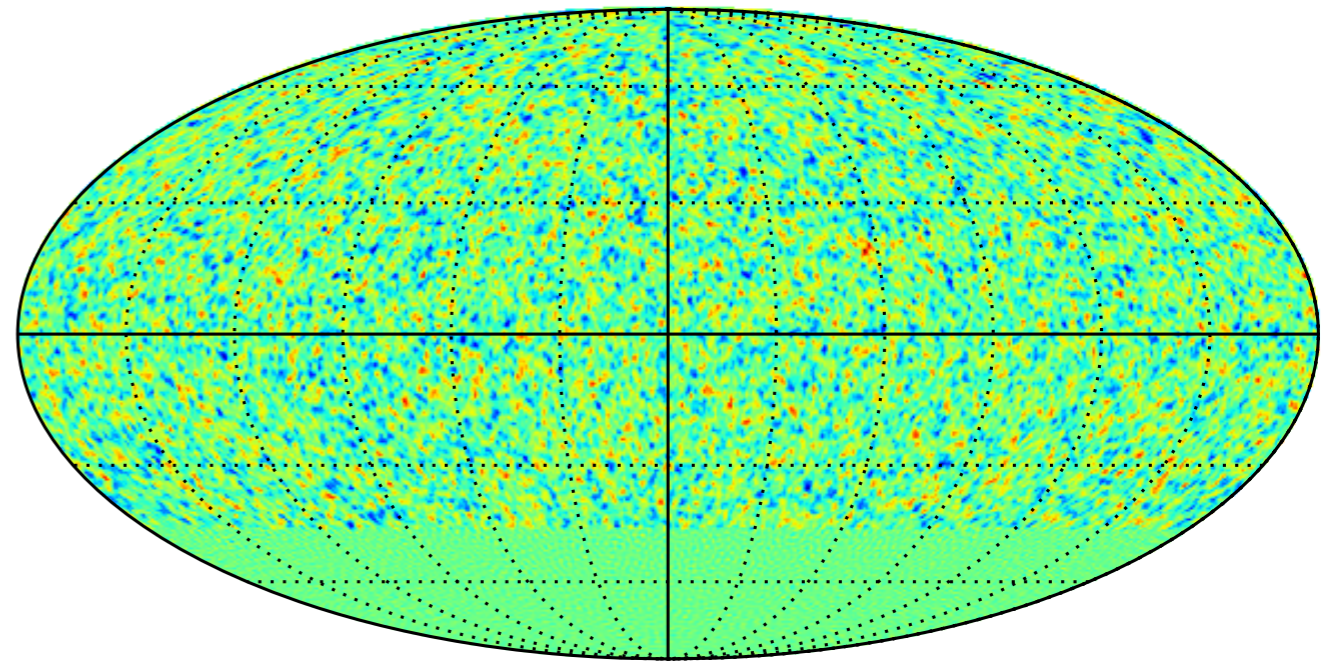
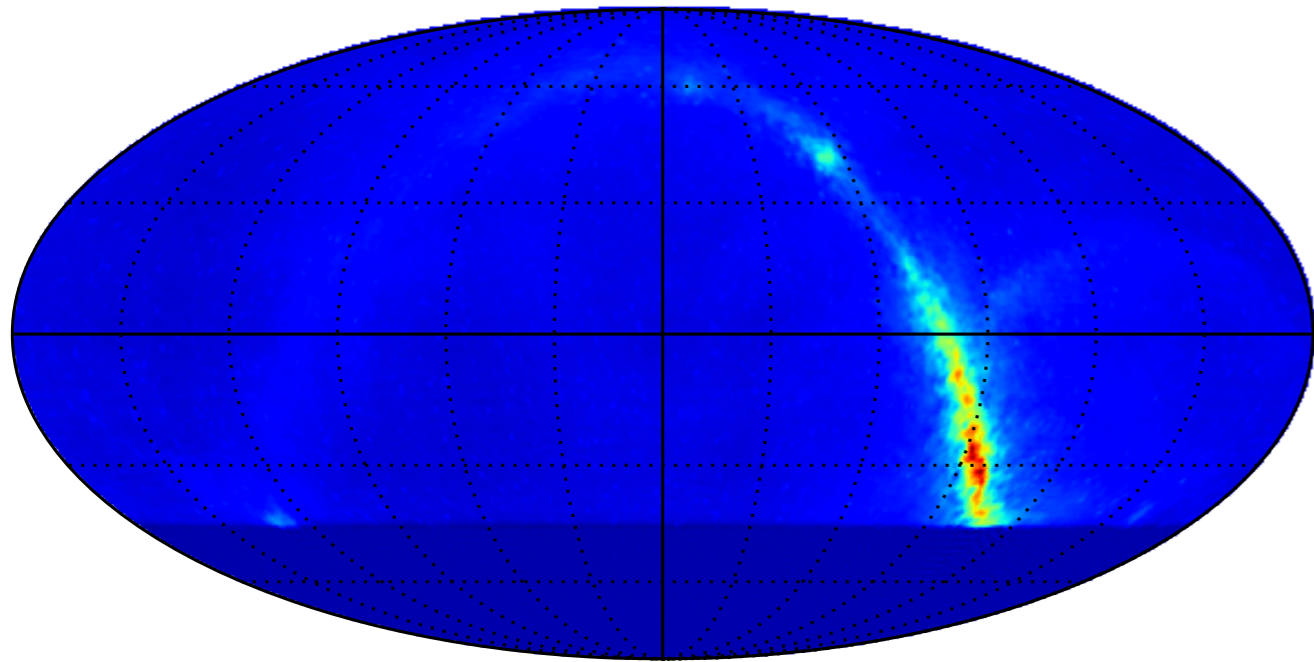
- ▶ Wiener Filter (*Bayesian expectation*)

- Conceptually straightforward. Deals naturally with all full sky effects, polarisation etc.

Simulated sky



Observed sky (from time stream) $\hat{\mathbf{a}} = \left(\mathbf{N}^{-\frac{1}{2}} \mathbf{B} \right)^+ \mathbf{N}^{-\frac{1}{2}} \mathbf{v}$

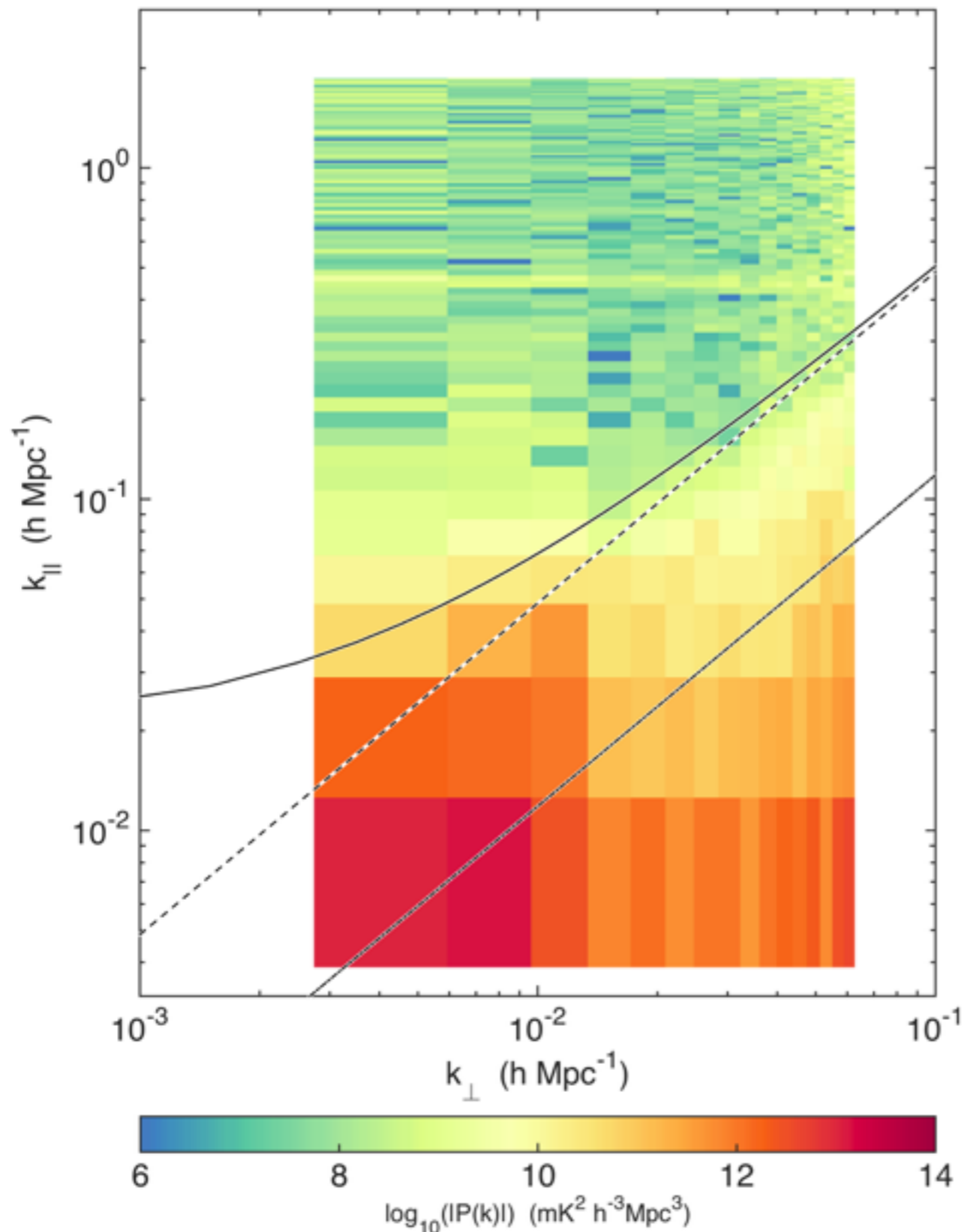


2x15m wide cylinders, 60 feeds, 0.25m spacing 400-600 MHz

Foreground Removal

- Spectral smoothness allows separation of 21cm
 - ▶ Measure components and model (Liu, Dillon etc.)
 - ▶ Power spectrum removal (Foreground wedge)
 - ▶ Delay-space filtering (Parsons et al. 2012)
- Most methods have difficulties:
 - ▶ *Mode mixing* of angular and frequency fluctuations by frequency-dependent beams (esp. interferometers)
 - ▶ *Robustness* Biasing introduced if foreground model poorly understood (esp. non-gaussianities)
 - ▶ *Statistical Optimality* Need to keep track of transformations on statistics, for optimal PS estimation
 - ▶ *Polarisation leakage* mixes fluctuations from polarised foreground

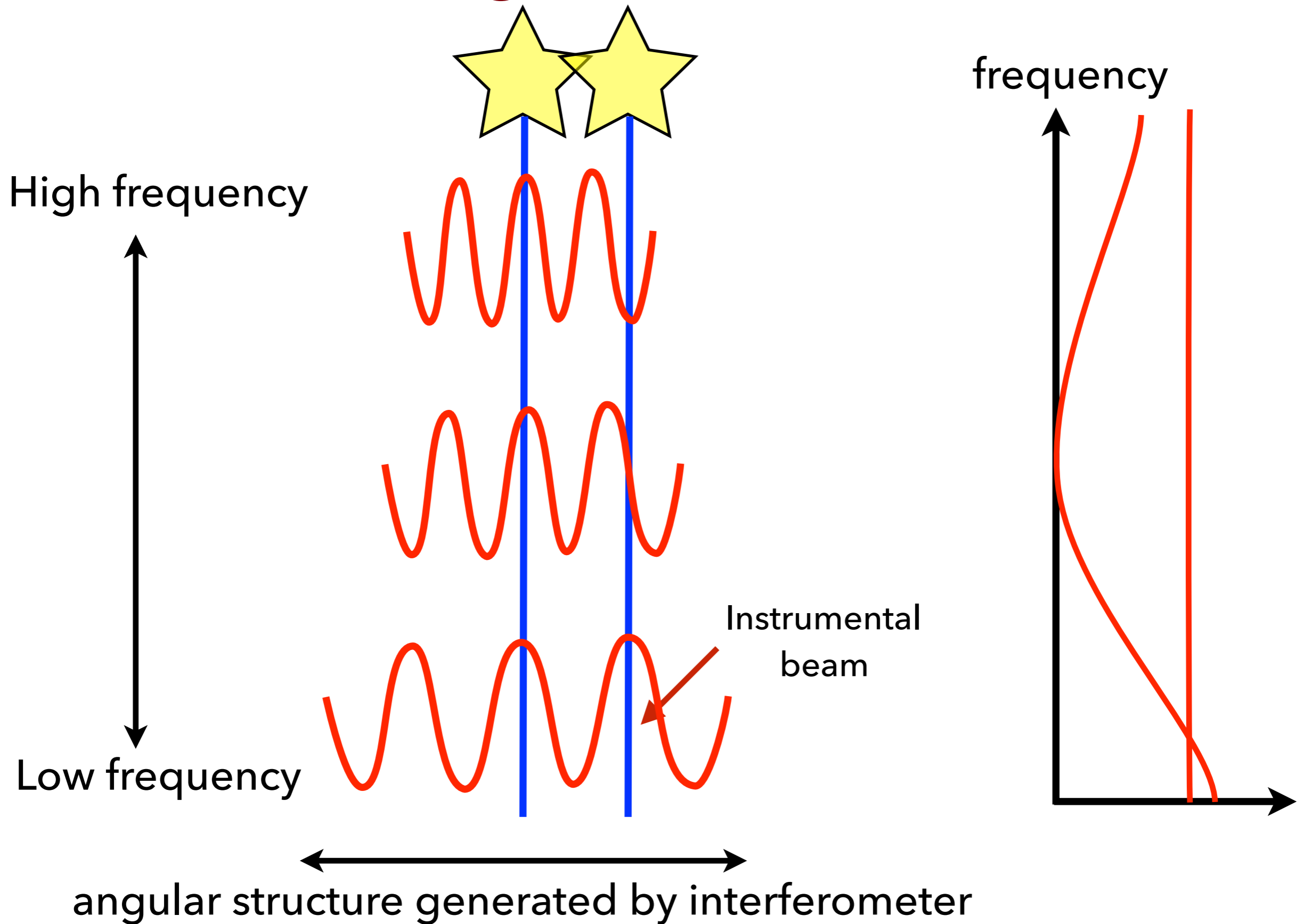
Foreground Wedge



Dillon et al. 2015 (MWA)

- Wedge is caused by mode mixing
- Argument for a smooth primary beam is that foreground power is limited in k_{par} , for a fixed baseline
- Optimistic:
 - ▶ Actual primary beam may not be smooth
 - ▶ Polarisation leakage
- Pessimistic too!
 - ▶ If we know about the beam we can remove it....

Mode mixing



Karhunen-Loeve Transform

- Old CMB idea - E/B mode separation (Bunn et al. 2003)
- An 'optimal' treatment - m-modes makes it feasible.
- Construct the covariances of the signal and foregrounds in the measured basis

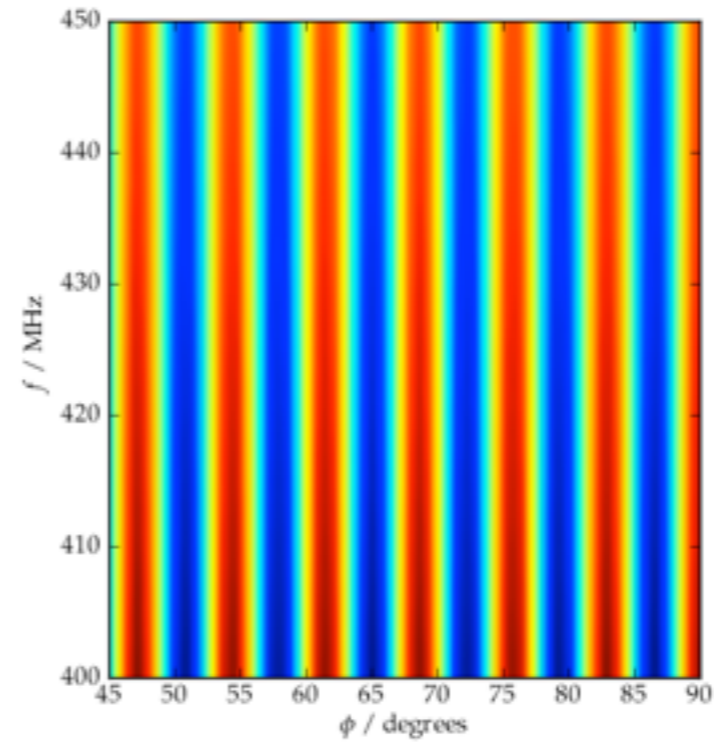
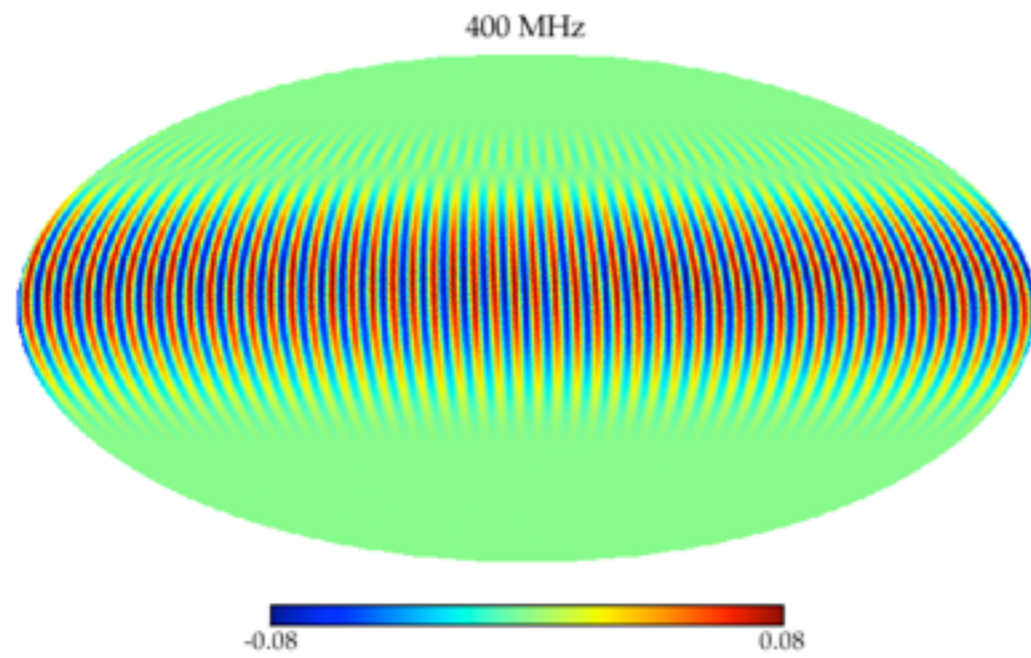
$$\mathbf{S} = \langle \mathbf{s} \mathbf{s}^\dagger \rangle = \mathbf{B} \langle \mathbf{a}_s^* \mathbf{a}_s^T \rangle \mathbf{B}^\dagger \quad \mathbf{F} = \mathbf{B} \langle \mathbf{a}_f \mathbf{a}_f^\dagger \rangle \mathbf{B}^\dagger$$

- Jointly diagonalise both (eigenvalue problem)

$$\mathbf{S} \mathbf{x} = \lambda \mathbf{F} \mathbf{x}$$

- Gives a new, uncorrelated basis. Corresponding eigenvalue gives the expected signal to foreground power ratio.

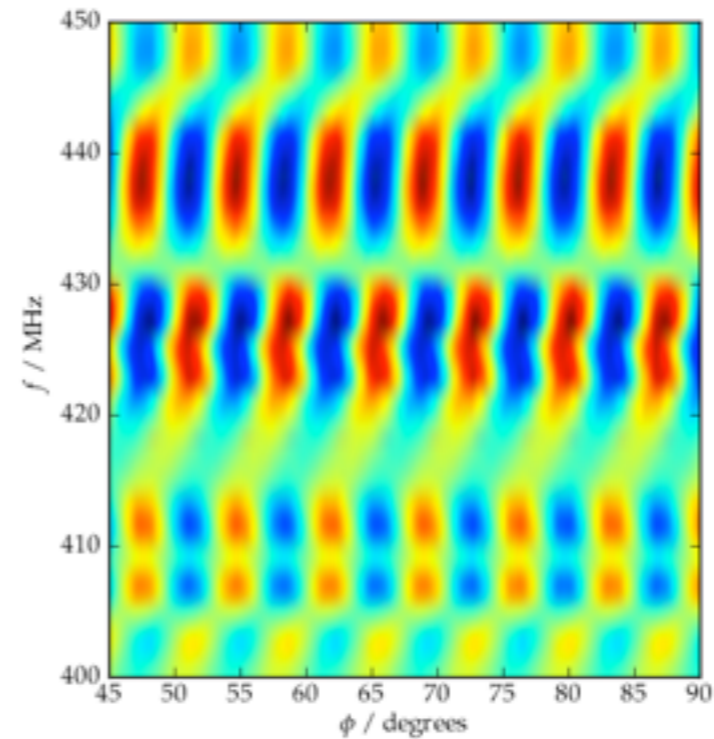
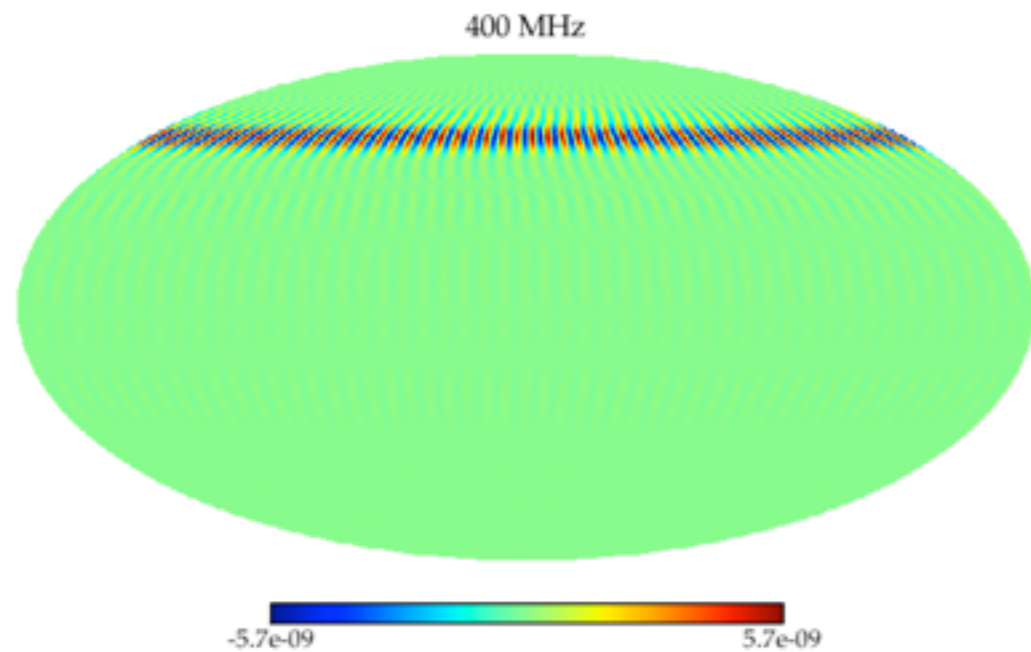
Most foreground



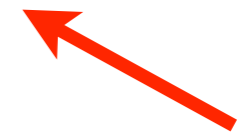
smooth
in freq



Most signal



oscillates
in freq

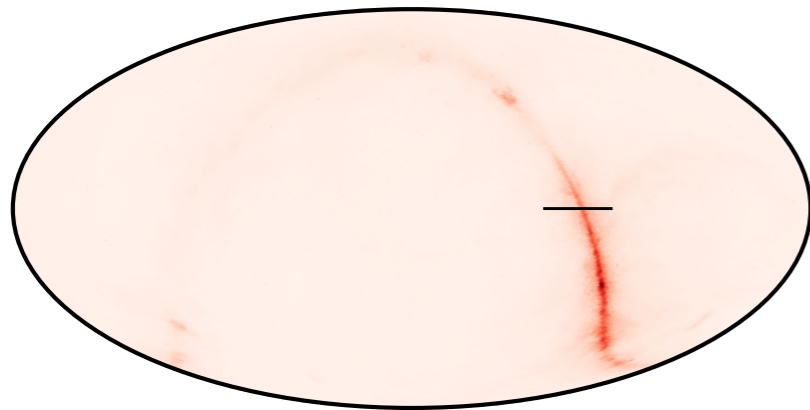


Foreground Removal with KLT

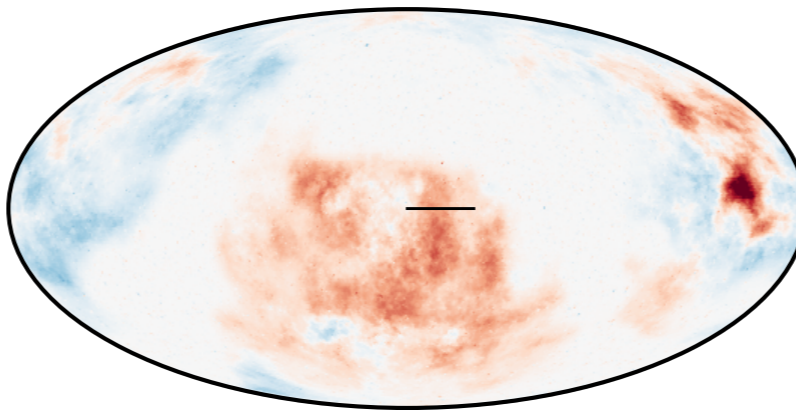
- Foreground removal is performed by projecting out modes with low signal-to-foreground ratio.
- Robustness to model uncertainties by choosing a conservatively large threshold; we would prefer to increase our errors bars in order to remove bias.
- Addresses the previous problems
 - ▶ Analysis uses all measured data to avoid mode mixing.
 - ▶ Can be made arbitrarily robust - increase threshold for removal
 - ▶ Linear transformation in the data space, keeps track of statistics

Foreground Cleaning

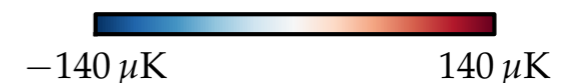
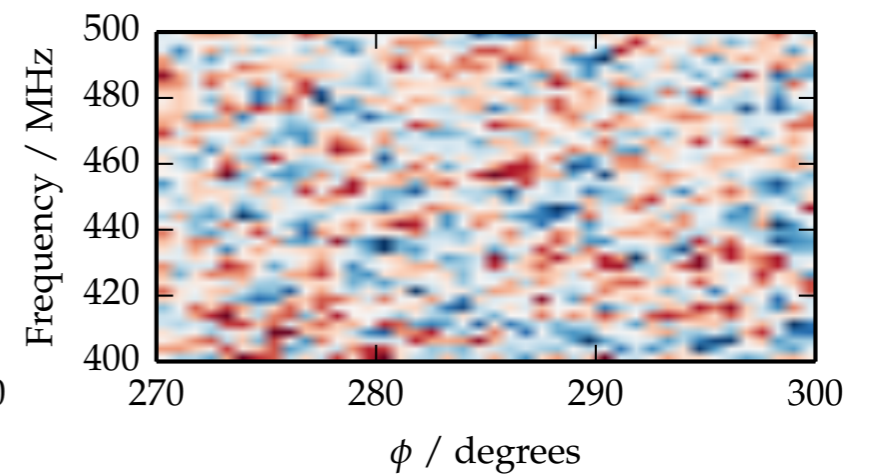
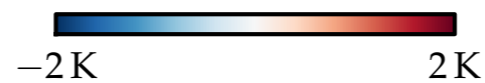
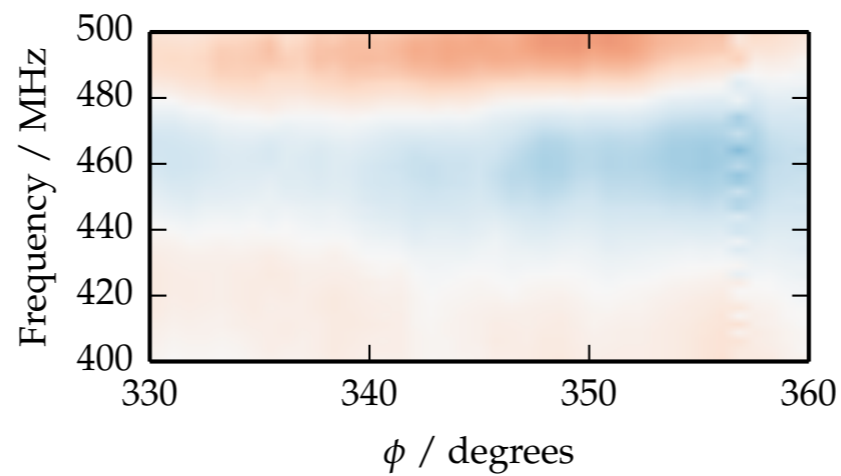
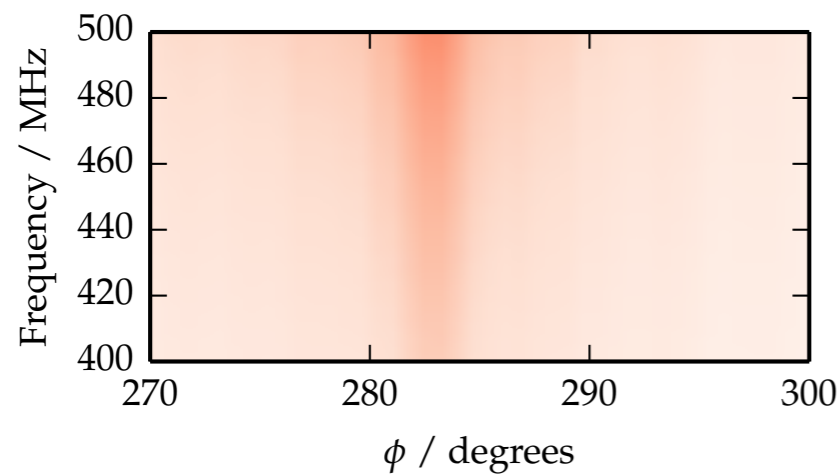
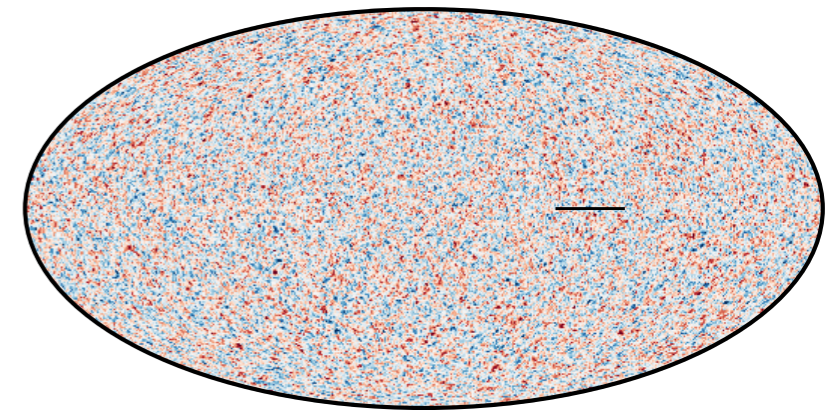
Unpolarised Foreground



Polarised Foreground (Q)



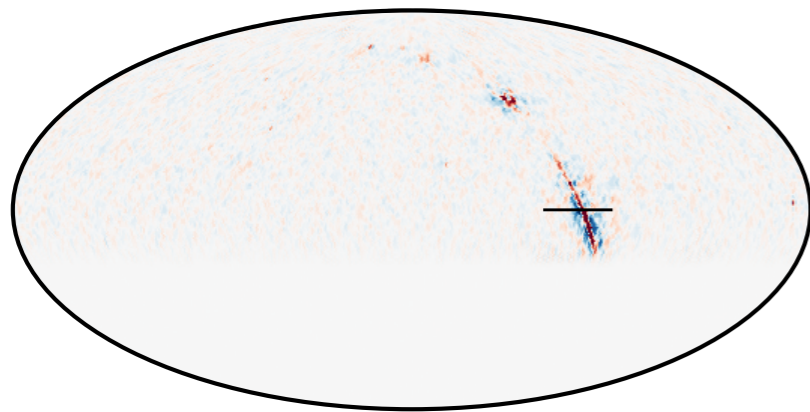
21cm Signal



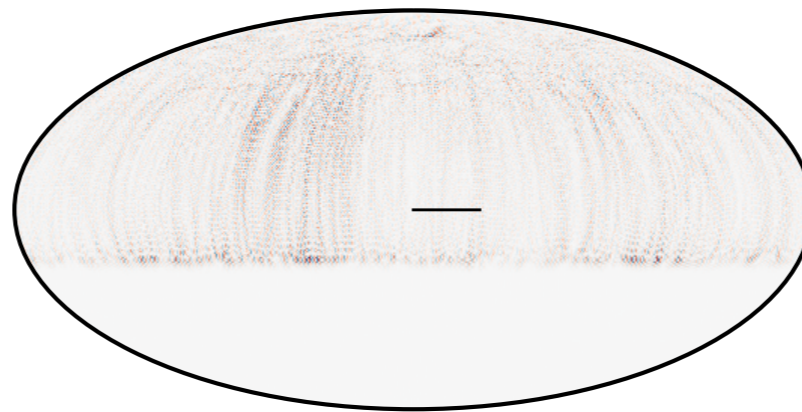
Foregrounds 10^6 times larger than signal

Foreground Cleaning

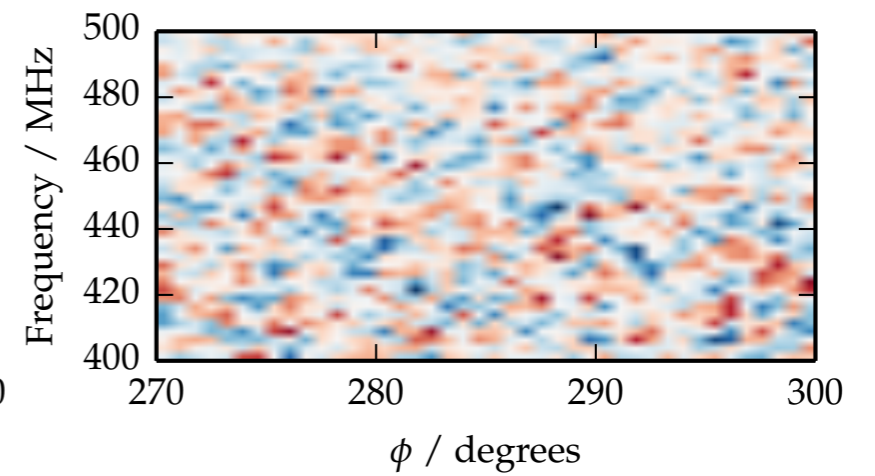
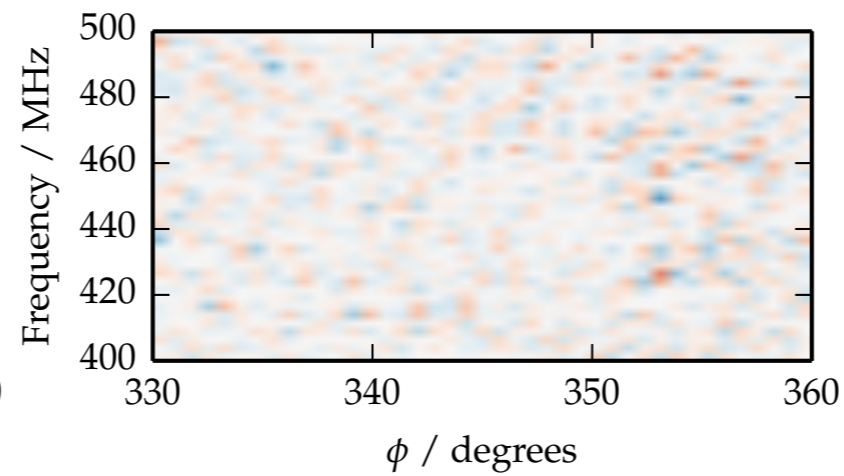
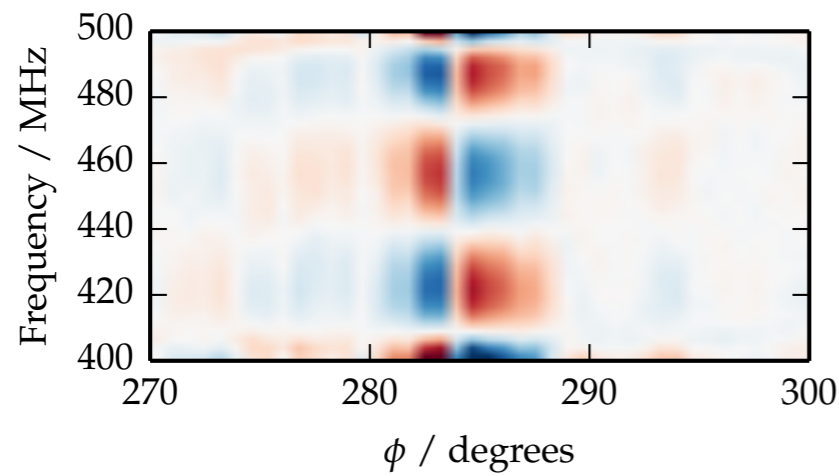
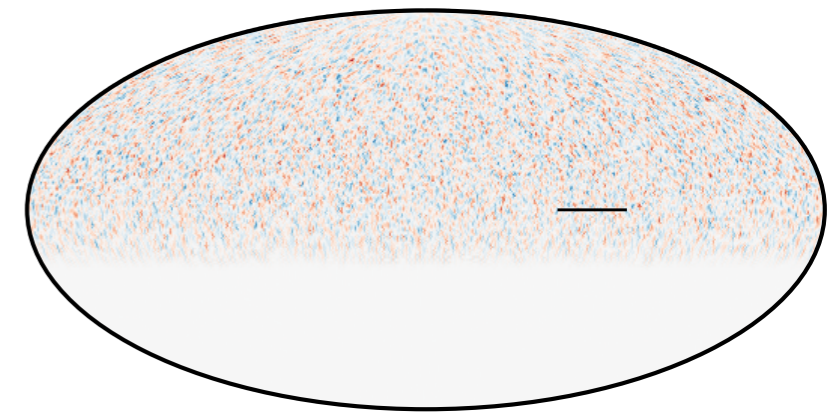
Unpolarised Foreground



Polarised Foreground (Q)

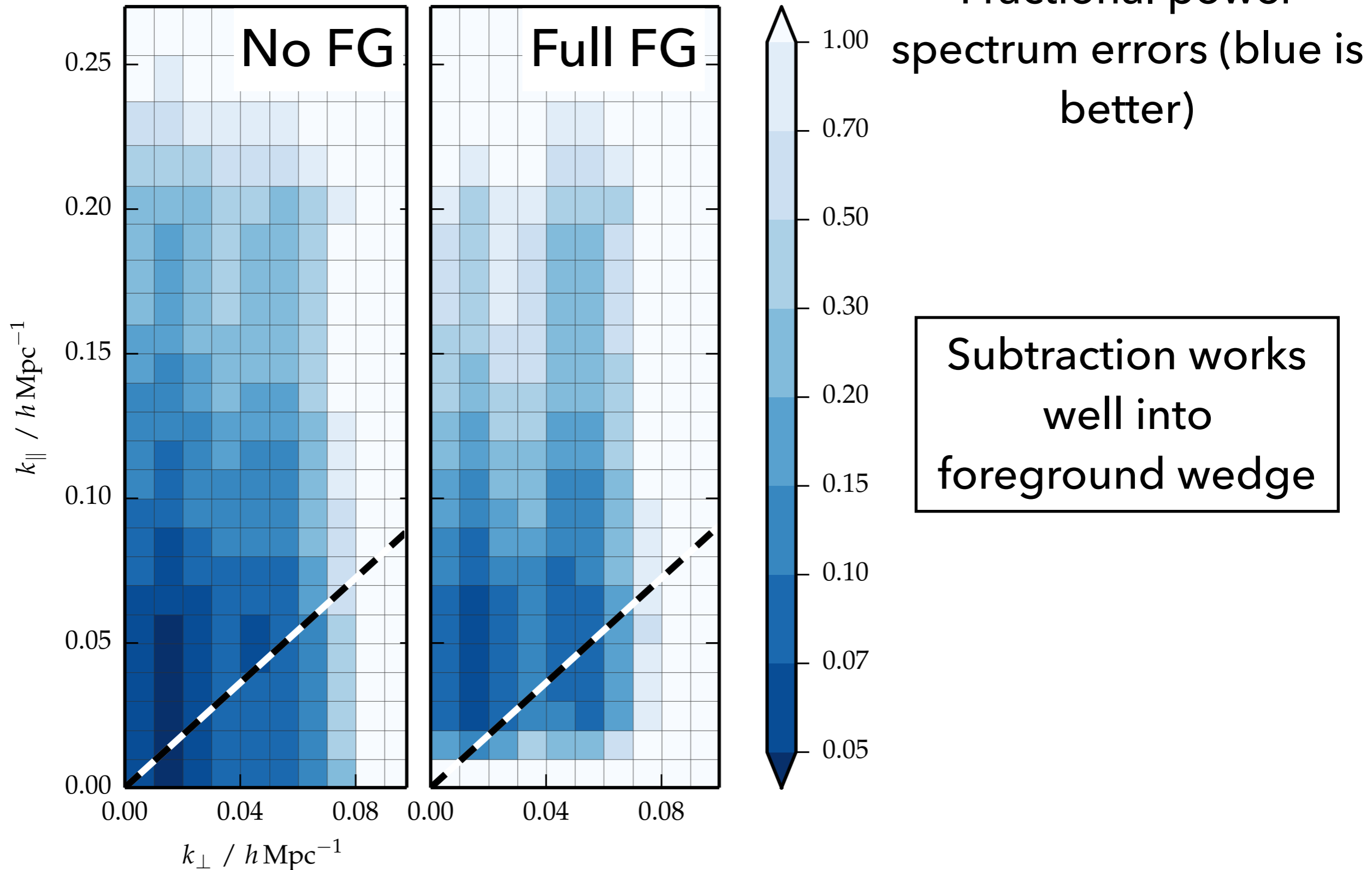


21cm Signal



Foreground residuals significantly smaller than signal

2D Power spectrum Estimation



Summary

- CHIME Pathfinder is operating, full instrument construction finishing in 2016
- Analysis is fun! Polarised radio sky simulation and 21cm data analysis code all available at:

<http://github.com/radiocosmology/>