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SEARCHING FOR DARK MATTER IN FERMI-LAT UNIDENTIFIED SOURCES WITH MACHINE LEARNING

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B. ZALDIVAR, J. CORONADO-BLAZQUÉZ, M. A. SÁNCHEZ-CONDE

June 16th, 2022

OUTLINE

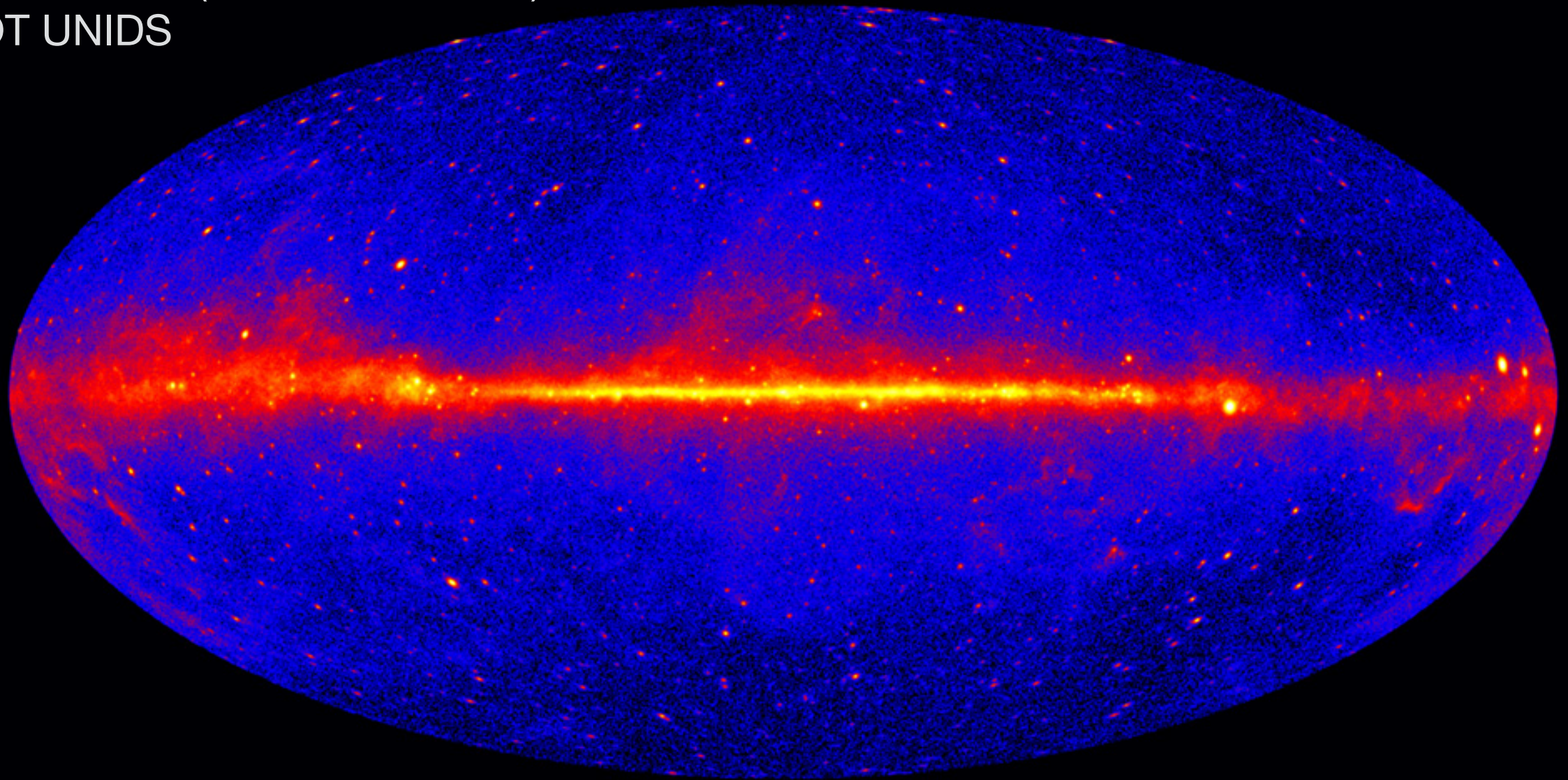
- **FERMI-LAT GAMMA-RAY DATA & BETA-PLOT**
- **DARK MATTER & BETA-PLOT**
- **“SYNTHETIC” FEATURES:
DETECTION SIGNIFICANCE σ_d AND UNCERTAINTY ON β**
- **INTRODUCTION TO CLASSIFICATION IN MACHINE LEARNING**
- **PRELIMINARY RESULTS**
- **PRELIMINARY CONCLUSIONS**

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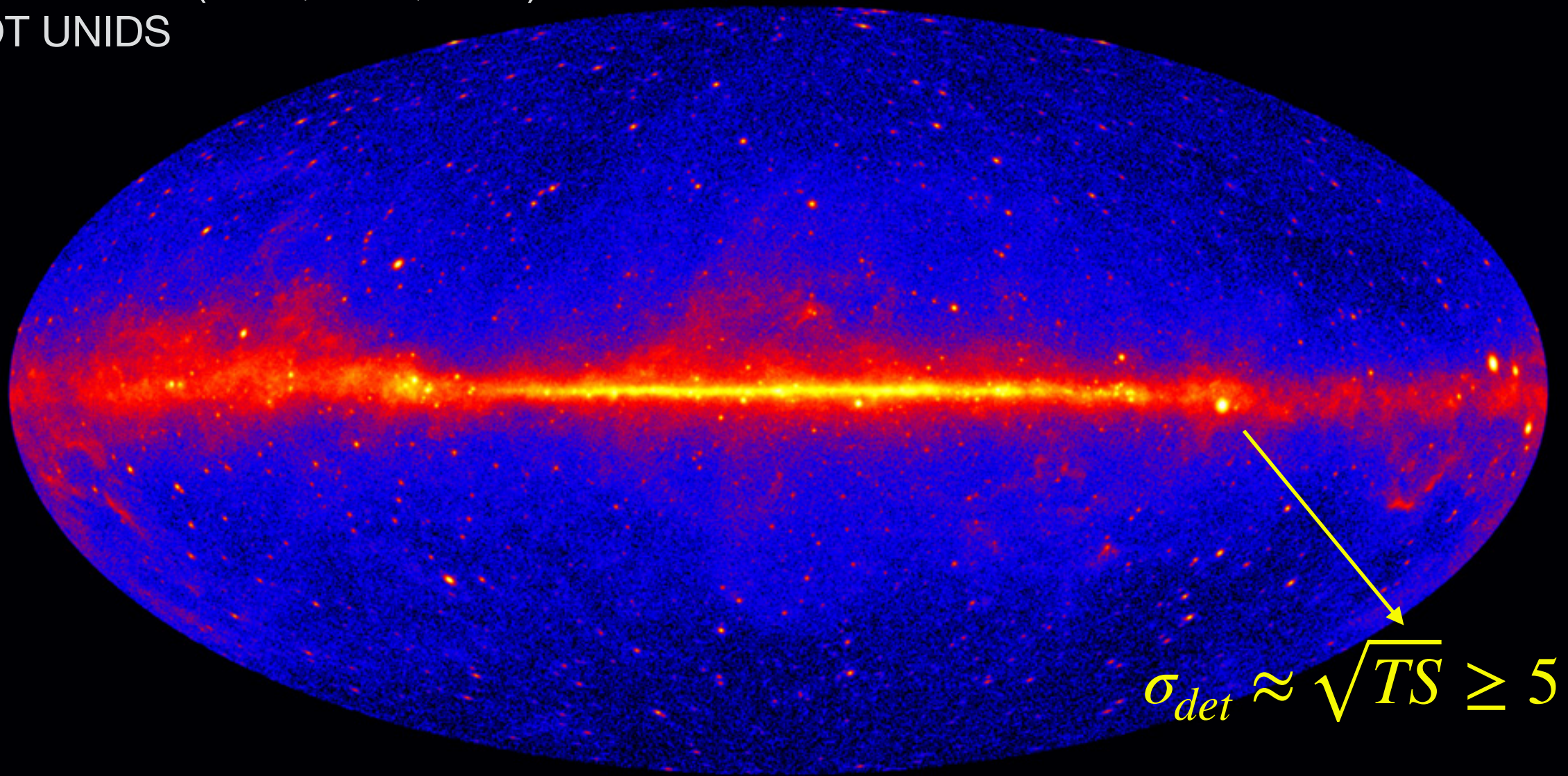
FERMI-LAT GAMMA-RAY DATA & BETA-PLOT

4FGL catalogue:
TOT ASTRO (PSR, QSR, BCU)
TOT UNIDS



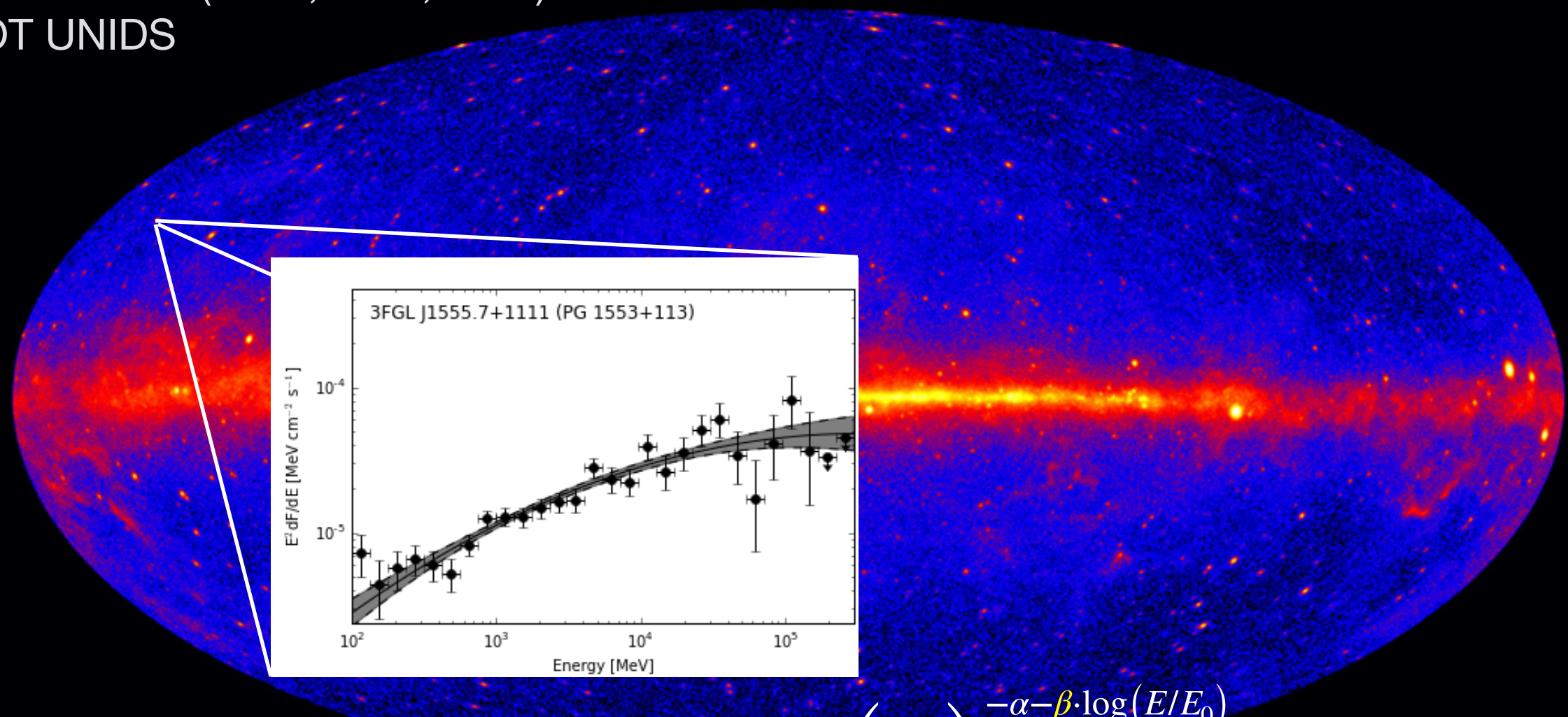
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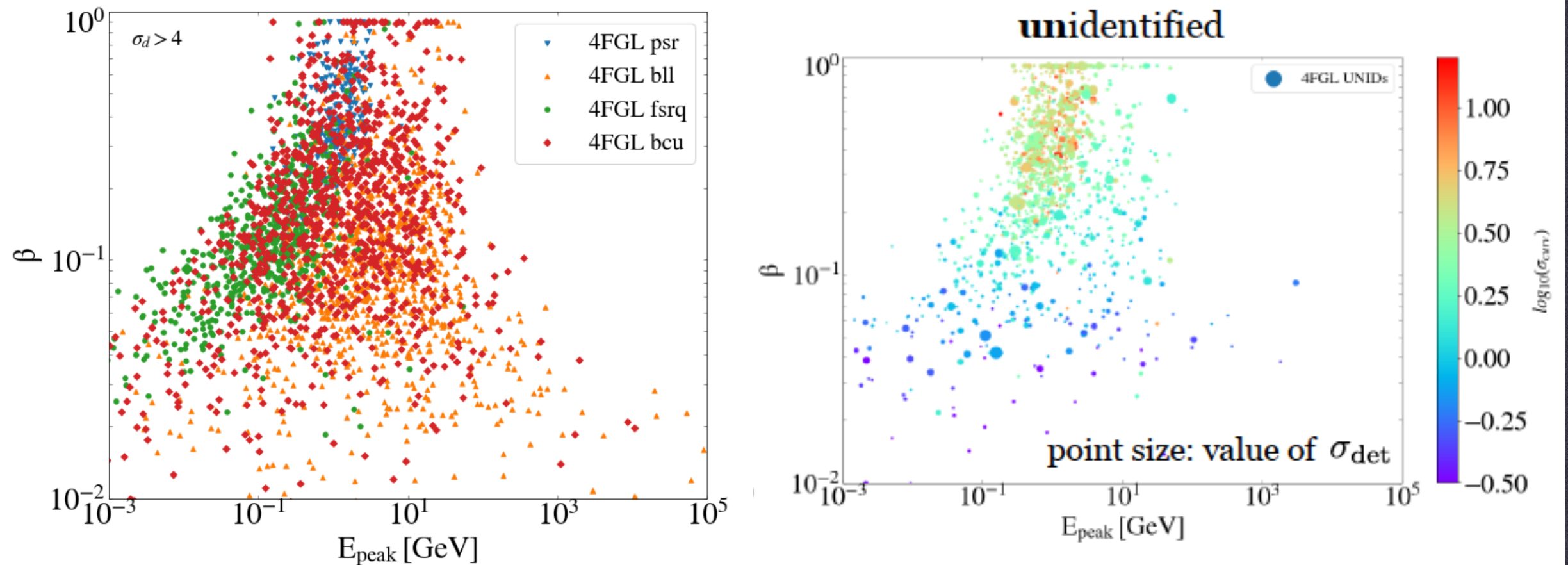
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Log-Parabola: $\frac{dN}{dE} = N_0 \left(\frac{E}{E_0} \right)^{-\alpha - \beta \cdot \log(E/E_0)}$, $E_{peak} = E_0 \cdot e^{\frac{2-\alpha}{2\beta}}$

FERMI-LAT GAMMA-RAY DATA & BETA-PLOT



$$\frac{dN}{dE} = N_0 \left(\frac{E}{E_0} \right)^{-\alpha - \beta \cdot \log(E/E_0)}, \quad E_{\text{peak}} = E_0 \cdot e^{\frac{2-\alpha}{2\beta}}$$

PREVIOUS WORKS

3FGLzoo. Classifying 3FGL Unassociated Fermi-LAT Gamma-ray Sources by Artificial Neural Networks

D. Salvetti^{1★}, G. Chiaro^{1,2†}, G. La Mura², and D. J. Thompson³

Artificial Neural Network Classification of 4FGL Sources

S. Germani,^{1★} G. Tosti,¹ P. Lubrano,² S. Cutini,² I. Mereu,² A. Berretta¹

¹*Dipartimento di Fisica e Geologia, Univ. degli Studi di Perugia, Via A. Pascoli snc, I-06123 Perugia, Italy*

²*INFN – Istituto Nazionale di Fisica Nucleare Sez. Perugia, Via A. Pascoli snc, I-06123 Perugia, Italy*

Searches for Pulsar-like Candidates from Unidentified Objects in the Third Catalog of Hard *Fermi*-LAT (3FHL) sources with Machine Learning Techniques

C. Y. Hui,^{1★} Jongsu Lee,² K.L. Li,^{1,3,4} Sangin Kim,² Kwangmin Oh,² Shengda Luo,⁵
Alex P. Leung,⁵ A. K. H. Kong,⁴ J. Takata,⁶ K. S. Cheng⁷

Machine learning application to Fermi-LAT data: sharpening all-sky map and emphasizing variable sources

Shogo Sato, Jun Kataoka, Soichiro Ito, Jun'ichi Kotoku, Masato Taki, Asuka Oyama, Takaya Toyoda, Yuki Nakamura, Marino Yamamoto

PREVIOUS WORKS

Spectral and spatial analysis of the dark matter subhalo candidates among *Fermi* Large Area Telescope unidentified sources

Javier Coronado-Blázquez^{a,b} Miguel A. Sánchez-Conde^{a,b} Mattia Di Mauro^{c,d} Alejandra Aguirre-Santaella^{a,b} Ioana Ciucă^e Alberto Domínguez^f Daisuke Kawata^e Néstor Mirabal^{c,g}

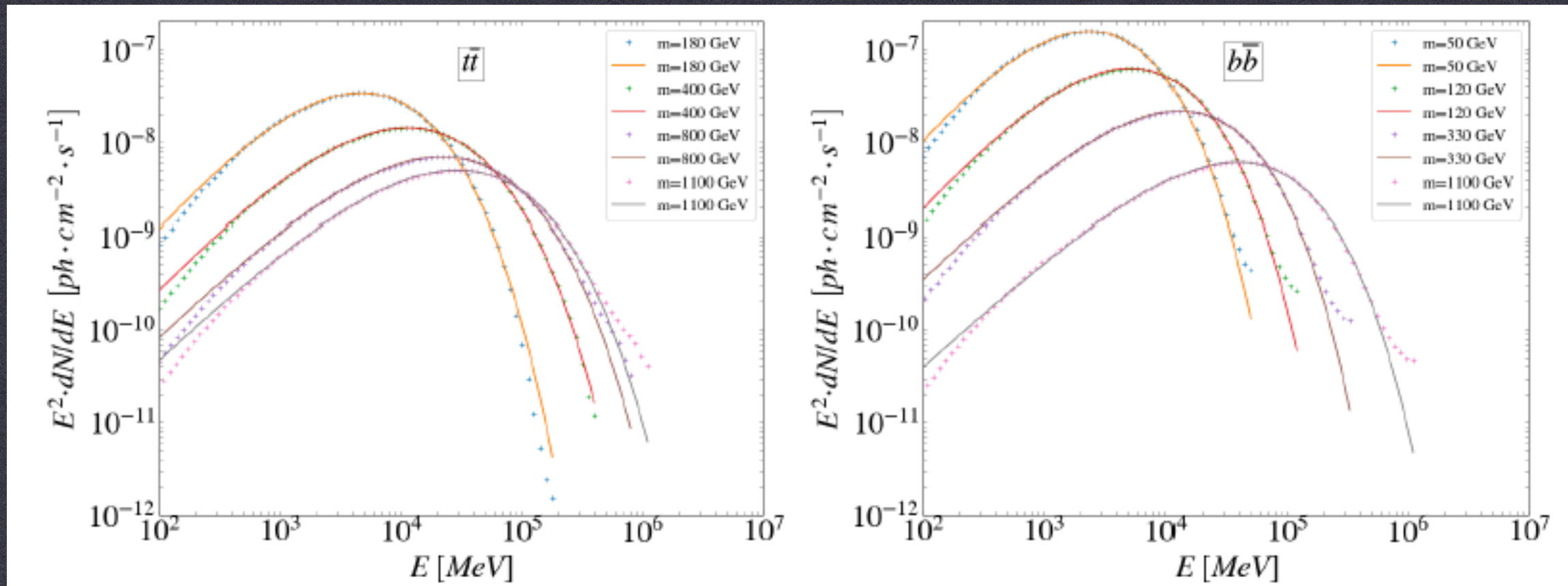
Unidentified Gamma-ray Sources as Targets for Indirect Dark Matter Detection with the Fermi-Large Area Telescope

Javier Coronado-Blázquez, Miguel A. Sánchez-Conde, Alberto Domínguez, Alejandra Aguirre-Santaella, Mattia Di Mauro, Néstor Mirabal, Daniel Nieto, Eric Charles

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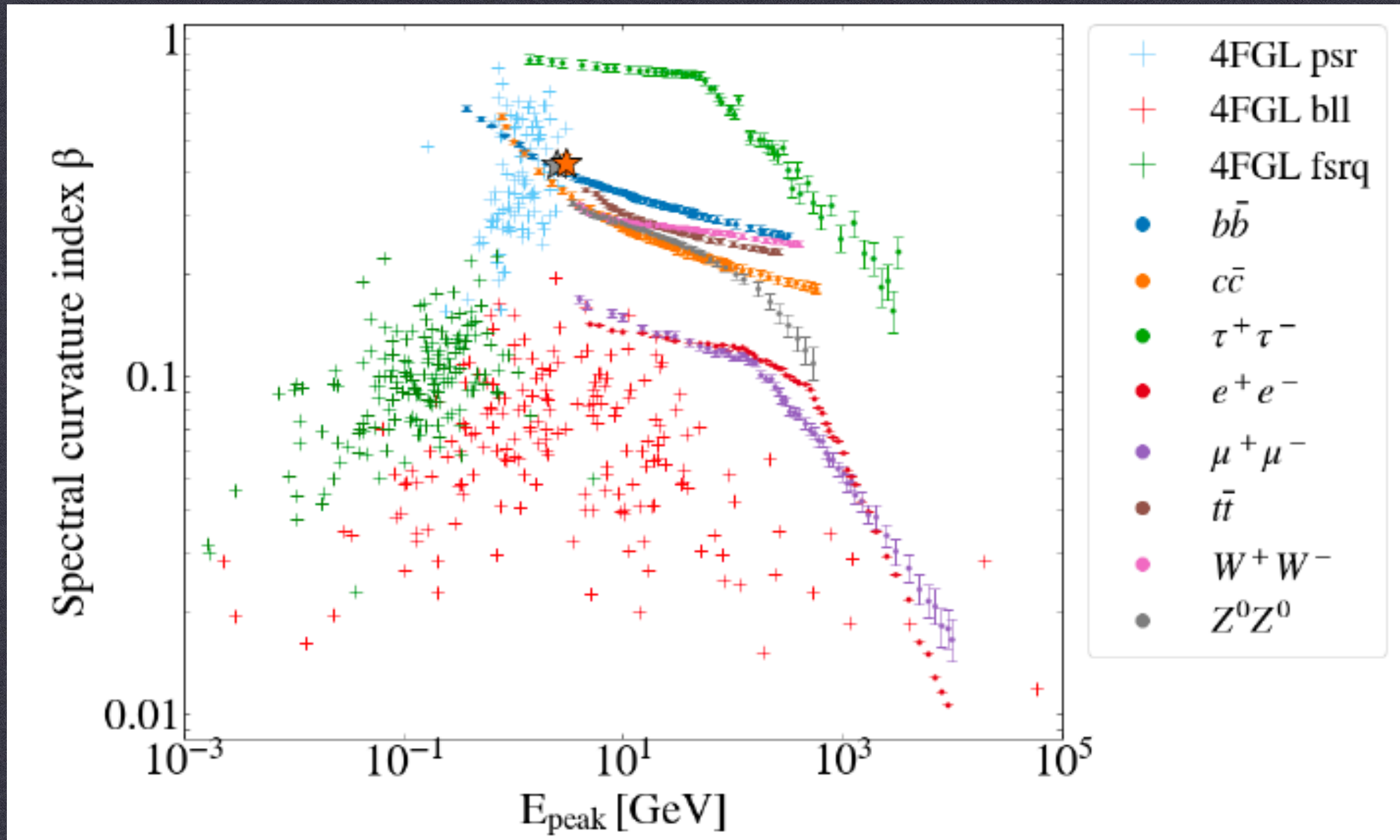
DARK MATTER & BETA-PLOT



J. Coronado-Blazquez et al. JCAP07(2019)020

$$\frac{dN}{dE} = N_0 \left(\frac{E}{E_0} \right)^{-\alpha - \beta \cdot \log(E/E_0)}, \quad E_{peak} = E_0 \cdot e^{\frac{2-\alpha}{2\beta}}$$

DARK MATTER & BETA-PLOT

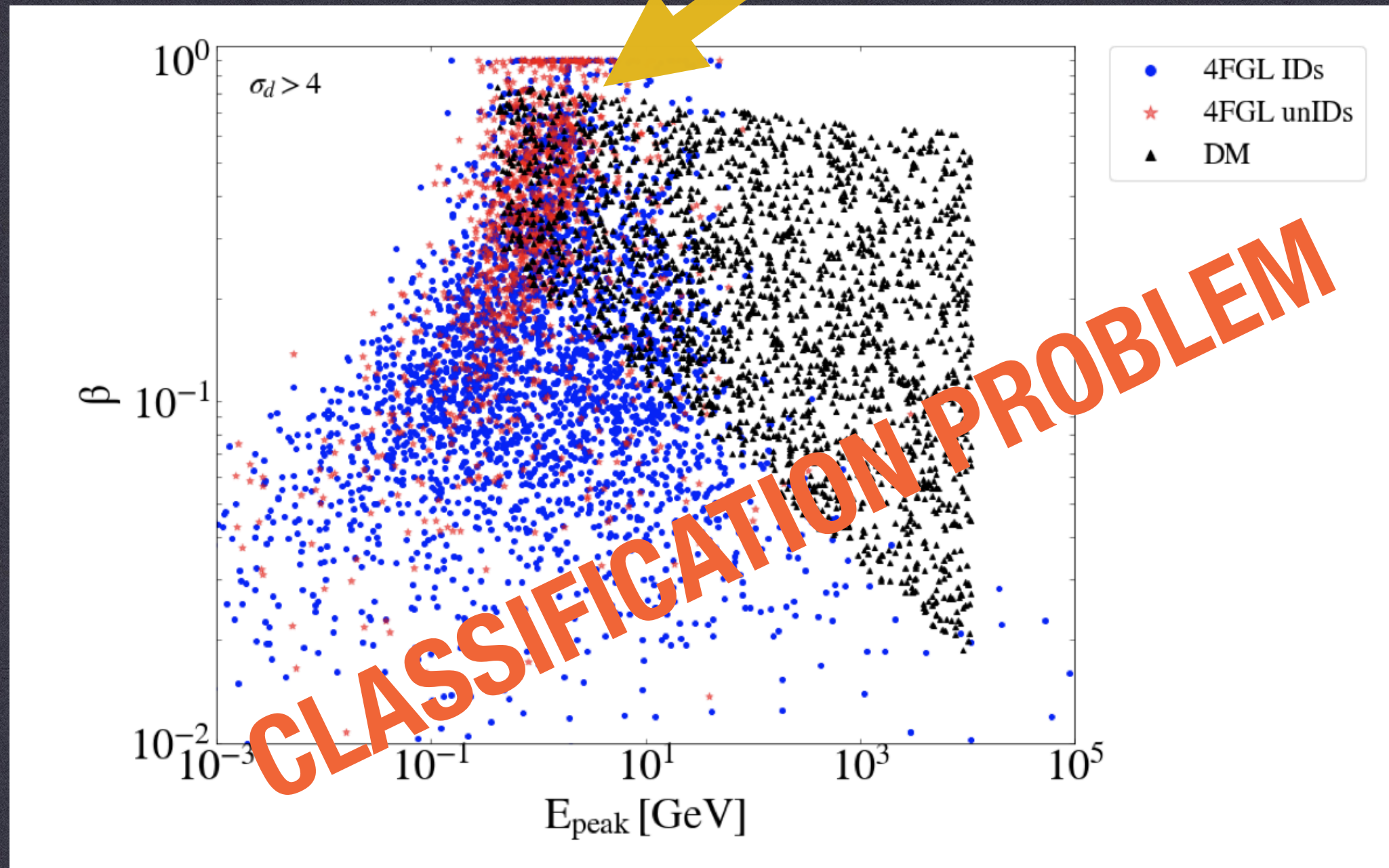


J. Coronado-Blázquez et al., JCAP11(2019)045

DARK MATTER & BETA-PLOT

$$\frac{dN}{dE} = B_r \left(\frac{dN}{dE} \right)_{c_1} + (1 - B_r) \left(\frac{dN}{dE} \right)_{c_2}$$

Degeneracy of
pulsar and DM signal



DARK MATTER & BETA-PLOT

Our strategy:

1. The classification algorithm is trained on a **sample of Astrophysical (Astro) and Dark Matter (DM) sources**. The classification accuracy is tested on a subsample of data;
2. The “machine” has learned the classification problem and it is **applied to the unIDS dataset**: we expect the algorithm telling us if any unIDS could be a DM source with a given probability.

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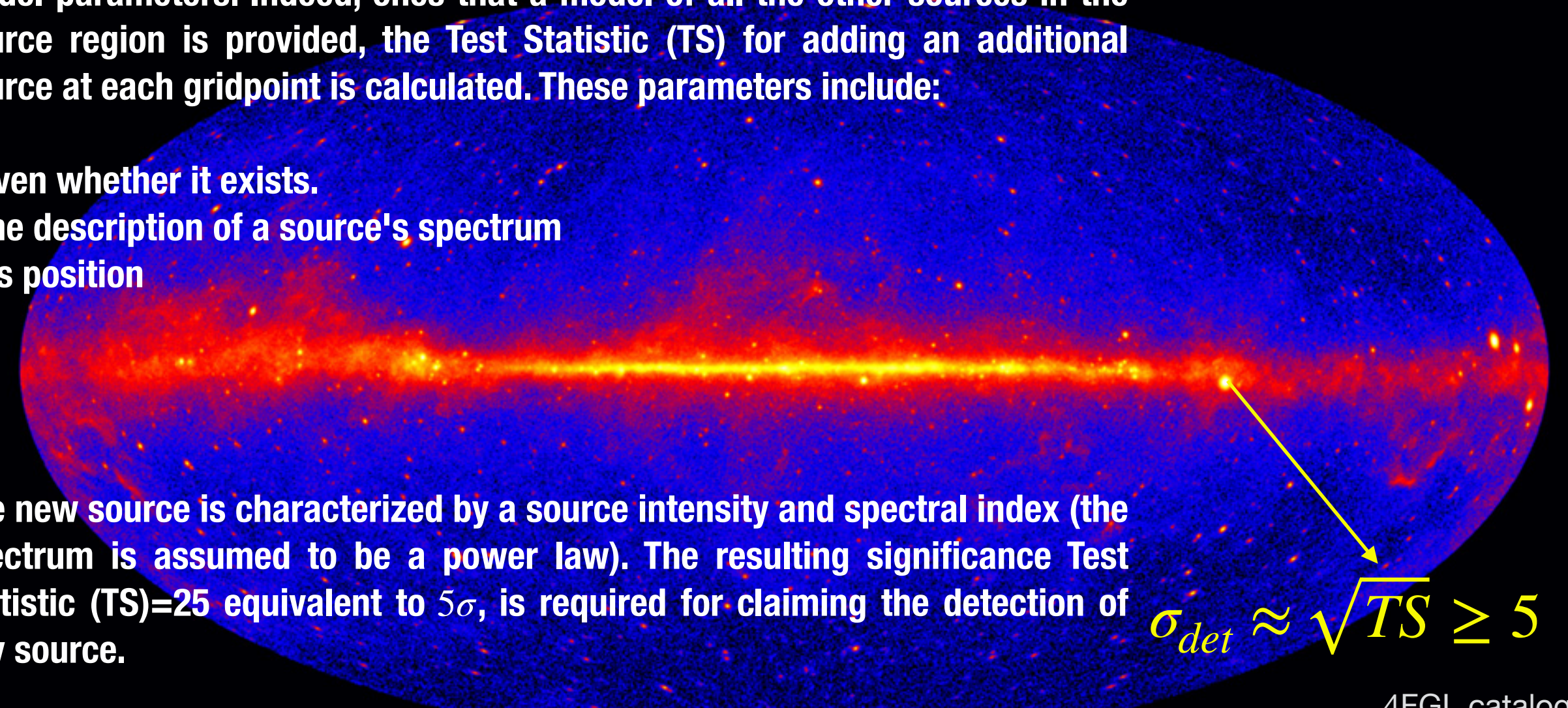
DETECTION SIGNIFICANCE

To analyze LAT data, the collaboration tools construct the likelihood that is applicable to the LAT data, and then use this likelihood to find the best fit model parameters. Indeed, once a model of all the other sources in the source region is provided, the Test Statistic (TS) for adding an additional source at each gridpoint is calculated. These parameters include:

- even whether it exists.
- the description of a source's spectrum
- its position

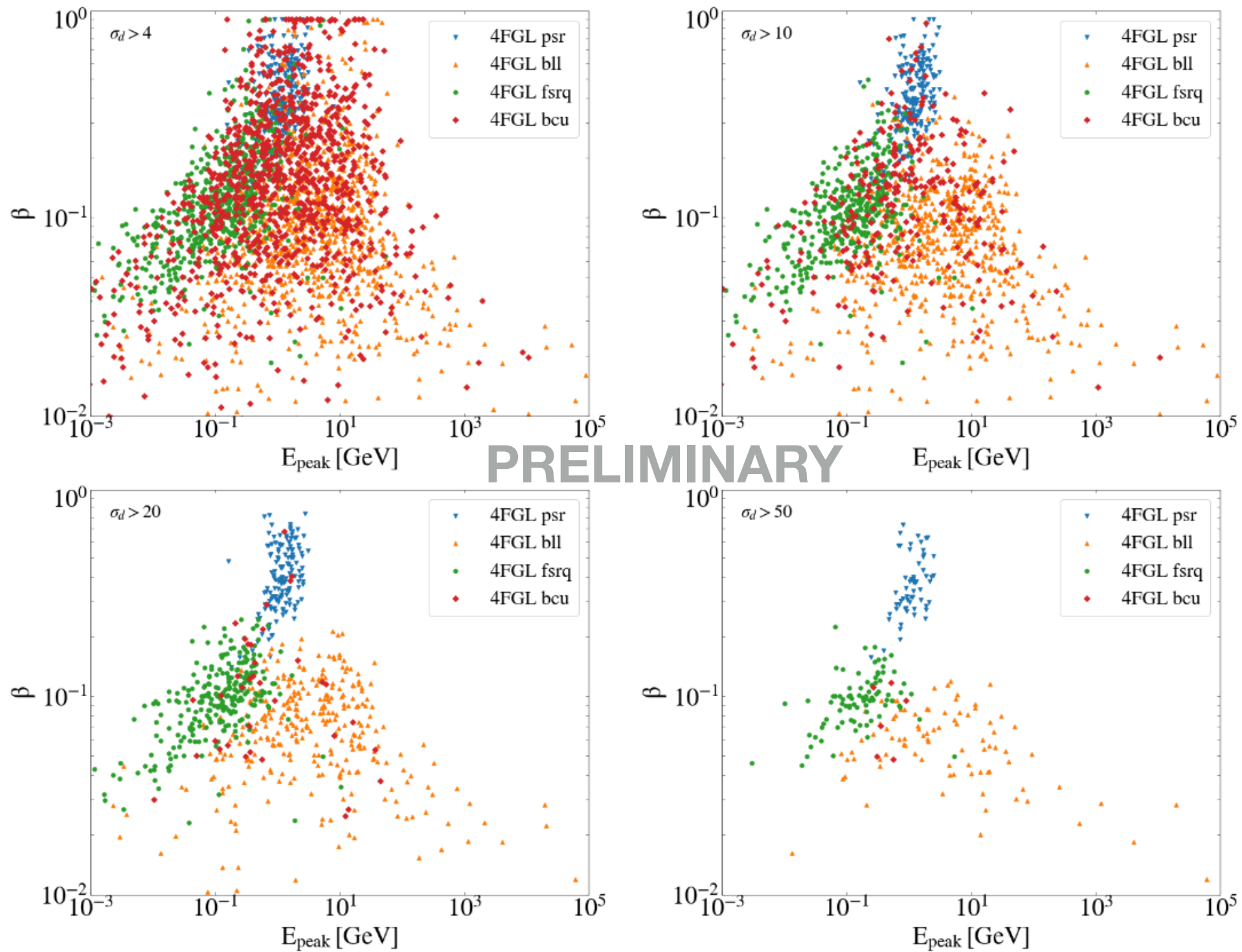
The new source is characterized by a source intensity and spectral index (the spectrum is assumed to be a power law). The resulting significance Test Statistic (TS)=25 equivalent to 5σ , is required for claiming the detection of any source.

Hereafter, we will use the so-defined detection significance σ_d as a feature of our classification problem.

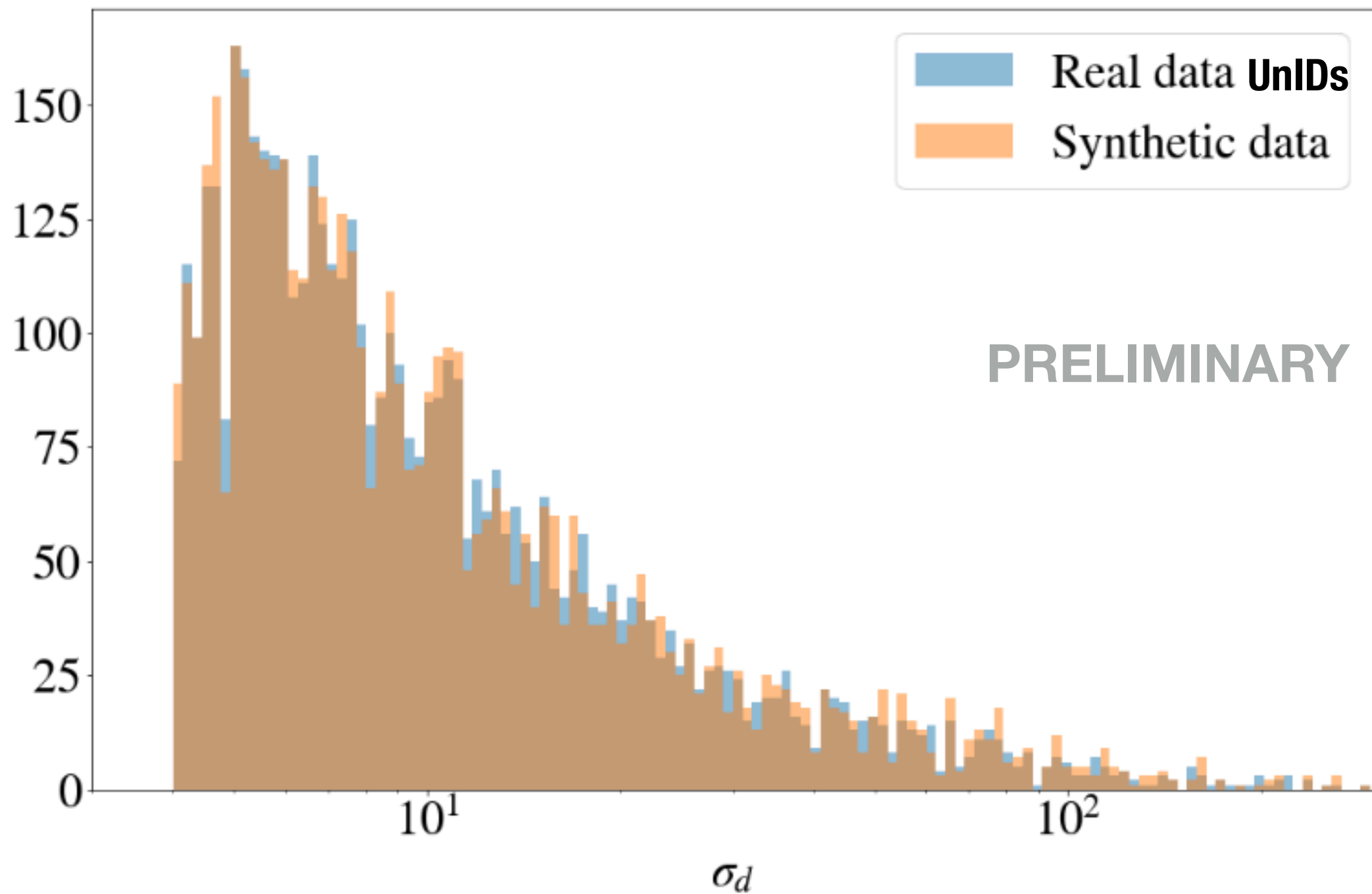

$$\sigma_{det} \approx \sqrt{TS} \geq 5$$

4FGL catalogue:
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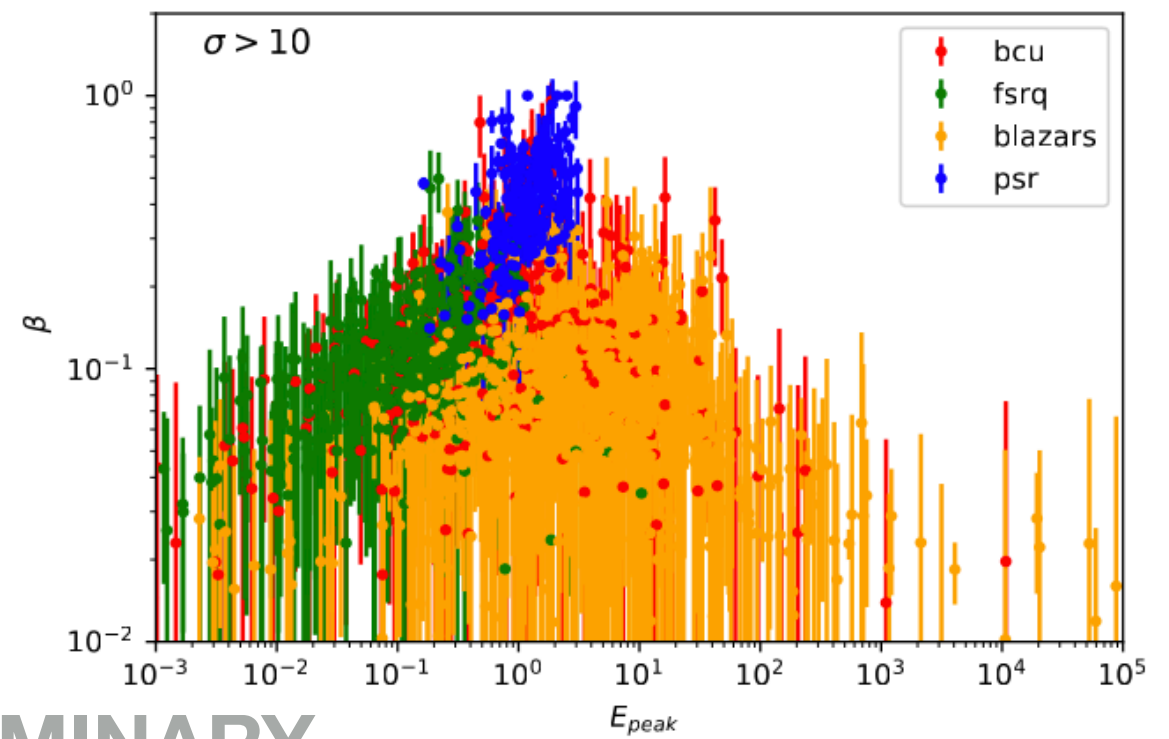
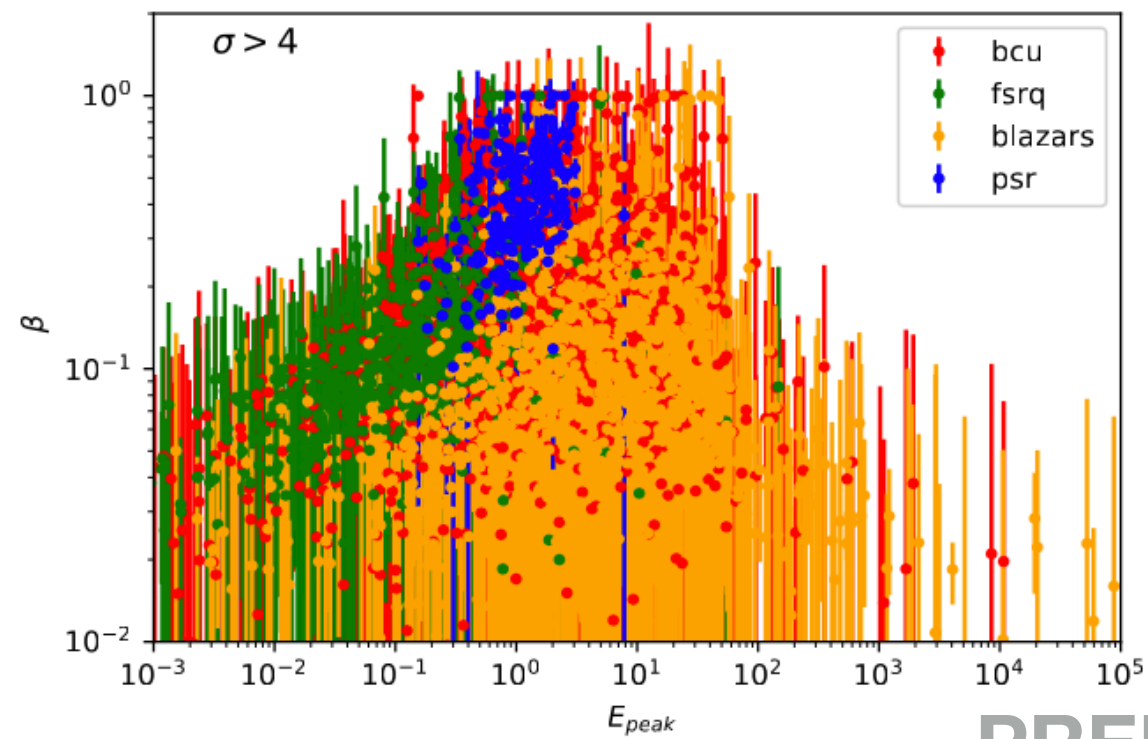
DETECTION SIGNIFICANCE



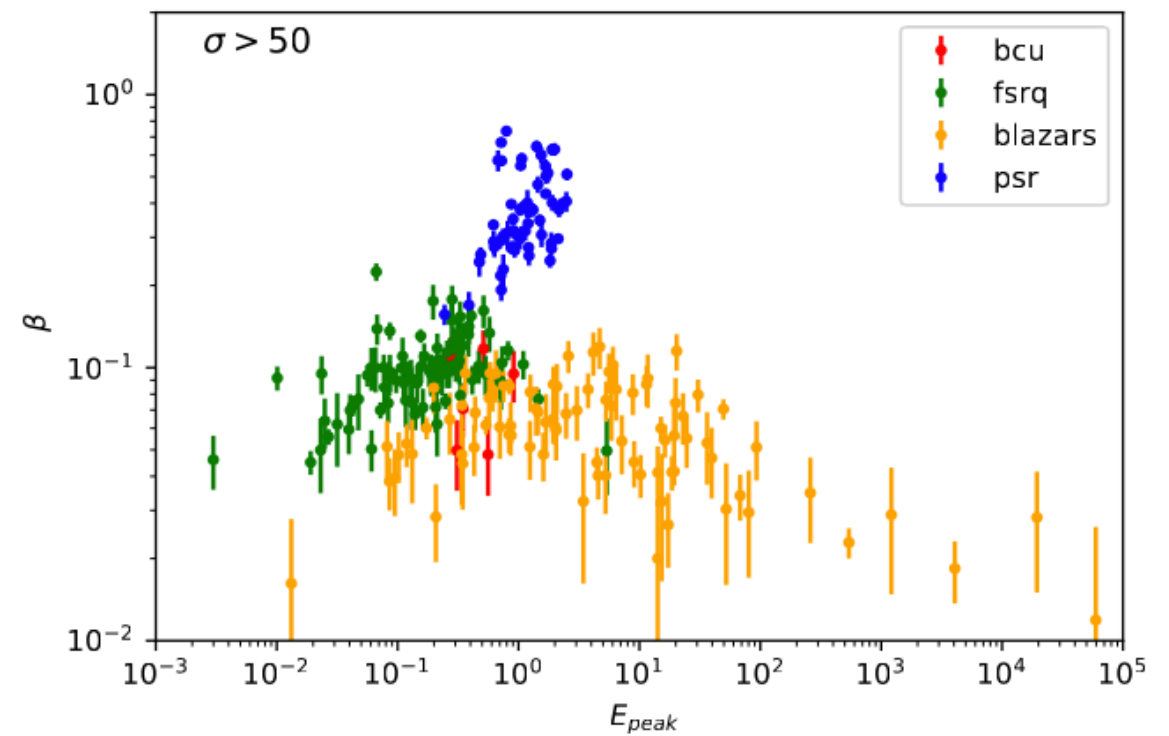
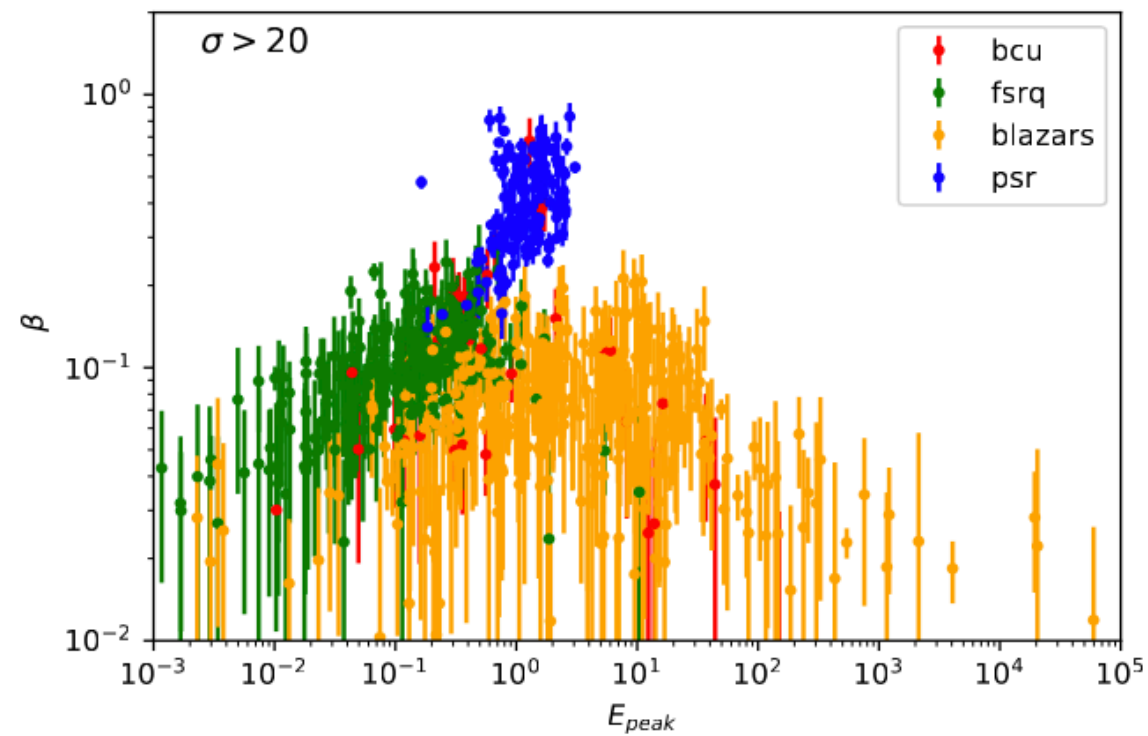
DETECTION SIGNIFICANCE



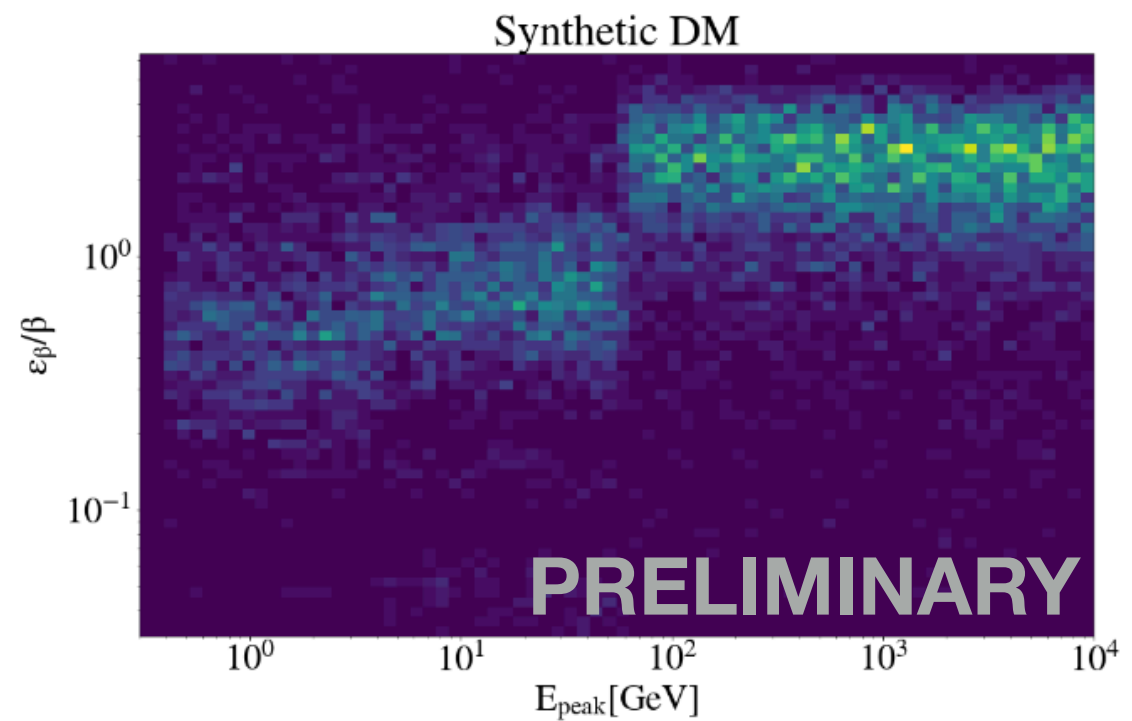
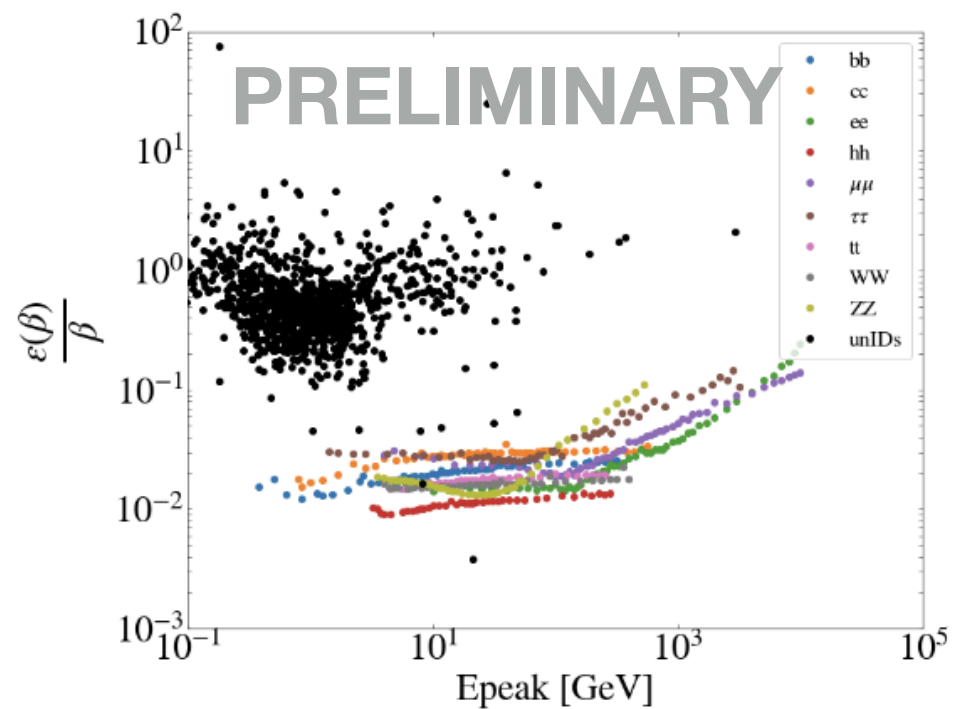
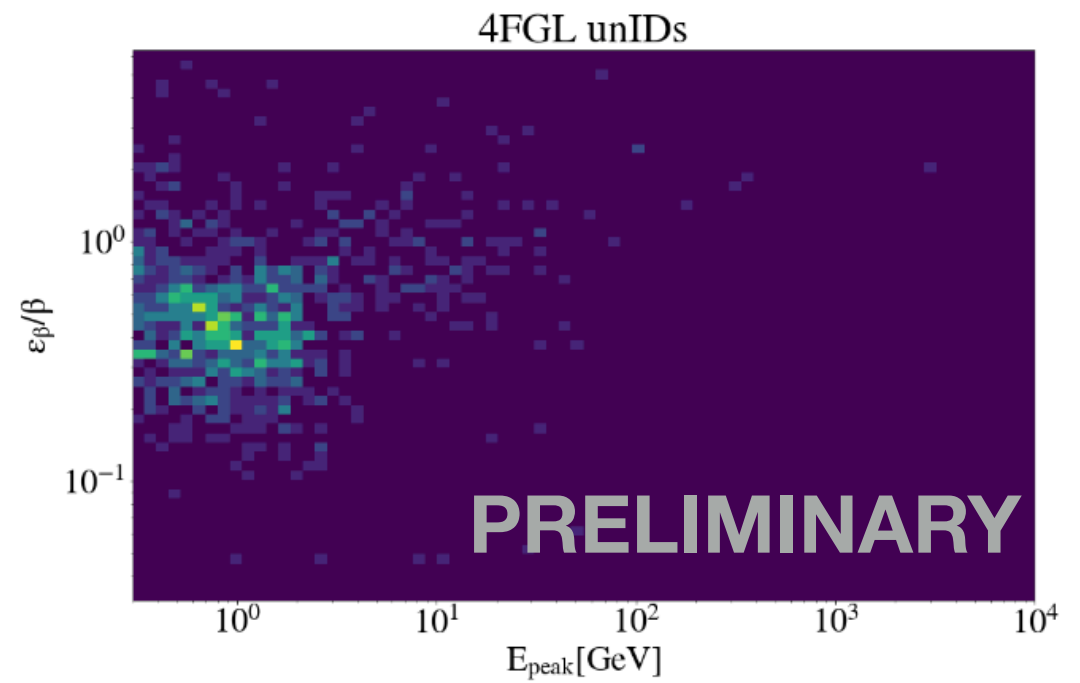
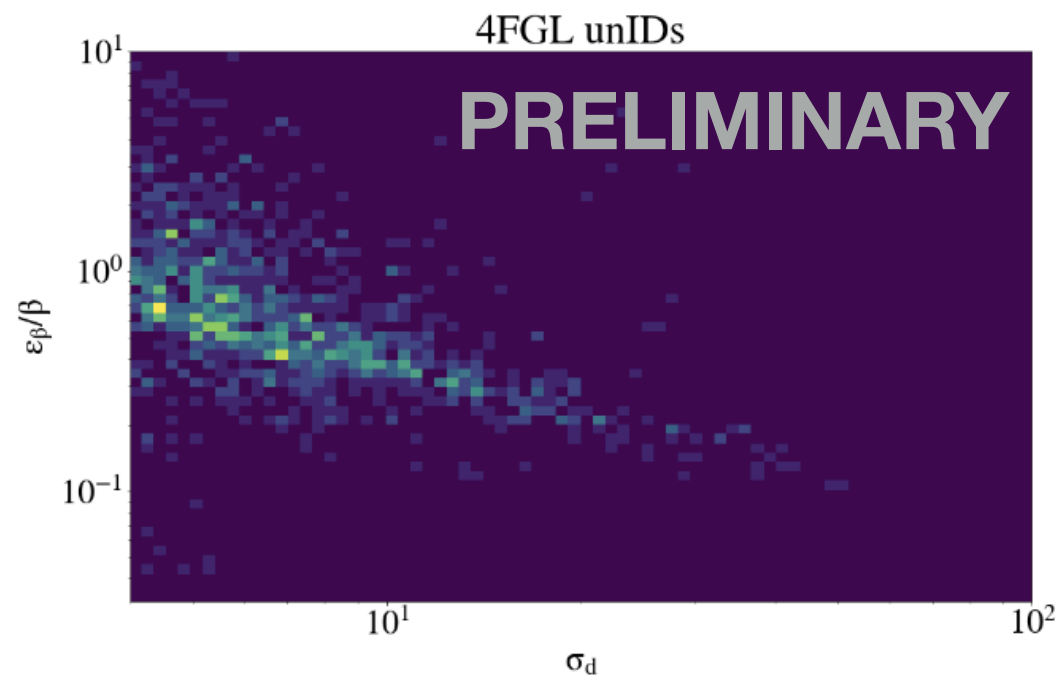
UNCERTAINTY ON β



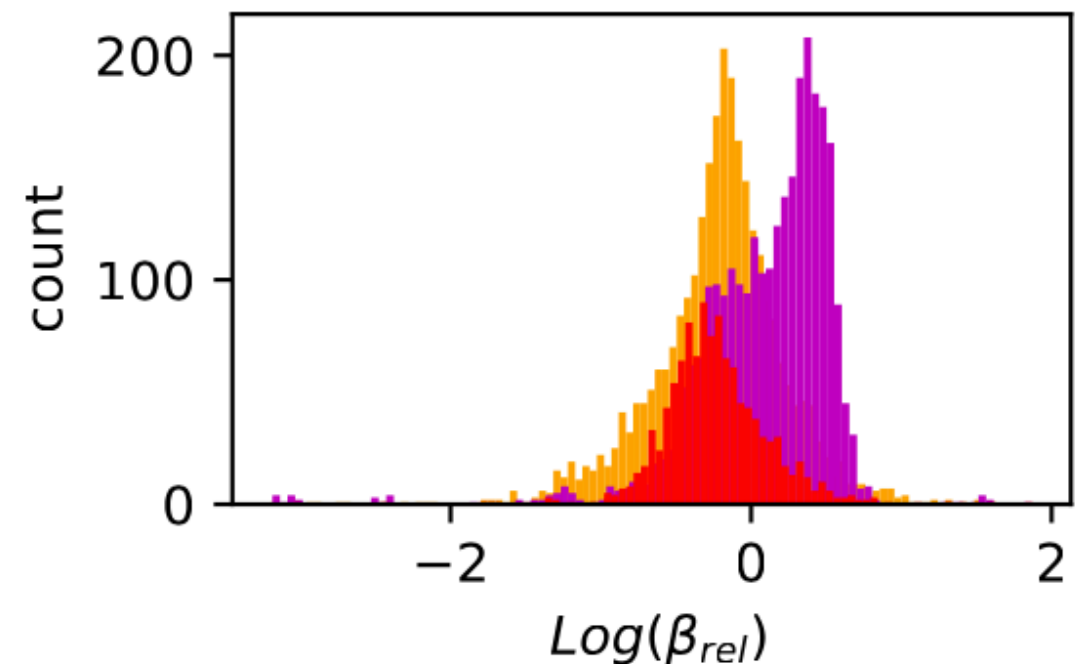
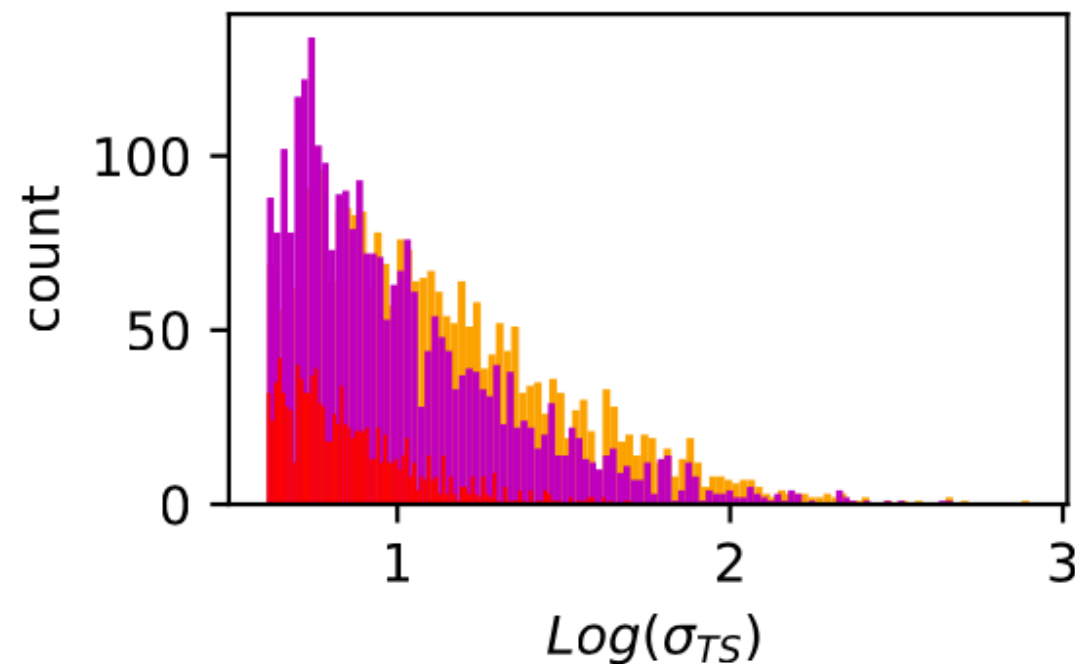
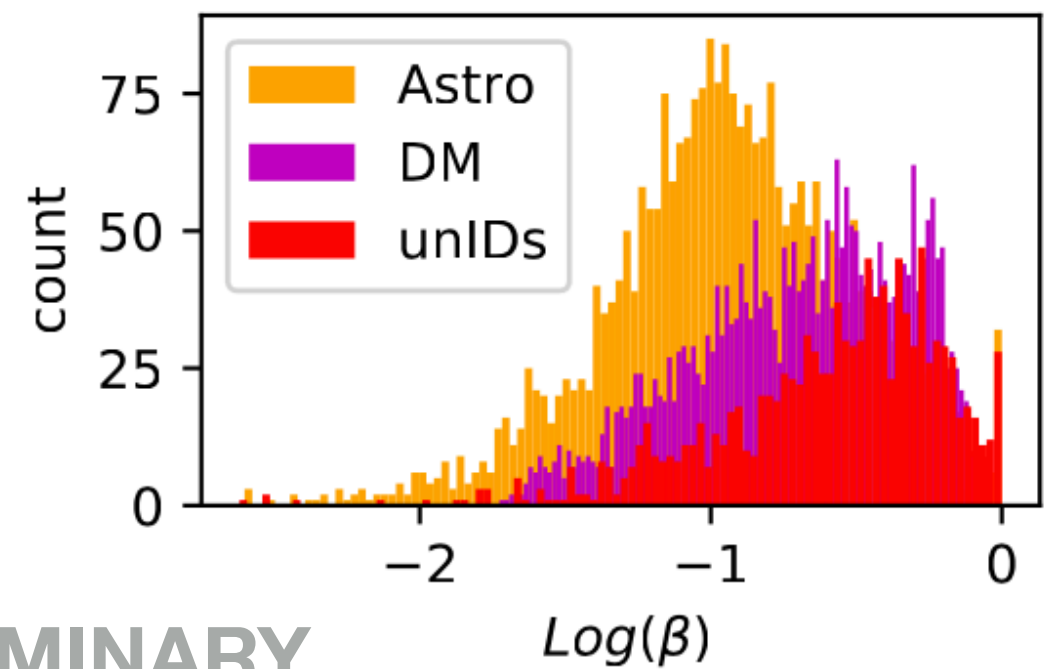
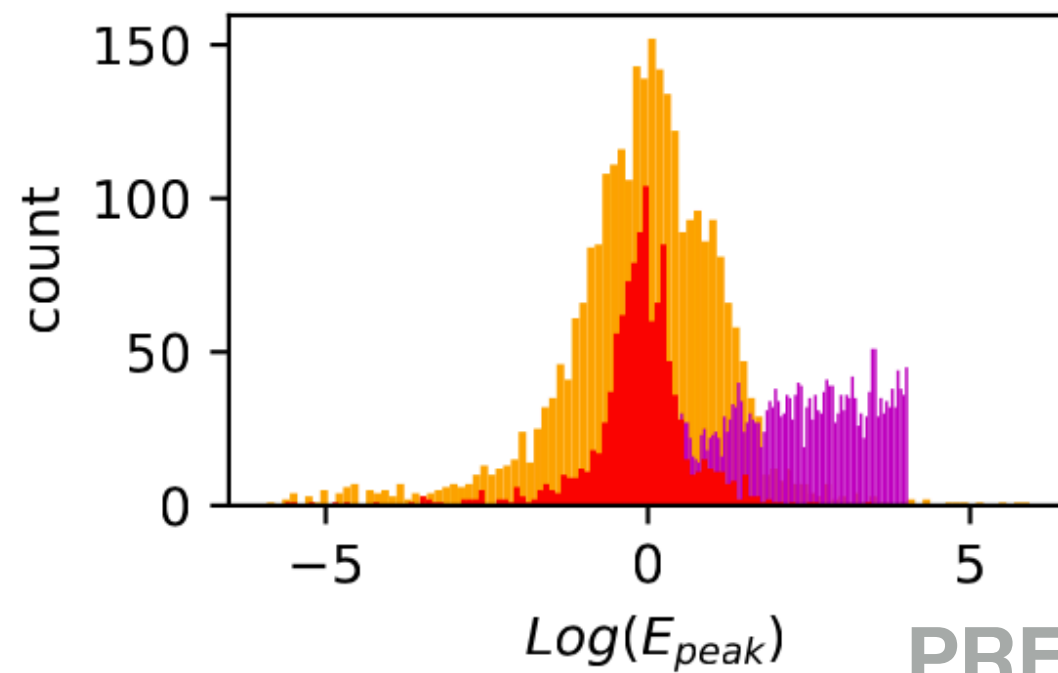
PRELIMINARY



UNCERTAINTY ON β



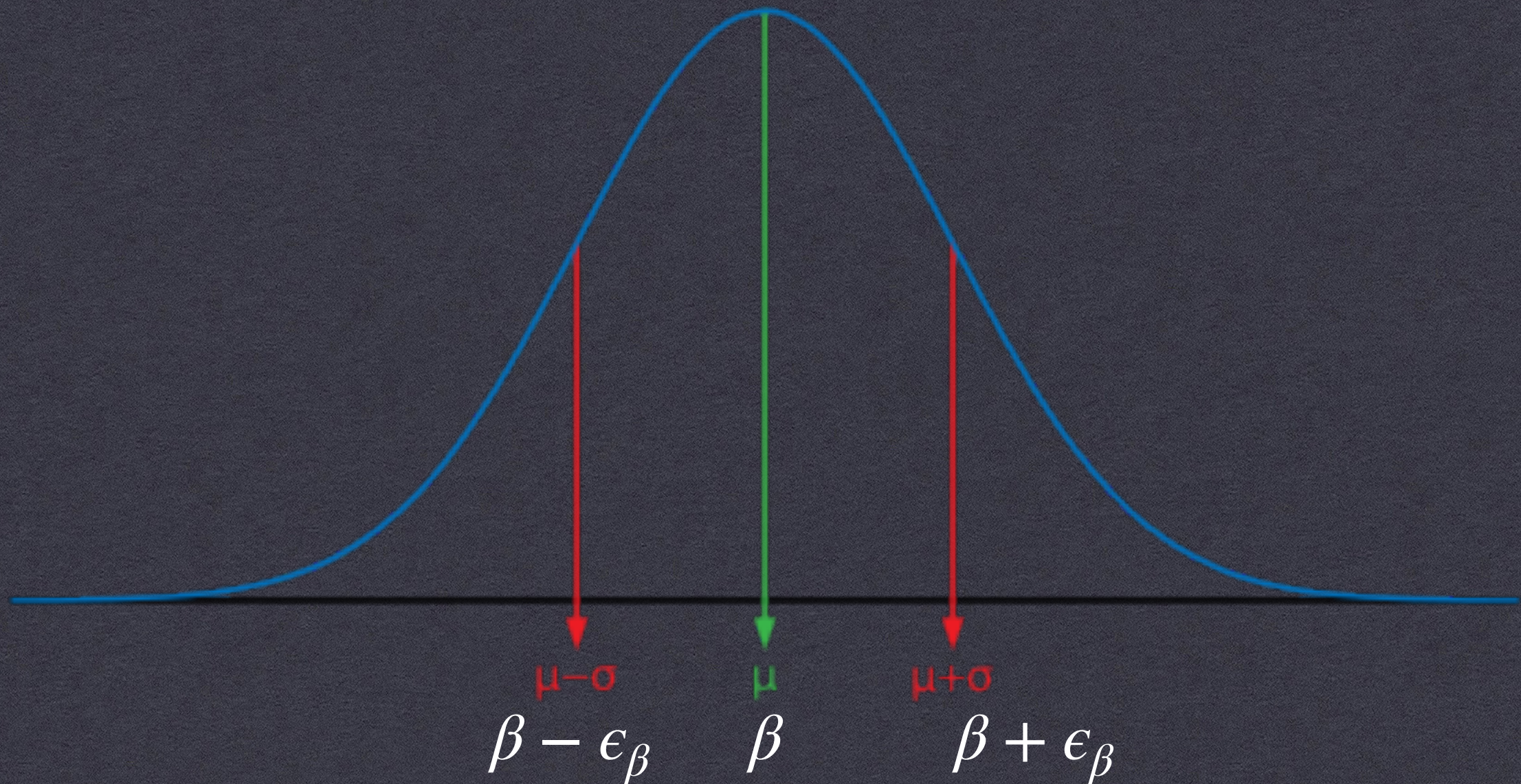
4 FEATURES DISTRIBUTIONS



PRELIMINARY

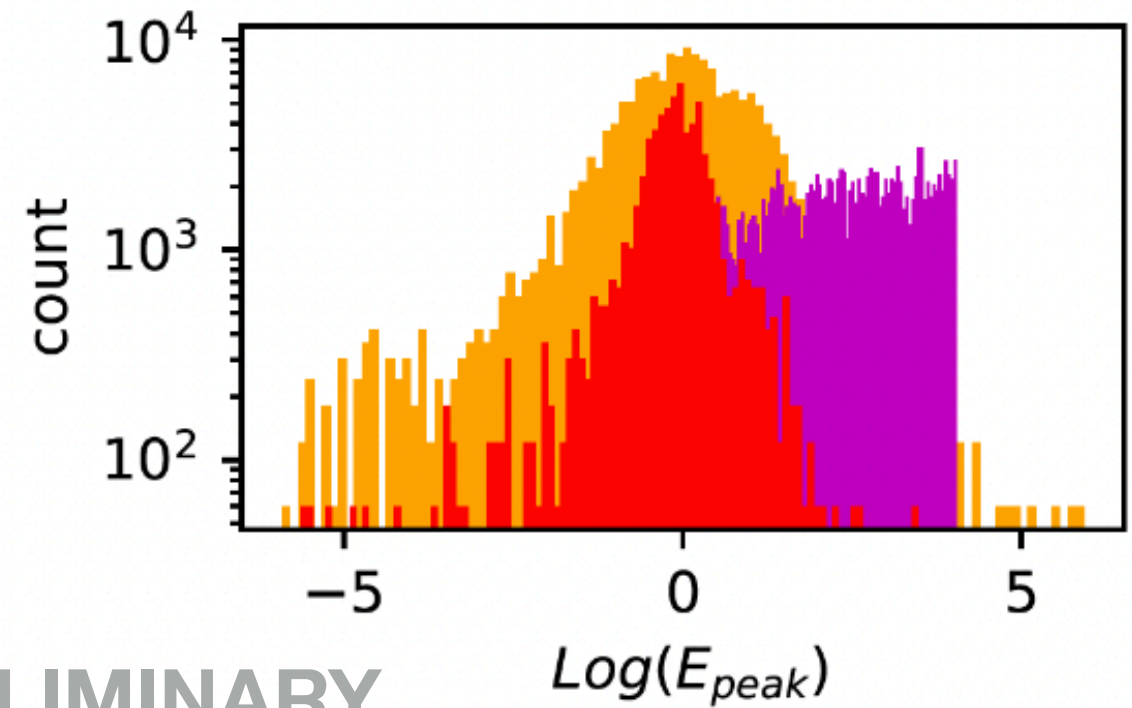
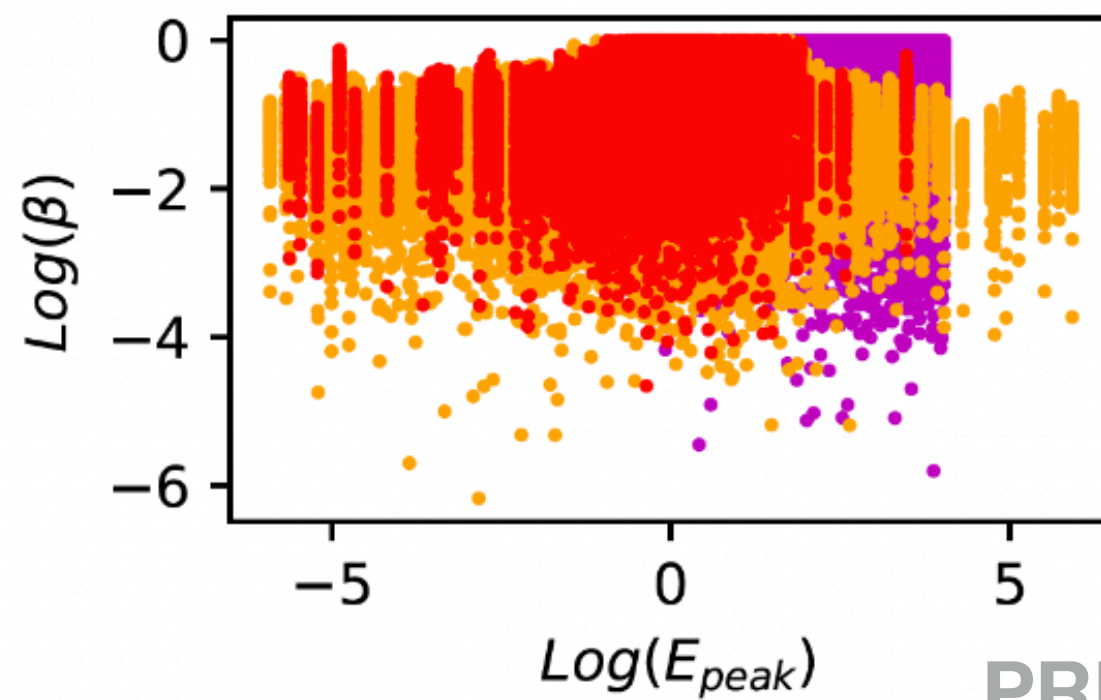
GAUSSIAN SAMPLING OF β UNCERTAINTY

$$M = 60$$

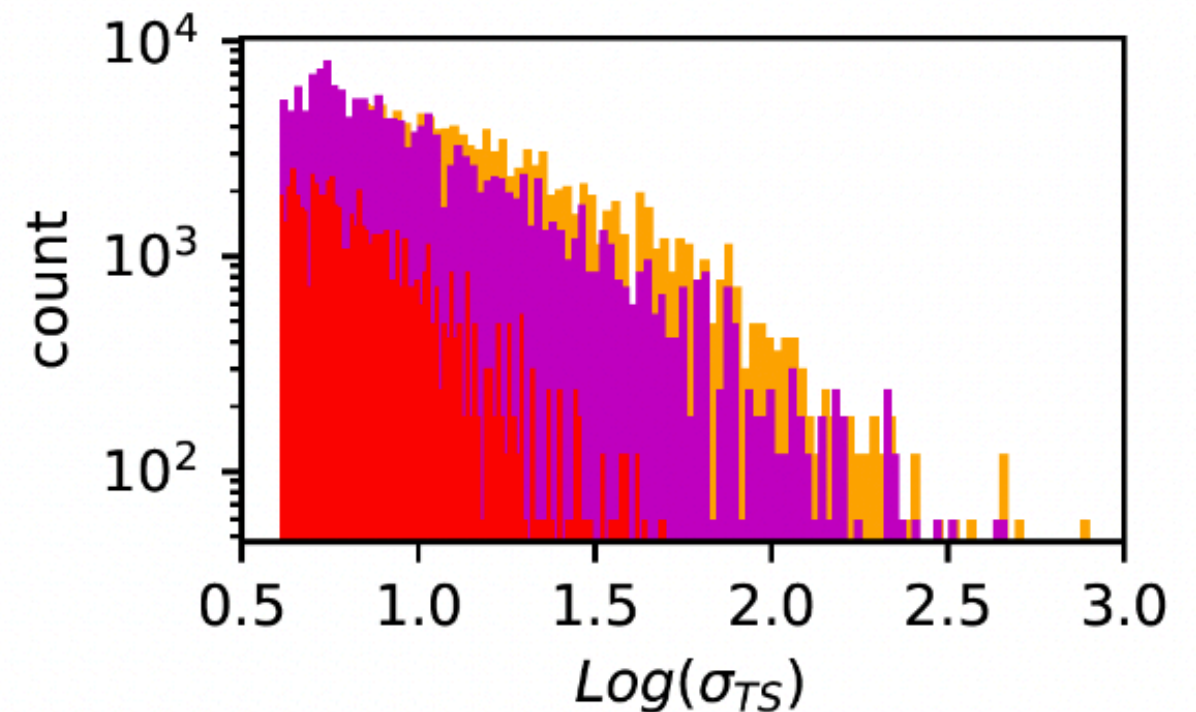
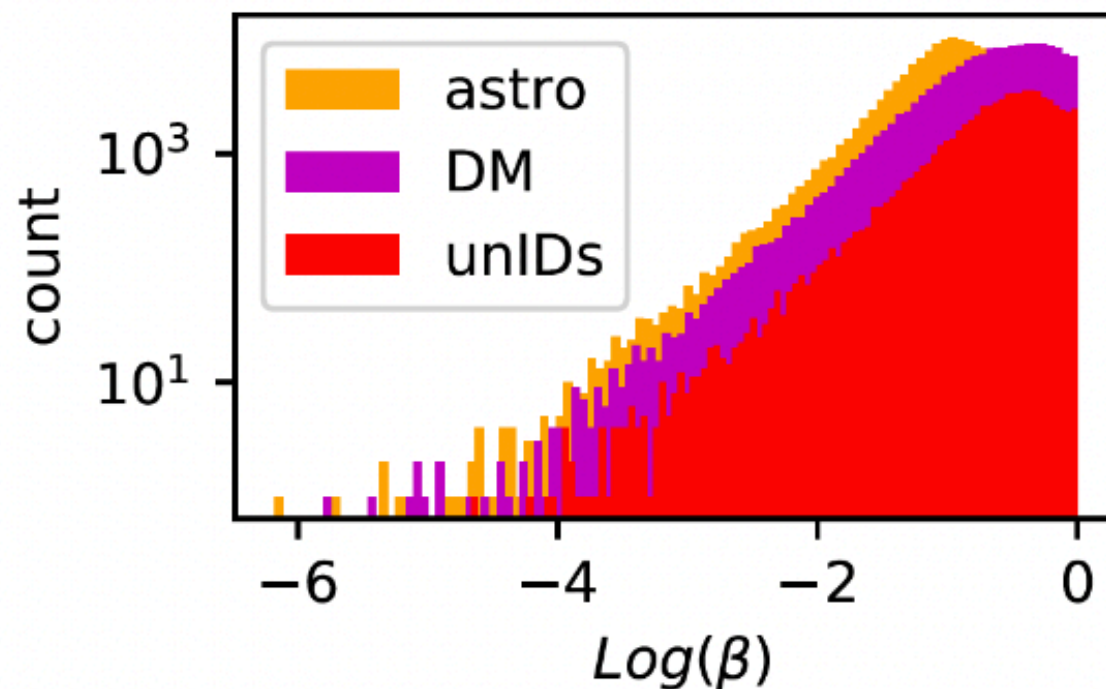


$0 < \beta \leq 1$ Is required if β is small and ϵ_β is big

GAUSSIAN SAMPLING OF β UNCERTAINTY



PRELIMINARY



GAUSSIAN SAMPLING OF β UNCERTAINTY

Related issues:

- **Increasing the number of data** from N (Astro+DM datasets) to MxN makes the learning process slower;
- After the learning step and in order to classify the unIDs, the method would also require the **sample of the unIDs uncertainty**, that is useless for the classification intent itself.

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CLASSIFICATION ALGORITHMS



- ▶ **LOGISTIC REGRESSION (LR) (SCIKITS-LEARN)**
- ▶ **ARTIFICIAL NEURAL NETWORK (NN) (SCIKITS-LEARN)**
- ▶ **NAIVES BAYES (NB) (TENSOR FLOW)**
- ▶ **GAUSSIAN PROCESS (GP) (TENSOR FLOW)**



CLASSIFICATION ALGORITHMS

- ▶ **LOGISTIC REGRESSION (LR):** PROBABILISTIC DISCRIMINATIVE MODEL. DESPITE ITS NAME, IS A CLASSIFICATION MODEL RATHER THAN REGRESSION MODEL.
- ▶ **NEURAL NETWORK (NN):** PROBABILISTIC DISCRIMINATIVE MODEL. ARE A NON-LINEAR STATISTICAL DATA MODELING TOOL COMPOSED OF HIGHLY INTERCONNECTED NODES THAT CAN MODEL COMPLEX RELATIONSHIPS BETWEEN INPUTS AND OUTPUTS.
- ▶ **NAIVE BAYES (NB):** GENERATIVE MODEL. A PROBABILISTIC CLASSIFIER BASED ON BAYES' THEOREM, WHICH ASSUMES THAT EACH FEATURE MAKES AN INDEPENDENT AND EQUAL CONTRIBUTION TO THE TARGET CLASS.
- ▶ **GAUSSIAN PROCESS (GP):** NON-PARAMETRIC MODEL. IT IS A STOCHASTIC PROCESS, I.E. A COLLECTION OF RANDOM VARIABLES, SUCH THAT EVERY FINITE LINEAR COMBINATION OF THEM IS NORMALLY DISTRIBUTED. THE DISTRIBUTION OF A GP IS THE JOINT DISTRIBUTION OF ALL THOSE RANDOM VARIABLES.

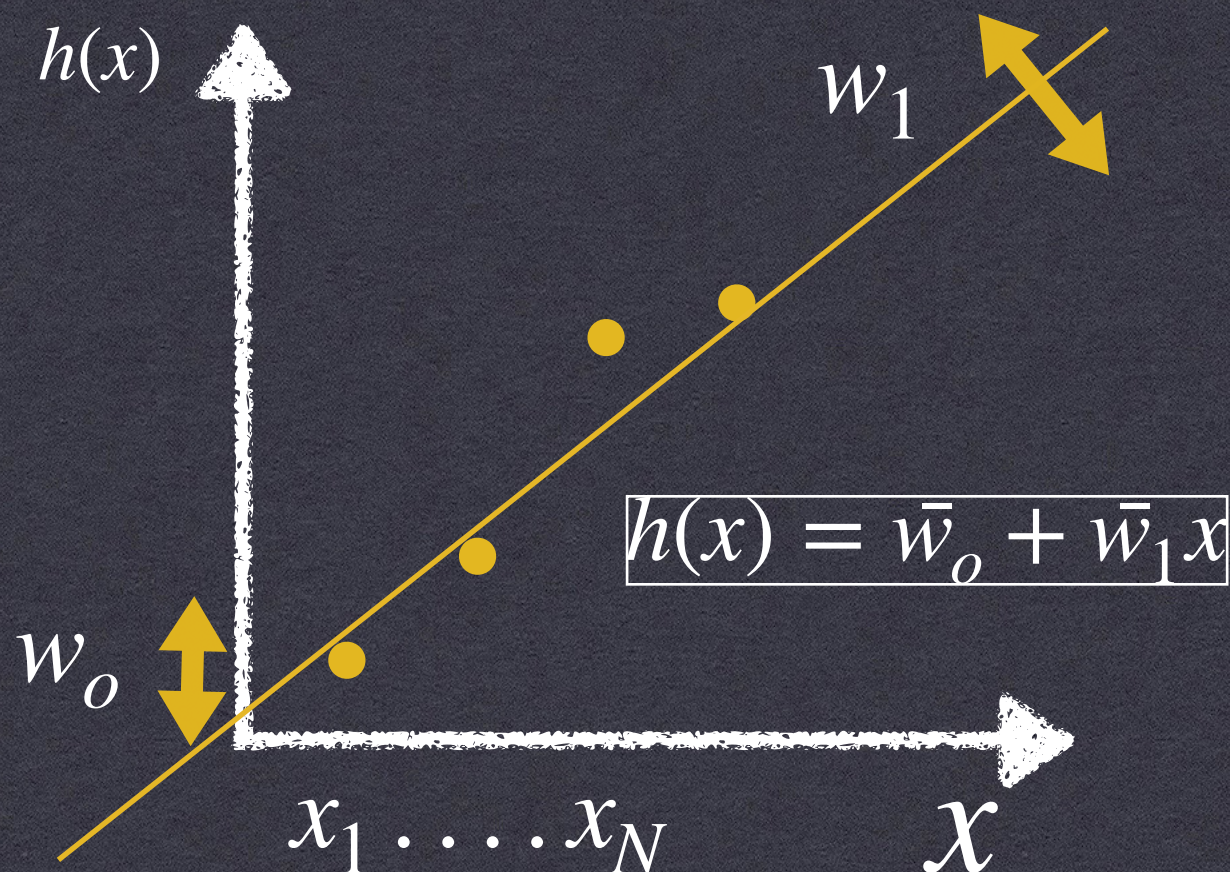
CLASSIFICATION ALGORITHMS

LINEAR REGRESSION

1-Feature (1F) (x), N measurements

$$\mathbf{X}^T = \{x_1 \dots x_N\}$$

$$\mathbf{W}^i = \{w_o^i, w_1^i\}_{i=1 \dots N}$$



LR cost function, e.g.

p-Feature (pF) (x), N measurements

$$[\mathbf{X}] = [N \times P]$$

$$\mathbf{X}_i = \{x_1 \dots x_p\}_{i=1 \dots N}$$

$$\mathbf{X}_j^T = \{X_1^T \dots X_N^T\}_{j=1 \dots p}$$

$$\mathbf{W}^i = \{W_o, W_1 \dots W_p\}_{i=1 \dots N}$$

$$h(\mathbf{X}) = W_o^i + W_1^i \mathbf{X}_i + \dots W_p^i \mathbf{X}_i^p = \mathbf{W}^T \mathbf{X}$$

$$J(\mathbf{W}) = \frac{1}{2} (h(x) - Y)^2 \equiv \frac{1}{2} \sum_{i=1}^N ((\mathbf{W}^T \mathbf{X})_i - Y_i^2)$$



CLASSIFICATION ALGORITHMS

LOGISTIC REGRESSION

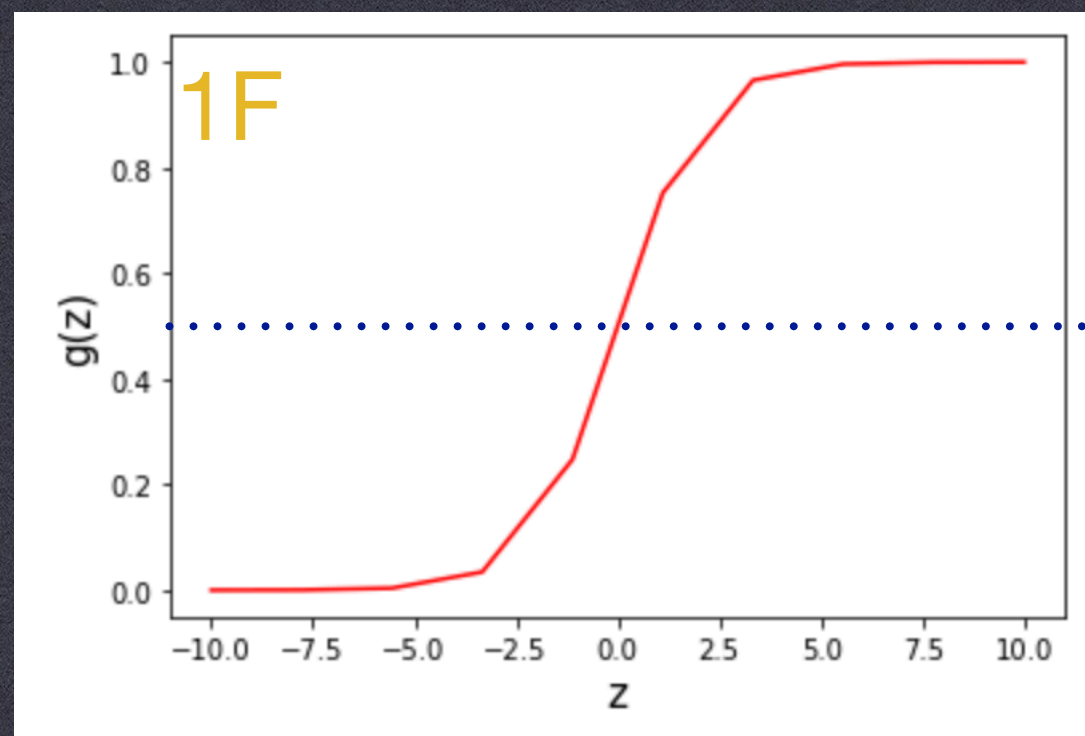
LINEAR REGRESSION

$$J(W) = \frac{1}{2}(h(x) - Y)^2 \equiv \frac{1}{2} \sum_{i=1}^N ((\mathbf{W}^T \mathbf{X})_i - Y_i^2)$$

LOGISTIC REGRESSION

$$J(W) = -\frac{1}{N} \left[\sum_{i=1}^N y^{(i)} \log(h_w(x^{(i)})) + (1 - y^{(i)}) \log(1 - h_w(x^{(i)})) \right]$$

$$h(x) \rightarrow g(z) = \frac{1}{1 + e^{-z}} \quad \text{Activation function}$$



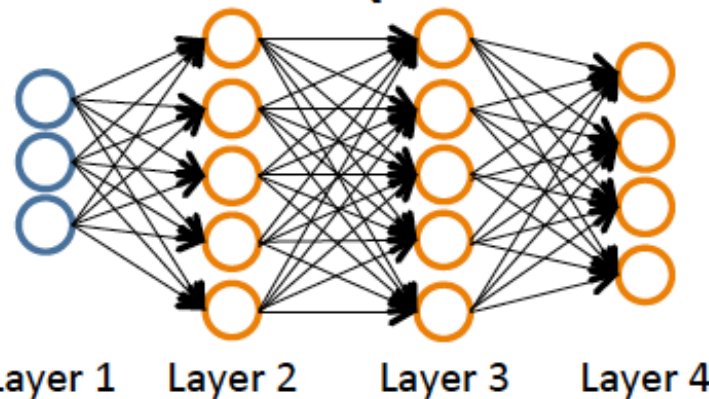
$$g(z) \leq 0.5 \rightarrow y^{(i)} = 0 \quad (\text{e.g. Astro})$$

$$g(z) > 0.5 \rightarrow y^{(i)} = 1 \quad (\text{e.g. DM})$$

CLASSIFICATION ALGORITHMS

ARTIFICIAL NEURAL NETWORK

Neural Network (Classification)



$$\{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(m)}, y^{(m)})\}$$

$L =$ total no. of layers in network

$s_l =$ no. of units (not counting bias unit) in layer l

Binary classification

$y = 0$ or 1

1 output unit

Multi-class classification (K classes)

$y \in \mathbb{R}^K$ E.g. $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$
pedestrian car motorcycle truck

K output units

CLASSIFICATION ALGORITHMS

ARTIFICIAL NEURAL NETWORK

LOGISTIC REGRESSION

$$J(\theta) = -\frac{1}{m} \left[\sum_{i=1}^m y^{(i)} \log(h_{\theta}(x^{(i)})) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)})) \right] + \frac{\lambda}{2m} \sum_{j=1}^n \theta_j^2$$

NEURAL NETWORK

$h_{\Theta}(x) \in \mathbb{R}^k$ $(h_{\Theta}(x))_i = i^{th}$ output

$$J(\Theta) = -\frac{1}{m} \left[\sum_{i=1}^m \sum_{k=1}^K y_k^{(i)} \log(h_{\Theta}(x^{(i)}))_k + (1 - y_k^{(i)}) \log(1 - h_{\Theta}(x^{(i)}))_k \right] + \frac{\lambda}{2m} \sum_{l=1}^{L-1} \sum_{i=1}^{s_l} \sum_{j=1}^{s_{l+1}} (\Theta_{ji}^{(l)})^2$$

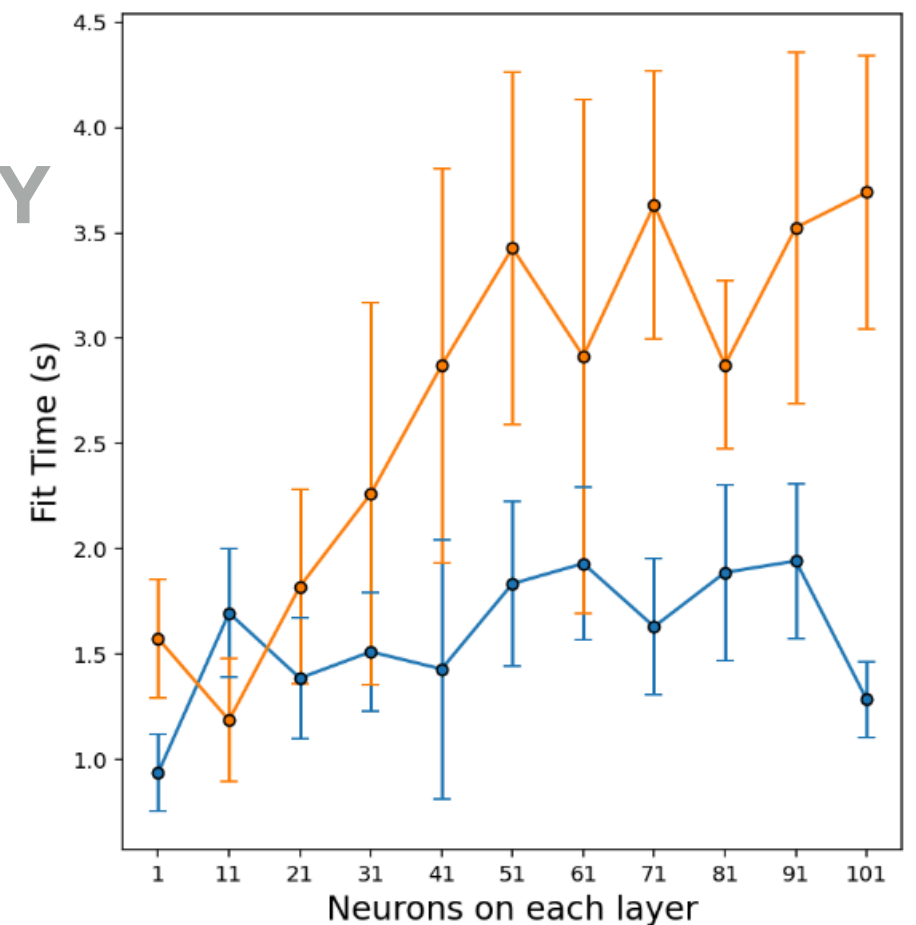
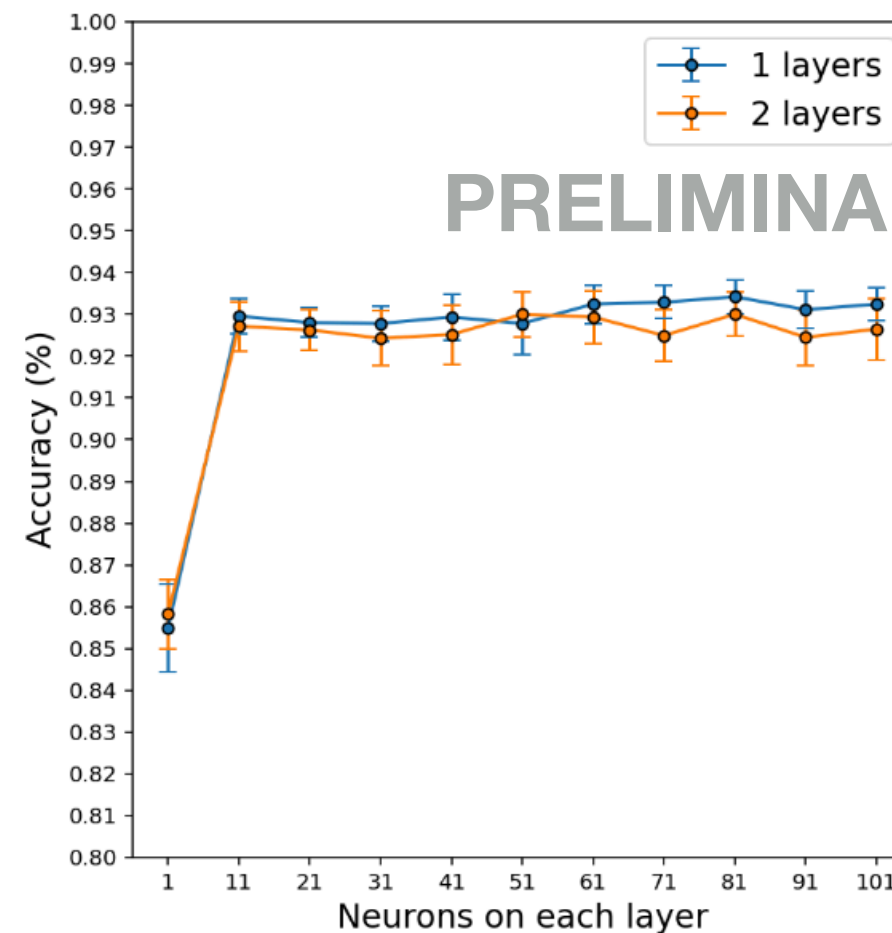
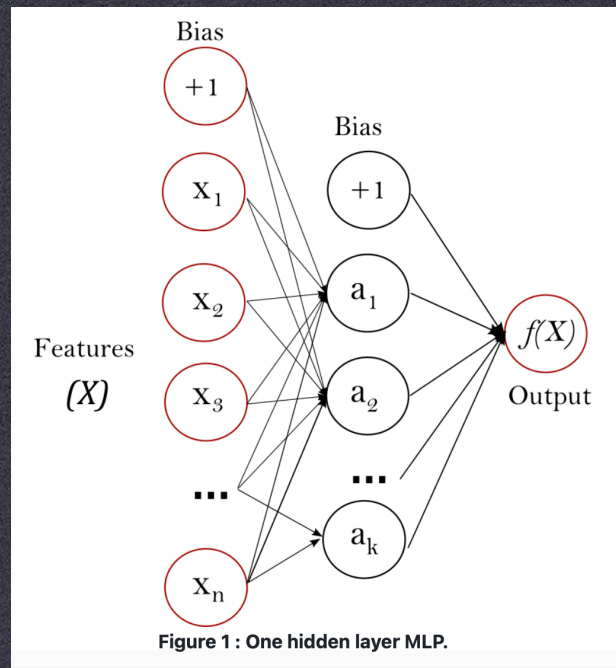
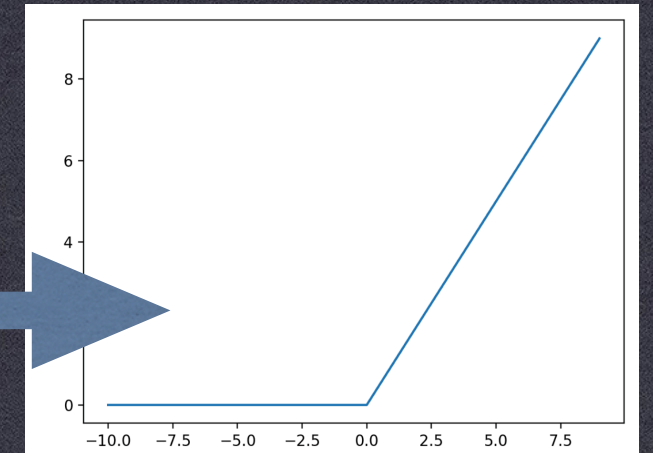
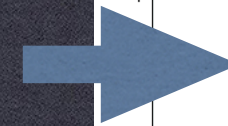
CLASSIFICATION ALGORITHMS



ARTIFICIAL NEURAL NETWORK

This work: 1 layer with 41 neurons

Rectified Linear Activation Function (ReLU)



CLASSIFICATION ALGORITHMS

NAIVE BAYES

Assuming the Bayes' theorem:

$$P(y | \mathbf{x}) = \frac{P(y)P(\mathbf{x} | y)}{P(\mathbf{x})}$$

$P(y)$ **Prior** on the class, e.g. $P(y_0)$ is the probability that a source is astro before to analyse the gamma-ray spectra

$P(y | \mathbf{x})$ **Posterior**: corresponding probability,
e.g. $P(\mathbf{x} | y_0)$ after the analysis of gamma-ray spectra (posterior)

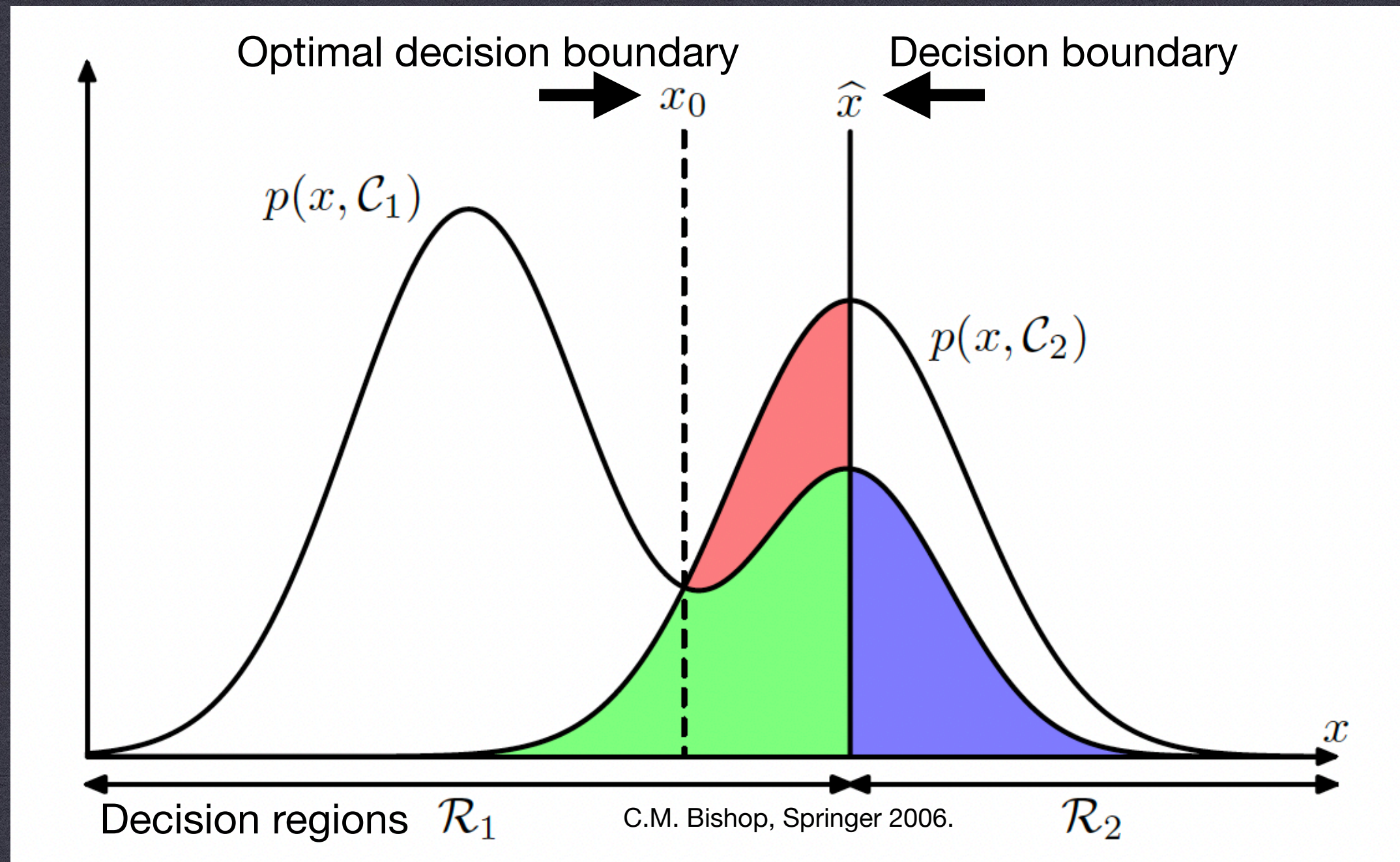
$P(\mathbf{x} | y)$ **Likelihood (joint distribution)**, i.e. the most complete probabilistic description of the scientific case

$P(\mathbf{x}) = \sum_k p_k(\mathbf{x} | y)p(y)$ **Typically intratable**

The “naive” assumption is the conditional independence between every pair of features given the value of the class variable. The solution is obtained by fitting the model for each class separately using the correspondingly labelled data.

CLASSIFICATION ALGORITHMS

NAIVE BAYES

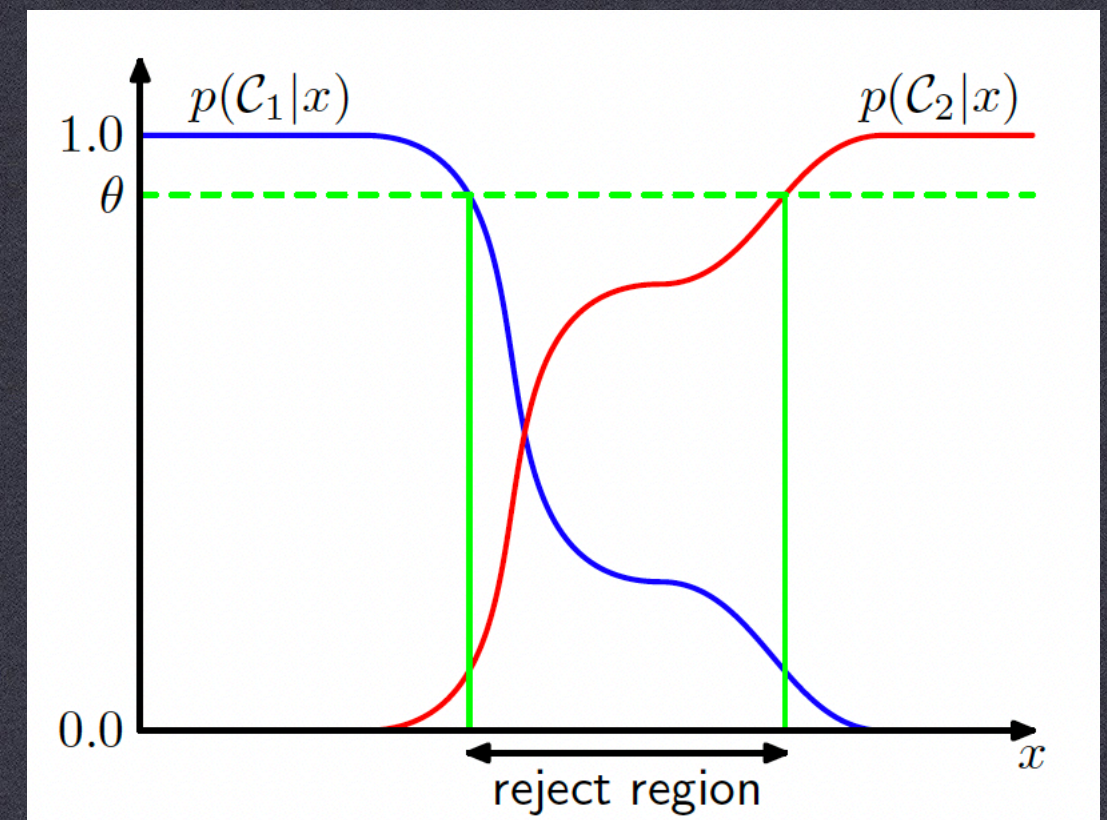
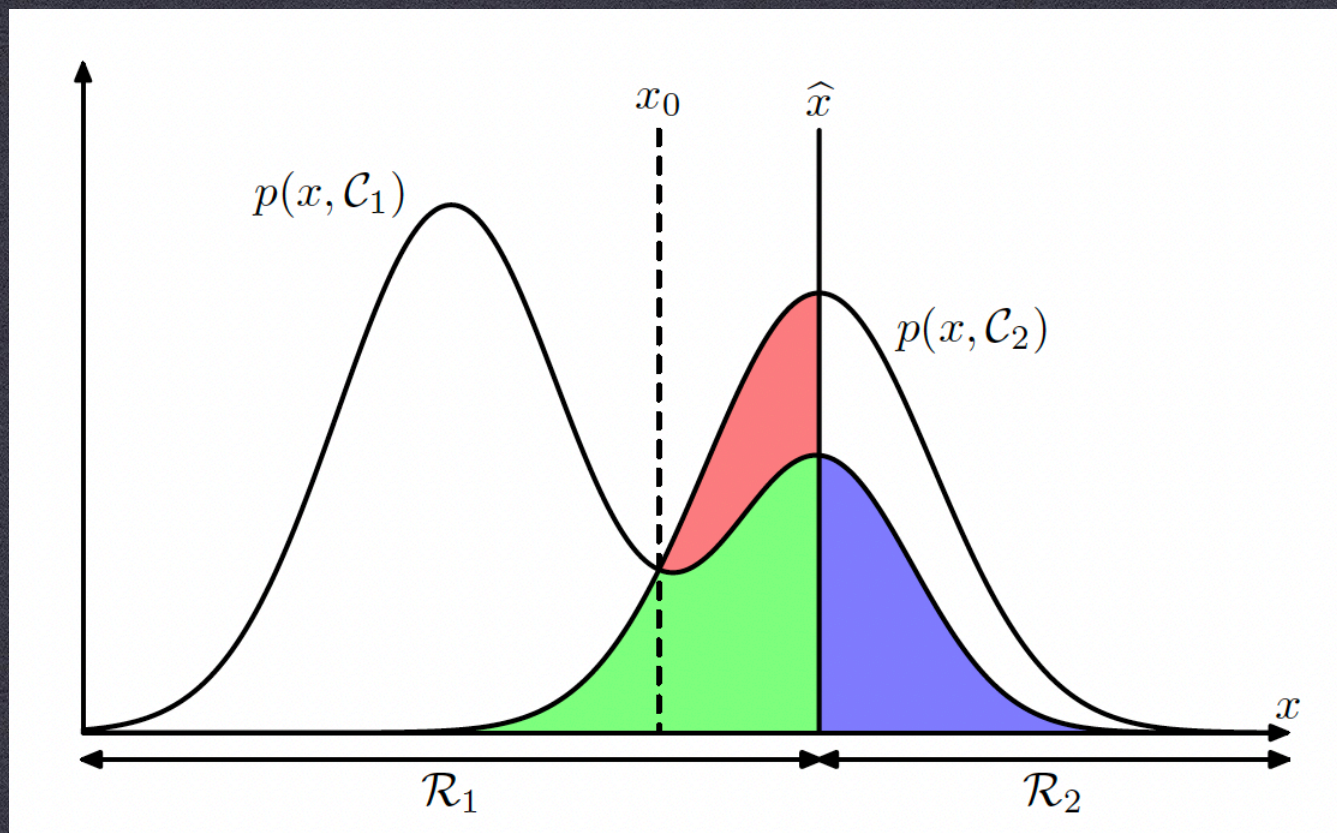


This is equivalent to the minimum misclassification rate decision rule, which assigns each value of \mathbf{x} to the class having the higher posterior probability

CLASSIFICATION ALGORITHMS

NAIVE BAYES

Having found the posterior probabilities, we use decision theory to determine class membership for each new input x .



C.M. Bishop, Springer 2006.

If our aim is to minimize the chance of assigning x to the wrong class, then intuitively we would choose the class having the higher posterior probability (here, Astro).

CLASSIFICATION ALGORITHMS

GAUSSIAN PROCESS WITH NOISY INPUTS

Based on:

Multi-class Gaussian Process Classification with Noisy Inputs

Autor (es): Villacampa-Calvo, Carlos ; Zaldívar, Bryan; Garrido-Merchán, Eduardo C.; Hernández Lobato, Daniel

Entidad: UAM. Departamento de Ingeniería Informática

Editor: Microtome Publishing

Fecha de edición: 2021-01

Cita: Journal Of Machine Learning Research 22.36 (2021): 1–52

ISSN: 1532-4435 (print); 1533-7928 (online)

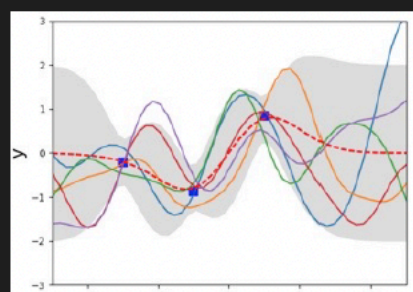
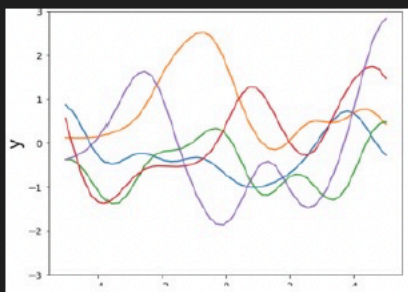
CLASSIFICATION ALGORITHMS

GAUSSIAN PROCESS WITH NOISY INPUTS

See B. Zaldivar's talk:

VILLACAMPA, GARRIDO, HERNÁNDEZ, AND BZ, JOURNAL OF ML RESEARCH, 2020

- Idea: Each input $\vec{x}_i = \vec{\bar{x}}_i + \Delta\vec{x}_i$
 - noisy observation \vec{x}_i
 - actual input (unknown) $\vec{\bar{x}}_i$
 - Input uncertainty (assumed Gaussian) $\Delta\vec{x}_i$
 - To be modelled(in analogy to what we typically do for the dependent variable y)
- Likelihood of data $p(Y, X | F, \underline{X}) = \prod_i^N p(y_i | f(\vec{x}_i)) \cdot \mathcal{N}(\vec{x}_i | \vec{\bar{x}}_i, \Delta\vec{x}_i)$
 - Latent variables for the output Y
- Y modelled as a Gaussian Process (GP) \Rightarrow Very popular Stochastic Process in ML, based on Gaussian distrib. [over functions]
 - GP prior
 - GP posterior after 3 obs.
 - GP give analytical predictions in regression problems
 - For classification the posterior should be approximated
 - \Rightarrow nowadays typically using Variational Inference



SETUPS

- ▶ **2-FEATURES (2F) CLASSIFICATION (LR, NN, NB):** INCLUDES THE 2-FEATURES INTRODUCED SO FAR, INDEED (E_{peak}, β)
- ▶ **4-FEATURES (4F) CLASSIFICATION (LR, NN, NB):** INCLUDES THE SYSTEMATICS UNCERTAINTY, BY INCLUDING TWO MORE FEATURES, THAT ARE: $(E_{\text{peak}}, \beta, \sigma_d, \beta_{\text{rel}})$ WHERE $\beta_{\text{rel}} = \epsilon_{\beta}/\beta$
- ▶ **3-FEATURES AUGMENTED (3F-A) (LR, NN, NB):** AN AUGMENTED DATASET CONTAINING THREE FEATURES: $(E_{\text{peak}}, \beta_{\text{sampled}}, \sigma_d)$ INSTEAD OF INCORPORATING THE UNCERTAINTY β_{rel} AS AN EXTRA FEATURE, THE STRATEGY HERE IS TO AUGMENT THE DATASET BY THE FOLLOWING PROCEDURE: FOR EACH OBSERVATION, WE ASSUME THAT THE VARIABLE β FOLLOWS A TRUNCATED GAUSSIAN DISTRIBUTION, WHOSE MEAN IS PRECISELY THE OBSERVED VALUE, AND THE STANDARD DEVIATION IS PRECISELY THE OBSERVED UNCERTAINTY ϵ_{β} , BUT TRUNCATED SUCH THAT $0 < \beta \leq 1$.
- ▶ **3F-B (GP):** A DATASET CONTAINING THE THREE SAME FEATURES AS ABOVE, I.E. $(E_{\text{peak}}, \beta, \sigma_d)$. HOWEVER, NOW THE UNCERTAINTIES ϵ_{β} ARE INCLUDED IN THE STATISTICAL MODEL. CONCRETELY, THIS SETUP WILL CONCERN EXCLUSIVELY THE NIMGP MODEL MENTIONED ABOVE.

OUTLINE

- **FERMI-LAT GAMMA-RAY DATA & BETA-PLOT**
- **DARK MATTER & BETA-PLOT**
- **“SYNTHETIC” FEATURES:
DETECTION SIGNIFICANCE σ_d AND UNCERTAINTY ON β**
- **INTRODUCTION TO CLASSIFICATION IN MACHINE LEARNING**
- **PRELIMINARY RESULTS**
- **PRELIMINARY CONCLUSIONS**

DATA PRE-PROCESSING

1. $10^{-3}\text{GeV} < E_{\text{peak}} < 10^6 \text{ GeV}$, reliable range of the Fermi-LAT sensitivity in energy
2. Balanced data: same number of DM and Astro
3. Log scale classification
4. Standardised data: each feature is normalised with respect to their medium values.
5. Training/Testing data set split:

RepeatedStratifiedKFold(n_splits=N_splits, n_repeats=N_Repeats)

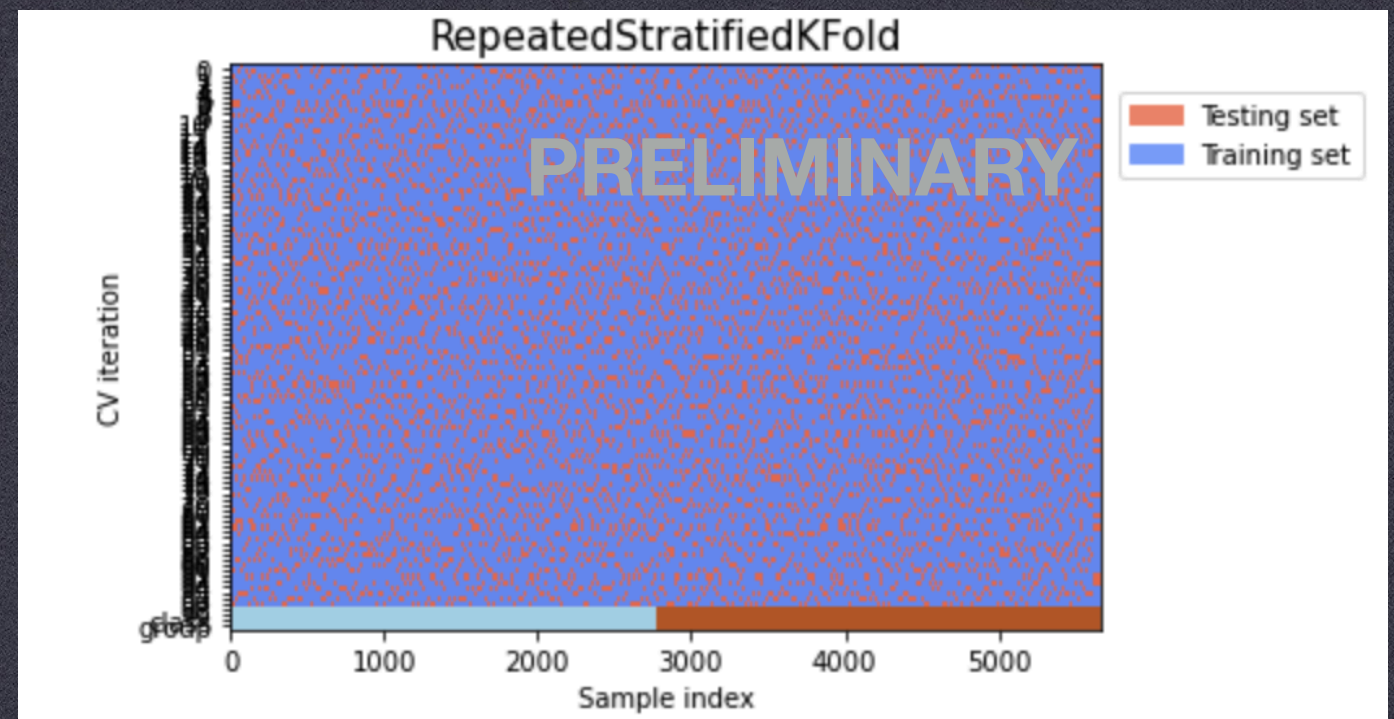
Number of folds, $N_{\text{splits}}=5 \rightarrow$ Train set = 4530 (80%) data Test set=1132 (20%)

Number of times cross-validator needs to be repeated, $N_{\text{Repeats}}=20$

$N_{\text{class}}=N_{\text{splits}} \times N_{\text{Repeats}}= 100$

Stratified: The split into N_{folds} preserve the percentage of samples for each class and without repeated data in different folds.

Repeated: the cross-validation is repeated a number of times with different random seed



DATA PRE-PROCESSING: CHECK

RepeatedStratifiedKFold(n_splits=N_splits, n_repeats=N_Repeats)

Number of folds, $N_splits=3$ \rightarrow Train set = 3774 (80%) data Test set=1888 (33%)

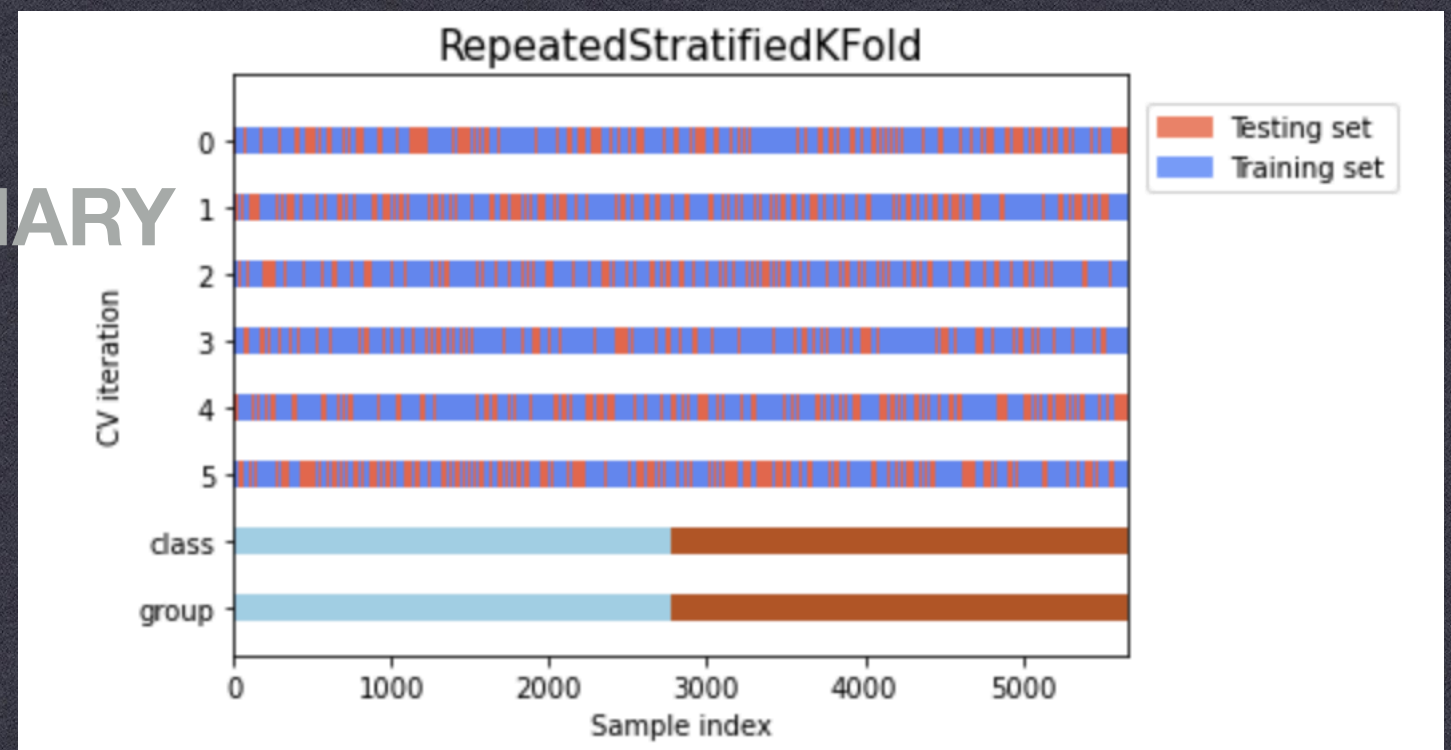
Number of times cross-validator needs to be repeated, $N_Repeats=2$

$N_class=N_splits \times N_Repeats=6$

Stratified: The split into N_folds preserve the percentage of samples for each class and without repeated data in different folds.

Repeated: the cross-validation is repeated a number of times with different random seed

PRELIMINARY



PRELIMINARY CLASSIFICATION RESULTS

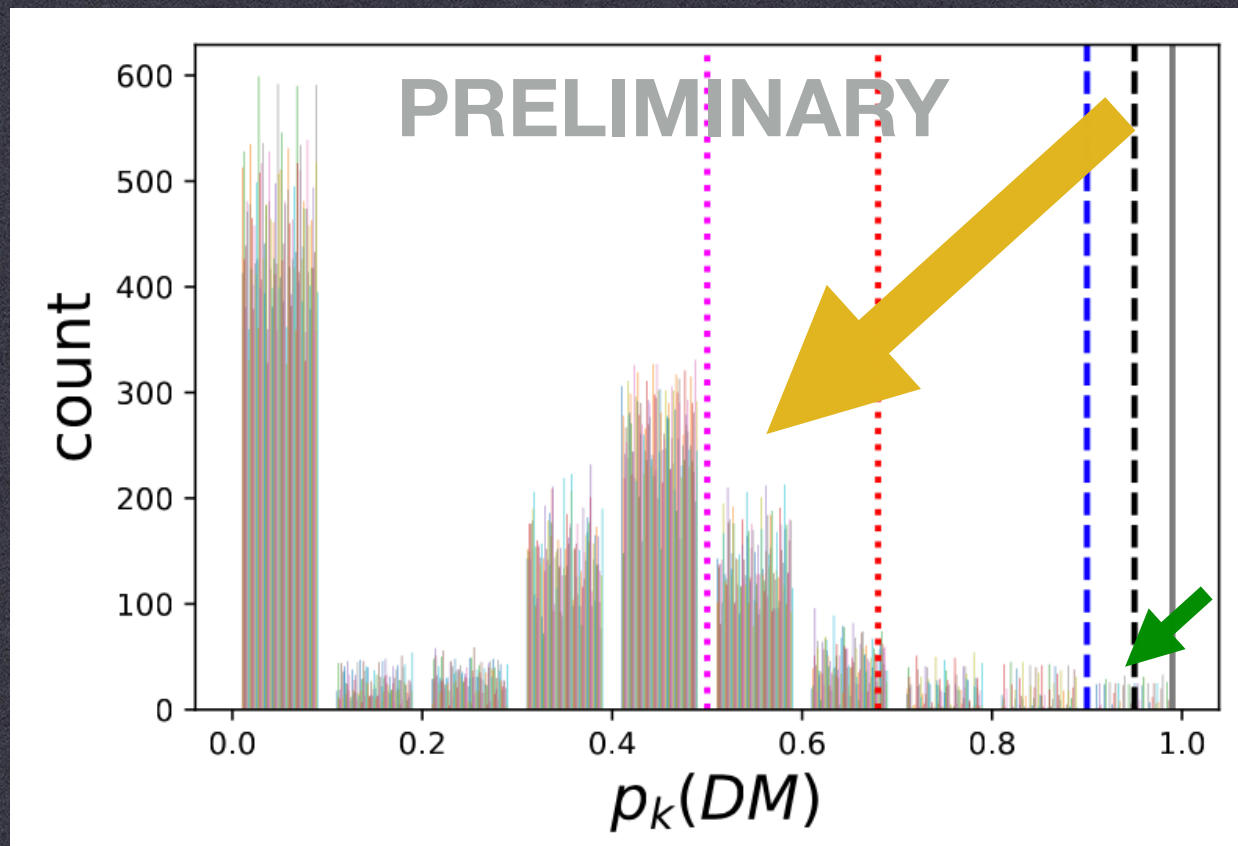
$$\text{Overall accuracy (OA)}(y, \hat{y}) = \frac{1}{n_{\text{samples}}} \sum_{i=0}^{n_{\text{samples}}-1} 1(\hat{y}_i = y_i)$$

- **TRUE NEGATIVE:** PERCENTAGE OF WELL CLASSIFIED ASTRO SOURCES (NORMALISED TO THE TOTAL NUMBER OF ASTRO SOURCES)
- **TRUE POSITIVE:** PERCENTAGE OF WELL CLASSIFIED DARK MATTER SOURCES (NORMALISED TO THE TOTAL NUMBER OF DM SOURCES)

	OA(%)	TN (%)	TP (%)
LR			
2F	84.9 ± 0.6	85.4 ± 1.3	84.4 ± 1.0
4F	86.0 ± 0.5	86.8 ± 1.2	85.6 ± 0.7
3F-A	82.9 ± 0.1	84.9 ± 0.2	80.9 ± .0.1
NN			
2F	86.8 ± 0.3	86.4 ± 2.4	87.2 ± 2.3
4F	93.1 ± 0.4	94.7 ± 1.1	91.4 ± 1.0
3F-A	85.0 ± 0.1	88.7 ± 0.8	81.3 ± 1.1
NB			
2F	82.0 ± 1.3	80.4 ± 2.7	83.8 ± 2.1
4F	83.7 ± 0.9	81.1 ± 1.9	86.4 ± 0.5
3F-A	82.6 ± 0.1	83.4 ± 0.2	81.3 ± 0.1
GP			
3F-B	87.0±0.1	84.5±0.2	89.4±0.2

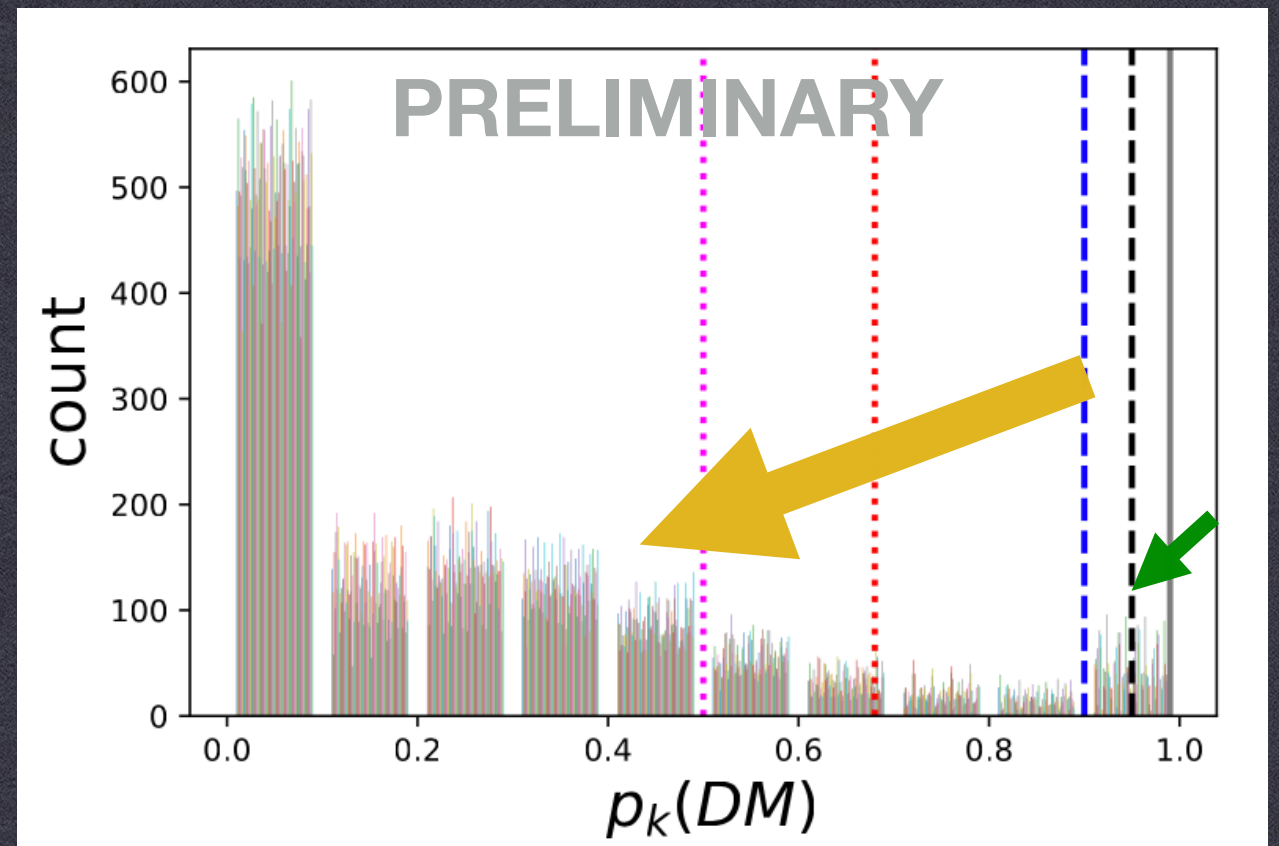
UNIDS CLASSIFICATION WITH NN

► 2-FEATURES (2F) CLASSIFICATION



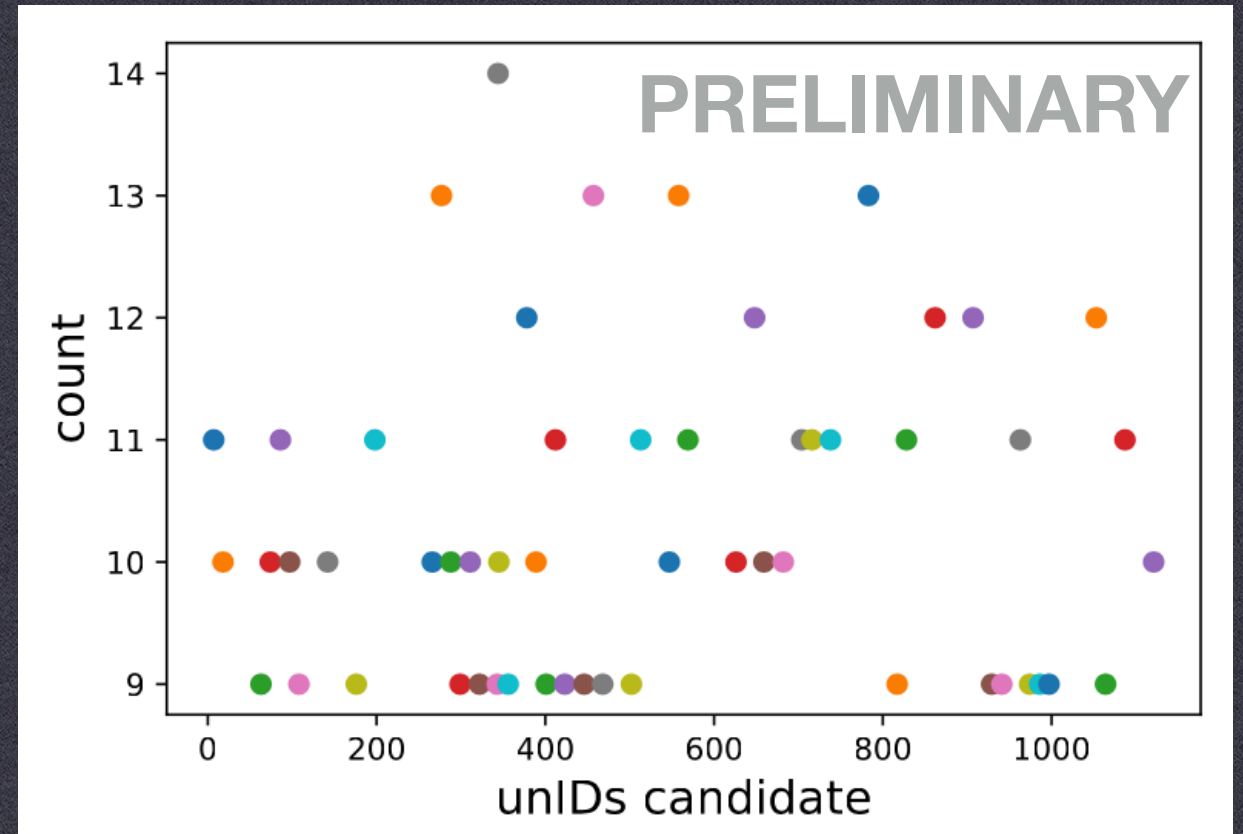
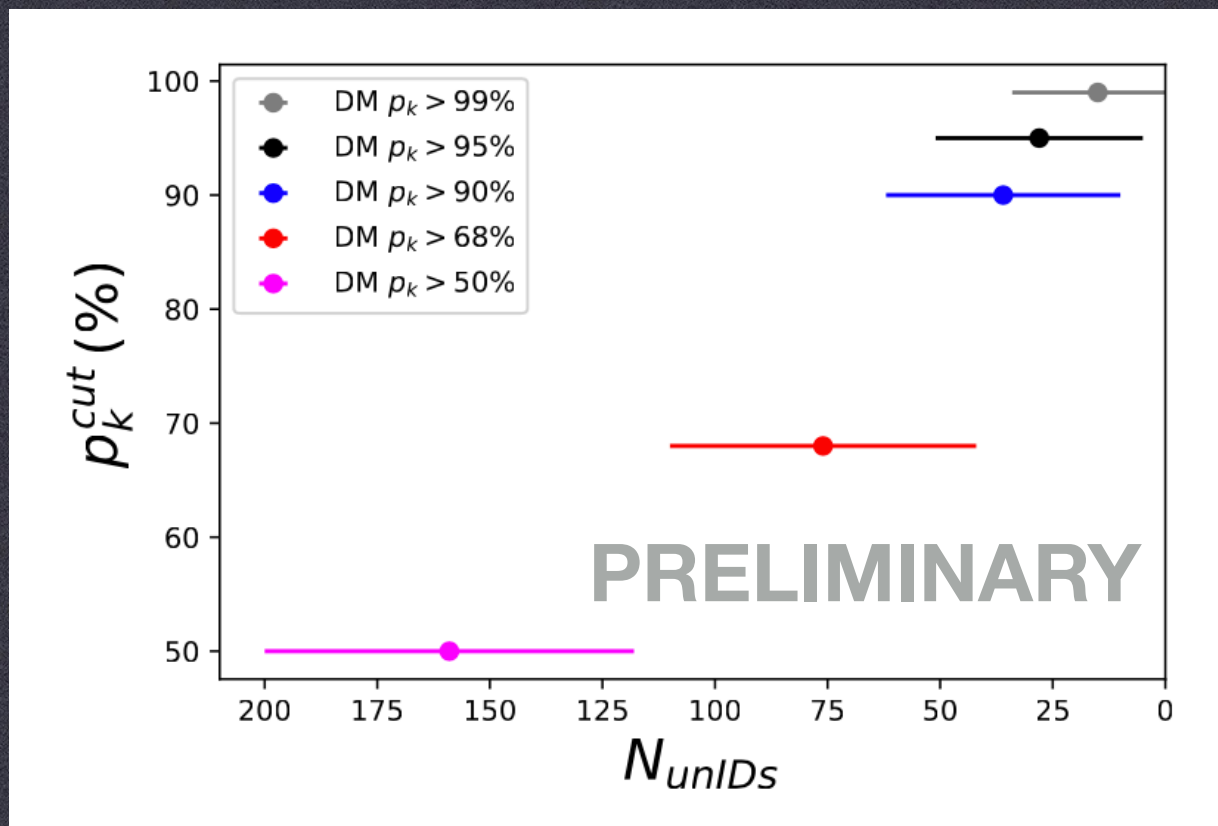
- 6 ± 10 UNIDS CLASSIFIED AS DM WITH $p_k > 90\%$ (ERROR DEFINED ON 100 CLASSIFICATION)
- 0 UNIDS WITH $\bar{p} > 90\%$ (50%)(40%)

► 4-FEATURES (4F) CLASSIFICATION



- 36 ± 26 UNIDS CLASSIFIED AS DM WITH $p_k > 90\%$ (ERROR DEFINED ON 100 CLASSIFICATION)
- 0 UNIDS WITH $\bar{p} > 90\%$ (50%)
- FEW UNIDS WITH $\bar{p} > 40\%$

UNIDS CLASSIFICATION WITH NN



PRELIMINARY CONCLUSIONS

- ▶ WE TRAINED FOUR DIFFERENT MACHINES ON A **SAMPLE OF BOTH EXPERIMENTAL AND EXPECTED DATA**
- ▶ WE INTRODUCED THE **SYNTHETIC FEATURES AND FOUR DIFFERENT SET-UPS**
- ▶ WE PROPOSED A METHODOLOGY TO INCLUDE **SYSTEMATIC UNCERTAINTY** IN CLASSIFICATION PROBLEMS, **IMPROVING THE OVERALL CLASSIFICATION ACCURACY** FOR ALL THE TRAINED ALGORITHMS.
- ▶ THE **NN IS THE BEST CLASSIFIER** AMONG OUR SELECTION OF DIFFERENT ML ALGORITHMS.
- ▶ THE **NN IN THE 4-FEATURES SETUP IMPROVES THE DEGENERACY** OF PULSARS AND DM SIGNAL
- ▶ THE RESULTS ARE IN STATISTICAL AGREEMENT WITHIN DIFFERENT RANDOM SEEDS
- ▶ **NO UNIDS ARE CLASSIFIED AS DM** IN AGREEMENT WITH PREVIOUS WORKS.
- ▶ THE PROPOSED METHODOLOGY COULD BE APPLIED TO **DIFFERENT SCIENTIFIC CASES**

**THANK YOU
FOR YOUR ATTENTION**

BACK-UP SLIDES

N-SPLITS TRAINING/TESTING SET

